

**A discretionary stopping problem with applications to
the optimal timing of investment decisions**

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THE PROBLEM

- Consider the following discretionary stopping problem:

maximise $\mathbb{E}_x [e^{-r\tau} g(X_\tau)]$ over all stopping times τ ,

where $dX_t = b(X_t) dt + \sigma(X_t) dW_t$, with $X_0 = x$.

APPLICATIONS

- When should you sell an asset that you have been endowed with?
 - X_t models the asset's price at time t ;
 - $g(x) = x$.
- Exercise of perpetual American options:
 - X_t models the underlying asset's price at time t ;
 - $g(x) = (x - K)^+$, where $K > 0$ is the strike.
- Real options:
 - X_t models the expected discounted payoff obtained from a project, realised at time t (the book value);
 - $g(x) = x - K$, where $K > 0$ is the cost of initialising the project.

- Mean-reverting Itô diffusions provide better models for the price processes of assets that exist in equilibrium than a geometric Brownian motion.
- General payoff functions, rather than affine ones provide significant additional modelling flexibility.
In particular, they allow for *utility* based decision making.
- Introducing a state-dependent discounting rate allows for modelling the likelihood of an investment's default.

PROBLEM FORMULATION

- State process

$$dX_t = b(X_t) dt + \sigma(X_t) dW_t, \quad X_0 = x > 0,$$

where W is a standard, one-dimensional Brownian motion, and b, σ are given deterministic functions.

- We assume that this SDE has a unique, in the sense of probability law, non-explosive solution such that $X_t > 0$, for all $t > 0$:

The functions $b, \sigma :]0, \infty[\rightarrow \mathbb{R}$ satisfy the following conditions:

$$\begin{aligned} & \sigma^2(x) > 0, \text{ for all } x \in]0, \infty[, \\ \forall x \in]0, \infty[, \exists \varepsilon > 0 : & \int_{x-\varepsilon}^{x+\varepsilon} \frac{1 + |b(s)|}{\sigma^2(s)} ds < \infty. \end{aligned}$$

Also, if we define

$$u(x) := \int_{x_0}^x \left[p_{x_0}(x) - p_{x_0}(y) \right] m(dy),$$

then $\lim_{x \downarrow 0} u(x) = \lim_{x \rightarrow \infty} u(x) = \infty$.

- A stopping strategy is a collection

$$\mathbb{S}_x = ((\Omega, \mathcal{F}, \mathcal{F}_t, \mathbb{P}_x, X, W), \tau).$$

- Given an initial condition $x > 0$, the objective is to maximise

$$J(\mathbb{S}_x) := \mathbb{E}_x \left[e^{-\Lambda_\tau} g(X_\tau) \mathbf{1}_{\{\tau < \infty\}} \right],$$

over all stopping strategies \mathbb{S}_x . Here,

$$\Lambda_t := \int_0^t r(X_s) ds.$$

- The value function is defined by

$$v(x) := \sup_{\mathbb{S}_x} J(\mathbb{S}_x), \quad \text{for } x > 0.$$

GEOMETRIC BROWNIAN MOTION

- Suppose that

$$dX_t = bX_t dt + \sigma X_t dW_t, \quad X_0 = x > 0,$$

$$g(x) = x - K \text{ and } r = \text{constant.}$$

- In this case

$$e^{-rt} X_t = x e^{(b-r)t} e^{-\frac{1}{2}\sigma^2 t + \sigma W_t},$$

and it follows that

- if $b > r$, then $v(x) = \infty$ and there is no optimal strategy;
- if $b < r$ and $K = 0$, then $v(x) = x$ and $\tau^* \equiv 0$ is optimal;
- if $b < r$ and $K > 0$, then the solution is not totally trivial.

- Note that, when $b \geq r$,

$$\lim_{t \rightarrow \infty} \mathbb{E}_x [e^{-\Lambda t} g(X_t)] = \lim_{t \rightarrow \infty} \mathbb{E}_x [e^{-rt} X_t] > 0.$$

ASSUMPTIONS ON g

- Observe that

$$\mathbb{E}_x [e^{-\Lambda t} g(X_t)] = g(x) + \mathbb{E}_x \left[\int_0^t e^{-\Lambda s} f(X_s) ds \right],$$

where

$$f(x) := \frac{1}{2} \sigma^2(x) g''(x) + b(x) g'(x) - r(x) g(x).$$

- If $f(x) < 0$, for all x , then $v(x) = g(x)$ and $\tau^* \equiv 0$ is optimal.
- If $f(x) > 0$, for all x , then $v \equiv \infty$ and there is no optimal strategy.

- We therefore assume that there exists $x_1 > 0$ such that

$$f(x) \equiv \frac{1}{2} \sigma^2(x) g''(x) + b(x) g'(x) - r(x) g(x) \begin{cases} > 0, & \text{for } x < x_1, \\ < 0, & \text{for } x > x_1. \end{cases}$$

- We impose the *Lisbon condition*:

There exists an $l :]0, \infty[\rightarrow [1, \infty[$ such that $\lim_{x \rightarrow \infty} l(x) = \infty$,

$$\lim_{t \rightarrow \infty} \mathbb{E}_x [e^{-\Lambda t} l(X_t) |g(X_t)|] = 0,$$

and

$$\frac{1}{2} \sigma^2(x) (lg)''(x) + b(x) (lg)'(x) - r(x) (lg)(x) \leq 0, \text{ for } x > x_2,$$

for some $x_2 > x_1$.

- Note that the Lisbon condition implies the validity of the *transversality condition*

$$\lim_{t \rightarrow \infty} \mathbb{E}_x [e^{-\Lambda t} |g(X_t)|] = 0,$$

- There exist constants $C, \varepsilon > 0$ such that

$$\begin{aligned} g(x) &\geq -C, & \text{for all } x > 0, \\ g(x) &> 0, & \text{for all } x > \frac{1}{\varepsilon}, \\ g(x) &< C \text{ and } g'(x) > -C, & \text{for all } x < \varepsilon. \end{aligned}$$

- There exist constants $C, x_3 > 0$ and $j \geq 1$ such that

$$\begin{aligned}\sigma^2(x) &\leq C(1 + x^j), \quad \text{for all } x > 0, \\ [\sigma(x)g'(x)]^2 &\leq C(1 + x^j), \quad \text{for all } x > x_3,\end{aligned}$$

and

$$\int_0^t \mathbb{E} [X_s^j] ds < \infty, \quad \text{for all } t \geq 0.$$

- There exists a constant $r_0 > 0$ such that

$$r(x) \geq r_0, \quad \text{for all } x > 0.$$

EXAMPLES OF g

- The following choices satisfy our assumptions for a wide range of diffusions X :

$$\begin{aligned}g(x) &= \xi x^\eta - K, & g(x) &= (\xi x^\eta - K)^+, \\g(x) &= \xi \ln(x + \gamma) - K, & g(x) &= -\xi e^{-\gamma x} - K,\end{aligned}$$

where $\xi, \eta, \gamma > 0$ and $K \in \mathbb{R}$.

THE HAMILTON-JACOBI-BELLMAN (HJB) EQUATION

- At any given time, say at time 0, there exist two possible actions: *wait* or *stop*.
- *Wait* for Δt and then continue optimally is associated with

$$v(x) \geq \mathbb{E}_x [e^{-\Lambda \Delta T} v(X_{\Delta T})].$$

Using Itô's formula, dividing by Δt and taking the limit $\Delta t \downarrow 0$ yields

$$\frac{1}{2} \sigma^2(x) v''(x) + b(x) v'(x) - r(x) v(x) \leq 0.$$

- *Stop* is associated with

$$v(x) \geq g(x).$$

- We therefore expect that the value function v should identify with a solution to the HJB equation

$$\max \left\{ \frac{1}{2} \sigma^2(x) w''(x) + b(x) w'(x) - r(x) w(x), g(x) - w(x) \right\} = 0.$$

THE SOLUTION TO THE DISCRETIONARY STOPPING PROBLEM

- We look for a critical point x^* , such that it is optimal to
 - wait while $X_t < x^*$,
 - stop as soon as X hits $[x^*, \infty[$.
- We therefore look for a solution to the HJB equation such that

$$\frac{1}{2}\sigma^2(x)w''(x) + b(x)w'(x) - r(x)w(x) = 0, \quad \text{for } x \in]0, x^*[,$$

and

$$w(x) = g(x), \quad \text{for } x \in [x^*, \infty[.$$

- Every solution to the ODE

$$\frac{1}{2}\sigma^2(x)w''(x) + b(x)w'(x) - r(x)w(x) = 0$$

is given by

$$w(x) = A\psi(x) + B\phi(x),$$

for some constants $A, B \in \mathbb{R}$, where the functions ψ and ϕ are defined by

$$\psi(x) := \begin{cases} \mathbb{E}_x[e^{-\Lambda\tau_z}], & \text{for } x < z, \\ 1/\mathbb{E}_z[e^{-\Lambda\tau_x}], & \text{for } x \geq z, \end{cases} \quad (\text{increasing})$$

and

$$\phi(x) := \begin{cases} 1/\mathbb{E}_z[e^{-\Lambda\tau_x}], & \text{for } x < z, \\ \mathbb{E}_x[e^{-\Lambda\tau_z}], & \text{for } x \geq z, \end{cases} \quad (\text{decreasing})$$

for a given choice of $z > 0$.

- When X is a geometric Brownian motion, i.e., when

$$dX_t = bX_t dt + \sigma X_t dW_t,$$

for some constants b, σ ,

$$\psi(x) = x^n \quad \text{and} \quad \phi(x) = x^m,$$

where $m < 0 < n$ are appropriate constants.

- When X is a square-root mean reverting process, i.e., when

$$dX_t = \kappa(\theta - X_t) dt + \sigma\sqrt{X_t} dW_t,$$

for some constants $\kappa, \theta, \sigma > 0$ such that $\kappa\theta - \frac{1}{2}\sigma^2 > 0$,

$$\psi(x) = {}_1F_1\left(\frac{r}{\kappa}, \frac{2\kappa\theta}{\sigma^2}; \frac{2\kappa}{\sigma^2}x\right) \quad \text{and} \quad \phi(x) = U\left(\frac{r}{\kappa}, \frac{2\kappa\theta}{\sigma^2}; \frac{2\kappa}{\sigma^2}x\right).$$

- When X is an exponential Ornstein-Uhlenbeck process, i.e., when

$$dX_t = \left(\kappa(\theta - \ln X_t) + \frac{1}{2}\sigma^2 \right) X_t dt + \sigma X_t dW_t,$$

for some constants $\kappa, \theta, \sigma > 0$,

$$\psi(x) = \begin{cases} \frac{\Gamma(\frac{r+\kappa}{2\kappa})}{\pi} U\left(\frac{r}{2\kappa}, \frac{1}{2}; \frac{\kappa}{\sigma^2}(\theta - \ln x)^2\right), & \text{for } x \leq e^\theta, \\ {}_1F_1\left(\frac{r}{2\kappa}, \frac{1}{2}; \frac{\kappa}{\sigma^2}(\theta - \ln x)^2\right), & \text{for } x > e^\theta, \end{cases}$$

and

$$\phi(x) = \begin{cases} {}_1F_1\left(\frac{r}{2\kappa}, \frac{1}{2}; \frac{\kappa}{\sigma^2}(\theta - \ln x)^2\right), & \text{for } x \leq e^\theta, \\ \frac{\Gamma(\frac{r+\kappa}{2\kappa})}{\pi} U\left(\frac{r}{2\kappa}, \frac{1}{2}; \frac{\kappa}{\sigma^2}(\theta - \ln x)^2\right), & \text{for } x > e^\theta. \end{cases}$$

- When X is a geometric Ornstein-Uhlenbeck process, i.e., when

$$dX_t = \kappa(\theta - X_t)X_t dt + \sigma X_t dW_t,$$

for some constants $\kappa, \theta, \sigma > 0$,

$$\psi(x) = x^n {}_1F_1 \left(n, 2n + \frac{2\kappa\theta}{\sigma^2}; \frac{2\kappa x}{\sigma^2} \right),$$

$$\phi(x) = x^n U \left(n, 2n + \frac{2\kappa\theta}{\sigma^2}; \frac{2\kappa x}{\sigma^2} \right).$$

- We consider solutions to the HJB equation given by

$$w(x) = \begin{cases} A\psi(x) + B\phi(x), & \text{if } x < x^*, \\ g(x), & \text{if } x \geq x^*, \end{cases}$$

- Since the payoff function is increasing and bounded for small x , we expect that the same is true for the value function, which implies $B = 0$.
- To specify A and x^* , we appeal to the “smooth-pasting” condition of optimal stopping that requires the value function to be C^1 at the free boundary point x^* . This implies

$$A\psi(x^*) = g(x^*) \quad \text{and} \quad A\psi'(x^*) = g'(x^*).$$

This system implies that x^* must satisfy $q(x^*) = 0$, where

$$q(x) := g(x)\psi'(x) - g'(x)\psi(x), \quad \text{for } x > 0.$$

- Under the assumptions that we have imposed, there exists a unique x^* satisfying $q(x^*) = 0$.