

**Nonsingular stationary metrics with a
negative cosmological constant**

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Cambridge, 12 December 2005

Abstract: We construct infinite dimensional families of non-singular stationary space times, solutions of the vacuum Einstein equations with a negative cosmological constant.

1 Introduction

We construct Lorentzian metrics ${}^{n+1}g$ in any space-dimension $n \geq 3$, with Killing vector $X = \partial/\partial t$. In adapted coordinates those metrics can be written as

$${}^{n+1}g = -V^2 \underbrace{(dt + \theta_i dx^i)}_{=\theta} + \underbrace{g_{ij} dx^i dx^j}_{=g}, \quad (1)$$

$$\partial_t V = \partial_t \theta = \partial_t g = 0. \quad (2)$$

Remarks : If $\Lambda = 0$ from **A. Lichnerowicz 1955 (AF)** and **M. Anderson 2000 (complete)**, when there is no black hole, it must be Minkowski.

If $\Lambda < 0$, with **M. Anderson and P. T. Chruściel (2002-2005)** : infinite dimensional families of static vacuum space-times.

Theorem : Let $n = \dim M \geq 3$, and consider a static Lorentzian Einstein metric of the form (1)(2) with $V = \tilde{V}$, $g = \tilde{g}$, and $\theta = 0$, such that the associated Riemannian metric $\tilde{g} = \tilde{V}^2 d\varphi^2 + \tilde{g}$ on $\mathbb{S}^1 \times M$ is smoothly compactifiable and non-degenerate. For every smooth $\hat{\theta}$, sufficiently close to zero in $C^{k+2,\alpha}(\partial M, \mathcal{I}_1)$, there exists a unique stationary vacuum metric (1)(2) such that, in local coordinates near the conformal boundary ∂M ,

$$V - \tilde{V} = O(\rho), \quad \theta_i = \hat{\theta}_i + O(\rho), \quad g_{ij} - \tilde{g}_{ij} = O(1). \quad (3)$$

The vacuum Einstein equations for a metric satisfying (1)(2) read

$$\begin{cases} V(\nabla^* \nabla V + nV) = \frac{1}{4} |\lambda|_g^2, \\ \text{Ric}(g) + ng - V^{-1} \text{Hess}_g V = \frac{1}{2V^2} \lambda \circ \lambda, \\ \text{div}(V\lambda) = 0, \end{cases} \quad (4)$$

where

$$\lambda_{ij} = -V^2(\partial_i \theta_j - \partial_j \theta_i), \quad (\lambda \circ \lambda)_{ij} = \lambda_i^k \lambda_{kj}.$$

2 The linearised equation

We first consider the operator :

$$\begin{pmatrix} V \\ g \end{pmatrix} \mapsto \begin{pmatrix} V(\nabla^* \nabla V + nV) \\ \text{Ric}(g) + ng - V^{-1} \text{Hess}_g V \end{pmatrix}.$$

The two parts of the linearisation of it at (V, g) are

$$\begin{aligned} p(W, h) &= V[(\nabla^* \nabla + 2n + V^{-1} \nabla^* \nabla V + V^{-2} |dV|^2)W \\ &\quad + V^{-1} \nabla_j V \nabla^j W - V^{-1} \nabla^j V \nabla^k V h_{kj} \\ &\quad + \langle \text{Hess}_g V, h \rangle_g + \langle w, dV \rangle_g] \\ &=: l(W, h) + V \langle w, dV \rangle_g. \end{aligned}$$

and ...

$$\begin{aligned}
P(W, h) &= \frac{1}{2} \Delta_L h_{ij} + n h_{ij} - \frac{1}{2} V^{-1} \nabla^k V \nabla_k h_{ij} \\
&\quad + \frac{1}{2} V^{-2} (\nabla_i V \nabla^k V h_{kj} + \nabla_j V \nabla^k V h_{ki}) \\
&\quad - \frac{1}{2} V^{-1} (\nabla_i \nabla^k V h_{kj} + \nabla_j \nabla^k V h_{ki}) \\
&\quad + 2V^{-2} W (\text{Hess}_g V)_{ij} - 2V^{-3} \nabla_i V \nabla_j V W + (\text{div}^* w)_{ij} \\
&=: L(W, h) + \text{div}^* w .
\end{aligned}$$

where

$$w_j = V^{-1} \nabla^k V h_{kj} + \nabla^k h_{kj} - \frac{1}{2} \nabla_j (\text{Tr} h) - V^{-1} \nabla_j W - V^{-2} \nabla_j V W ,$$

$$(\text{div} h)_i = -\nabla^k h_{ik}, \quad (\text{div}^* w)_{ij} = \frac{1}{2} (\nabla_i w_j + \nabla_j w_i) ,$$

Note : (l, L) is elliptic.

3 The modified equation

We will first solve :

$$\begin{cases} q(V, g) := V(\nabla^* \nabla V + nV + \langle \Omega, dV \rangle) - \frac{1}{4} |\lambda|_g^2 = 0, \\ Q(V, g) := \text{Ric}(g) + ng - V^{-1} \text{Hess}_g V + \text{div}^* \Omega - \frac{1}{2V^2} \lambda \circ \lambda = 0, \\ (\mathcal{Q} - 2(V^{-1} \nabla^* \nabla V + n))(\theta) := -V^{-3} \text{div}(V\lambda) + d\sigma = 0 \end{cases}$$

with

$$\begin{aligned} -\Omega_j \equiv -\Omega(V, g, \tilde{V}, \tilde{g})_j &:= \tilde{V}^{-1} \tilde{\nabla}^k \tilde{V} (g - \tilde{g})_{kj} + \tilde{\nabla}^k (g - \tilde{g})_{kj} \\ &\quad - \frac{1}{2} \partial_j (\text{Tr}_{\tilde{g}}(g - \tilde{g})) \\ &\quad - \tilde{V}^{-1} \partial_j (V - \tilde{V}) - \tilde{V}^{-2} \partial_j \tilde{V} (V - \tilde{V}), \end{aligned}$$

and $\sigma = V^{-3} \nabla^i (V^3 \theta_i)$. In particular $D(q, Q)(\tilde{V}, \tilde{g}) = (l, L)$ is elliptic and the same is true for \mathcal{Q} .

4 Solutions to the modified equation gives solutions :

Suppose that θ solves $\operatorname{div}(V\lambda) + V^3 d\sigma = 0$, then clearly $\operatorname{div}[\operatorname{div}(V\lambda) + V^3 d\sigma] = \operatorname{div}(V^3 d\sigma) = 0$. If $\sigma = O(\rho^2)$ then $\sigma = 0$.

Now the divergence of $E(g) := \operatorname{Ric}(g) - \frac{1}{2}R(g)g$ equals

$$\begin{aligned} \operatorname{div}E(g)_j &= -\frac{1}{2}[\nabla^k \nabla_k \Omega_j + V^{-1} \nabla^i V \nabla_i \Omega_j \\ &\quad - V^{-2} \nabla_j V \nabla^i V \Omega_i + R_{ij} \Omega^i - V^{-1} \nabla_j \nabla^i V \Omega_i] \\ &=: -\frac{1}{2} \mathcal{B}(\Omega)_j . \end{aligned}$$

The Bianchi identity $\operatorname{div}E(g) = 0$ gives $\mathcal{B}(\Omega) = 0$. If $\Omega = O(\rho)$ then $\Omega = 0$.

5 The construction

We consider $\tilde{V}^2 d\varphi^2 + \tilde{g}$, a non degenerate AHES metric on $\mathbb{S}^1 \times M$. For any Riemannian metric g on M , close to \tilde{g} in $O(\rho^{-1})$, for any function V on M , close to \tilde{V} in $O(\rho^0)$, and for any $\hat{\theta} \in C^{k+2,\alpha}(\partial M, \mathcal{T}_1)$, there exists a unique solution

$$\theta = \theta(\hat{\theta}, V, g) \in O(\rho^0)$$

to

$$\begin{cases} \operatorname{div}(V\lambda) + V^3 d\sigma \equiv V^3[-Q + 2(V^{-1}\nabla^*\nabla V + n)]\theta = 0, \\ \theta - \hat{\theta} \in O(\rho), \end{cases}$$

where we recall that

$$\lambda_{ij} = -V^2(\partial_i\theta_j - \partial_j\theta_i) \text{ and } \sigma = V^{-3}\nabla^i(V^3\theta_i).$$

Moreover, the map $(\hat{\theta}, V, g) \mapsto \theta - \hat{\theta}$ is smooth. Now $\sigma = O(\rho^2)$ thus $\sigma = 0$. Let $F(\hat{\theta}, V, g)$ defined by

$$\begin{pmatrix} V(\nabla^* \nabla V + nV + \langle \Omega(V, g, \tilde{V}, \tilde{g}), dV \rangle) - \frac{1}{4} |\lambda|_g^2 \\ \text{Ric}(g) + ng - V^{-1} \text{Hess}_g V + \text{div}^* \Omega(V, g, \tilde{V}, \tilde{g}) + \frac{1}{2V^2} \lambda \circ \lambda \end{pmatrix},$$

and

$$\mathcal{F}(\hat{\theta}, W, h) := F(\hat{\theta}, \tilde{V} + W, \tilde{g} + h),$$

then \mathcal{F} is smooth from $C^{k+2, \alpha}(\partial M, \mathcal{T}_1) \times O(\rho^1) \times O(\rho^0)$ to $O(\rho^0) \times O(\rho^0)$

Proof of the theorem :

$$D_{(W,h)}\mathcal{F}(0,0,0) = D_{(V,g)}F(0,\tilde{V},\tilde{g}) = (l,L) ,$$

is an isomorphism. From the implicit function theorem the conclusion of Theorem are valid but for the modified equation. Now $\Omega = \Omega(V,g,\tilde{V},\tilde{g}) \in O(\rho^1)$ and $\mathcal{B}(\Omega) = 0$, so $\Omega = 0$.

6 An example of isomorphism

Theorem [J.M. Lee 2001] : Let $\mathbb{S}^1 \times M$ be equipped with a non-degenerate asymptotically hyperbolic metric \tilde{g} . For $\delta \in (0, n)$ the operator $\tilde{\Delta}_L + 2n$ is an isomorphism from $O(\rho^{\delta-2})$ to $O(\rho^{\delta-2})$.

If $\tilde{g} = \tilde{V}^2 d\varphi^2 + \tilde{g}$, W, θ, h does not depend on φ , let

$$\tilde{h} = 2\tilde{V}Wd\varphi^2 + 2\tilde{V}^2\theta_i d\varphi dx^i + h_{ij} dx^i dx^j .$$

Then

$$\begin{aligned} \tilde{\Delta}_L \tilde{h}_{00} + 2n\tilde{h}_{00} &= 2l(W, h). \\ \tilde{\Delta}_L \tilde{h}_{i0} + 2n\tilde{h}_{i0} &= V^2 Q(\theta)_i \\ \tilde{\Delta}_L \tilde{h}_{ij} + 2n\tilde{h}_{ij} &= 2L(W, h)_{ij}; . \end{aligned}$$

Thus the Lee's theorem gives

Corollary : The operator (l, L) is an isomorphism from $O(\rho^{\delta-1}) \times O(\rho^{\delta-2})$ to $O(\rho^{\delta-2}) \times O(\rho^{\delta-2})$ when $\delta \in (0, n)$. The operator Q is an isomorphism from $O(\rho^\delta)$ to $O(\rho^\delta)$ when $\delta \in (0, n)$.