

Condition Number Estimates for Oscillatory Integral Operators

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Focus of Today's Talk

For

$$\Delta u + k^2 u = 0,$$

and boundary integral methods for its solution:

How does conditioning depend on k , the geometry and on 'coupling parameters' in the integral equation formulation?

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For an continuous linear operator $A : X \rightarrow Y$, the condition number is

$$\text{cond } A := \|A\|_{X \rightarrow Y} \|A^{-1}\|_{Y \rightarrow X} \text{ where } \|A\|_{X \rightarrow Y} := \sup_{0 \neq x \in X} \frac{\|Ax\|_Y}{\|x\|_X}.$$

Large condition numbers associated with, inter alia, **slow convergence of iterative solution methods.**

Precise Focus of Today's Talk

For

$$\Delta u + k^2 u = 0,$$

and boundary integral equation methods for its solution.

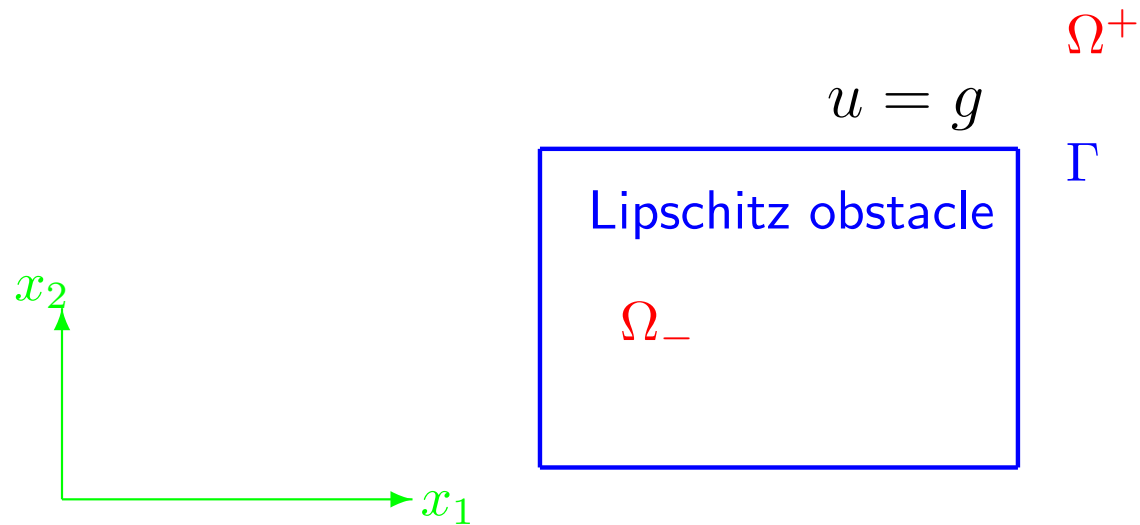
Precisely, we will study dependence of $\|A\|$ and $\|A^{-1}\|$ on k when A is a specific oscillatory boundary integral operator.

Contents

- Exterior Dirichlet problem for time-harmonic wave equation
- The standard combined potential integral equation formulation
- The known results (some very recent, 2007) for circle/sphere
- **New results for general Lipschitz obstacles**

The Exterior Problem in \mathbb{R}^d ($d = 2$ or 3)

$$\Delta u + k^2 u = 0$$

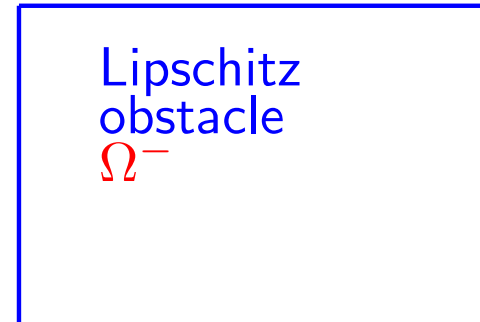


BVP. Find u which satisfies the Helmholtz equation in Ω_+ , $u = g$ on Γ , and the Sommerfeld radiation condition $\frac{\partial u}{\partial r} - iku = o\left(r^{-(d-1)/2}\right)$ as $r = |x| \rightarrow \infty$.

$$\Delta u + k^2 u = 0$$

 Ω^+

$$u = g$$

 Γ


Following Brakhage & Werner, Leis, Panich (1965), look for a solution as a **combined single and double-layer potential**, with density φ and **coupling parameter** $\eta \in \mathbb{R}$, i.e. in the form

$$u(x) = \int_{\Gamma} \frac{\partial \Phi(x, y)}{\partial n(y)} \varphi(y) ds(y) - i\eta \int_{\Gamma} \Phi(x, y) \varphi(y) ds(y), \quad x \in \Omega_+,$$

where

$$\Phi(x, y) := \frac{i}{4} H_0^{(1)}(k|x-y|) \approx C \frac{e^{ik|x-y|}}{(k|x-y|)^{1/2}} \quad (2D), \quad := \frac{1}{4\pi} \frac{e^{ik|x-y|}}{|x-y|} \quad (3D).$$

$$\Delta u + k^2 u = 0$$

 Ω^+

$$u = g$$

 Γ

Lipschitz
obstacle
 Ω^-

$$u(x) = \int_{\Gamma} \frac{\partial \Phi(x, y)}{\partial n(y)} \varphi(y) ds(y) - i\eta \int_{\Gamma} \Phi(x, y) \varphi(y) ds(y), \quad x \in \Omega_+.$$

satisfies the BVP iff **the trace of u on Γ is g** , i.e.

$$g(x) = \frac{1}{2}u(x) + \int_{\Gamma} \frac{\partial \Phi(x, y)}{\partial n(y)} \varphi(y) ds(y) - i\eta \int_{\Gamma} \Phi(x, y) \varphi(y) ds(y), \quad x \in \Gamma,$$

in operator form

$$A\varphi = 2g, \quad A := I + D - i\eta S.$$

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where I is the identity operator, $\eta \in \mathbb{R}$ the coupling parameter, and, for $\varphi \in L^2(\Gamma)$ and (almost all) $x \in \Gamma$,

$$S\varphi(x) = 2 \int_{\Gamma} \Phi(x, y) \varphi(y) ds(y), \quad D\varphi(x) = 2 \int_{\Gamma} \frac{\partial \Phi(x, y)}{\partial n(y)} \varphi(y) ds(y).$$

Boundedness and Invertibility.

$$A : H^{s+1/2}(\Gamma) \rightarrow H^{s+1/2}(\Gamma)$$

and is bounded for $|s| \leq 1/2$; further this mapping is a bijection, for $\eta \neq 0$ (Mitrea (1996), C-W & Langdon (2007)).

$$A := I + D - i\eta S$$

Wave Number Dependence. But how do $\|A\|$ and $\|A^{-1}\|$ depend on k , especially as $k \rightarrow \infty$, and how should we choose η ?

Engineering practice is to take $\eta = k$, but is this optimal in terms of minimising $\text{cond } A$?

We will address these questions for A as an operator on $H^0(\Gamma) = L^2(\Gamma)$.

The Case of a Circle/Sphere (Kress & Spassov '83, Kress '85)

Spherical harmonics are the eigenfunctions of A and A is normal.

The eigenvalues for the unit circle (Kress 1985) are

$$\lambda_m = \pi i H_m^{(1)}(k) [k J'_m(k) - i \eta J_m(k)], \quad m = 0, 1, \dots,$$

and, as operators on $L^2(\Gamma)$,

$$\|A\| = \sup_m |\lambda_m|, \quad \|A^{-1}\| = \frac{1}{\inf_m |\lambda_m|}, \quad \text{cond } A = \frac{\sup_m |\lambda_m|}{\inf_m |\lambda_m|}.$$

Dominguez, Graham, Smyshlyayev, Numer. Math., 2007 If Γ is a circle, and $\eta = k$, then, for all sufficiently large k , A is elliptic on $L^2(\Gamma)$, precisely

$$\inf_m \Re \lambda_m \geq 1 \Rightarrow \Re(A\phi, \phi) \geq \|\phi\|^2,$$

so that $\|A^{-1}\| \leq 1$.

C-W & Monk to appear SIAM J. Math. Anal. $1 \lesssim \|A^{-1}\| \lesssim 1 + \frac{k}{\eta}$.

Banjai, Sauter, SIAM J. Numer. Anal., 2007

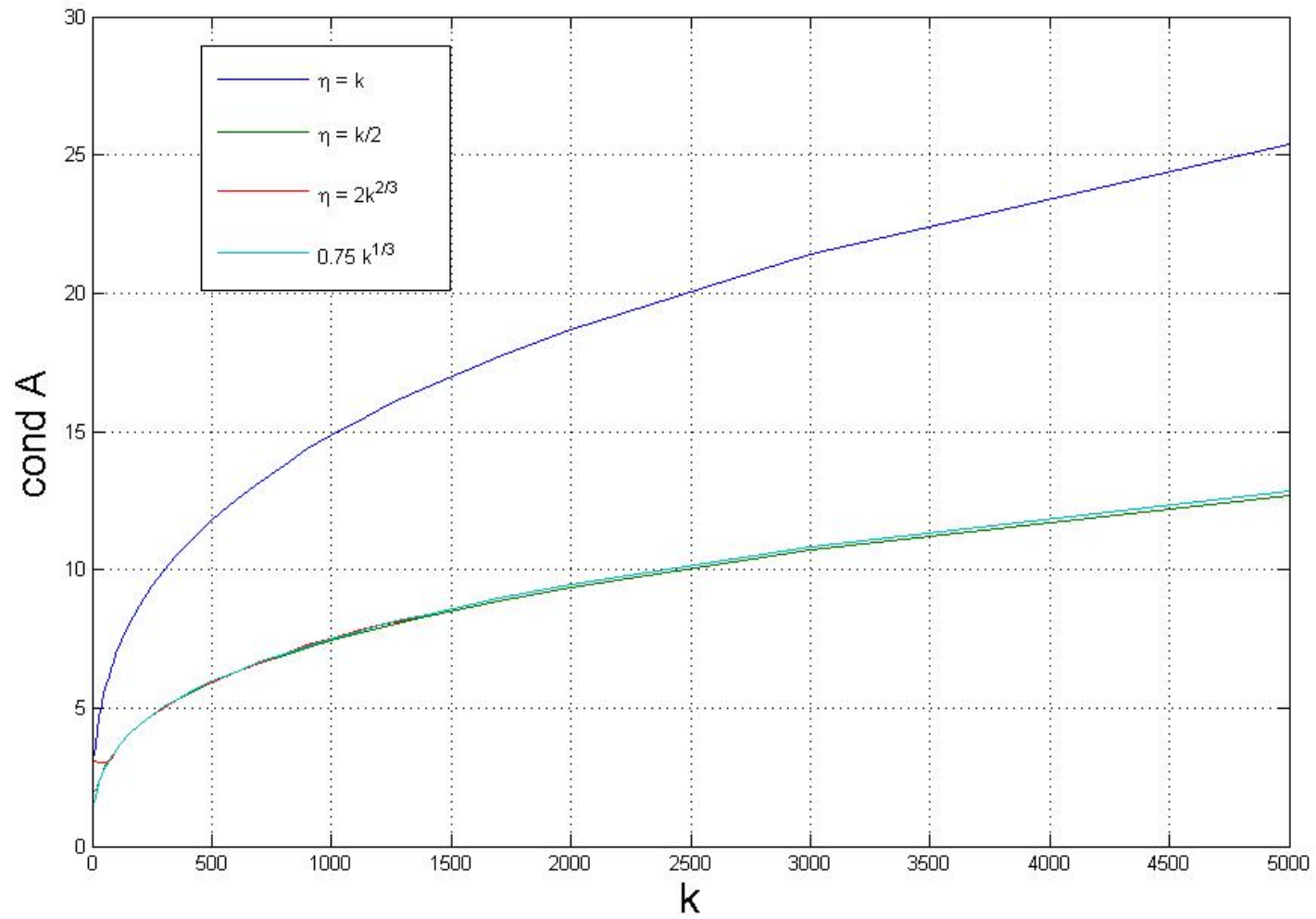
$$\|D\| \approx 1, \quad \|S\| \approx k^{-2/3} \text{ so } \|A\| \lesssim 1 + \eta k^{-2/3}.$$

so, for $\eta \approx k^\epsilon$, $\frac{2}{3} \leq \epsilon \leq 1$, it holds that

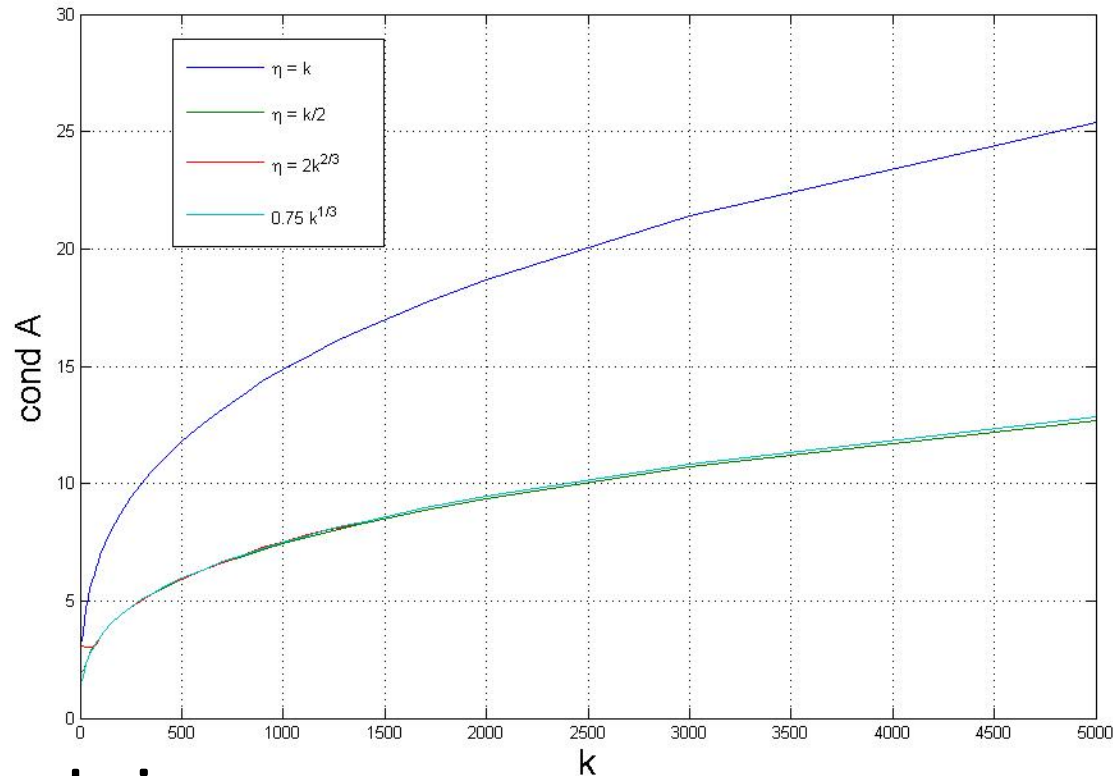
$$\text{cond } A \lesssim 1 + k^{1/3},$$

with equality for $\eta \approx k$.

Unit Circle: Plot of $\text{cond } A$ against k for choices of η



Unit Circle: Plot of cond A against k for choices of η



Conclusions.

- (i) cond A grows only slowly (like $k^{1/3}$) for circle sphere: cond $A \approx 100$ for $k \approx 5 \times 10^6$.
- (ii) cond A is almost minimised by every η between $0.75k^{2/3}$ and $k/2$.

**What Happens for Geometries Other than Circle/Sphere:
Some New Results**
(C-W, Graham, Langdon, Lindner, in preparation.)

Simple Upper Bounds, by interpolation, which ignore oscillation. E.g.

$$\|S\|_2 \leq \max(\|S\|_1, \|S\|_\infty) = \text{ess sup}_{x \in \Gamma} \int_{\Gamma} |\Phi(x, y)| ds(y) \lesssim 1$$

in **3D**, since

$$|\Phi(x, y)| = \left| \frac{\exp(ik|x - y|)}{4\pi|x - y|} \right| = \frac{1}{4\pi|x - y|}.$$

Similarly, in 3D,

$$\|D\|_2 \lesssim k,$$

which compares with

$$\|S\| \lesssim k^{-2/3}, \quad \|D\| \lesssim 1$$

for a sphere.

In **2D**

$$\|S\|_2 \leq \max(\|S\|_1, \|S\|_\infty) = \text{ess sup}_{x \in \Gamma} \int_{\Gamma} |\Phi(x, y)| ds(y) \lesssim k^{-1/2}$$

since

$$|\Phi(x, y)| = \frac{1}{4} |H_0^{(1)}(k|x - y|)| \leq Ck^{-1/2}|x - y|^{-1/2}.$$

Similarly,

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compared to

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for a circle.

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Similarly,

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for a circle. **But these simple bounds can be sharp.**

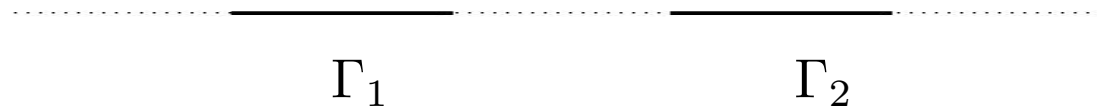
Lemma. If Γ contains a straight line segment, then

$$\|S\| \approx k^{-1/2}$$

so that, for $\eta \approx k$,

$$\|A\| = \|I + D - i\eta S\| \approx 1 + k^{1/2}.$$

Proof.



Take $\varphi(y) = \exp(iky_1)$ on Γ_1 , $= 0$ elsewhere. Then, for $x \in \Gamma_2$,

$$S\varphi(x) = \int_{\Gamma_1} \Phi(x, y) \exp(iky_1) dy_1 \approx C \int_{\Gamma_1} \frac{\exp(ik(x_1 - y_1))}{k^{1/2}(x_1 - y_1)^{1/2}} \exp(iky_1) dy_1.$$

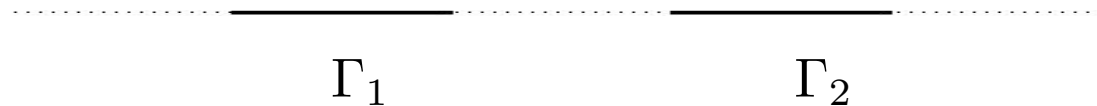
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Take $\varphi(y) = \exp(iky_1)$ on Γ_1 , $= 0$ elsewhere. Then, for $x \in \Gamma_2$,

$$|S\varphi(x)| = \left| \int_{\Gamma_1} \Phi(x, y) \exp(iky_1) dy_1 \right| \geq Ck^{-1/2}.$$

Lemma. In **2D**, if Γ contains a $C^{1,1}$ line element then

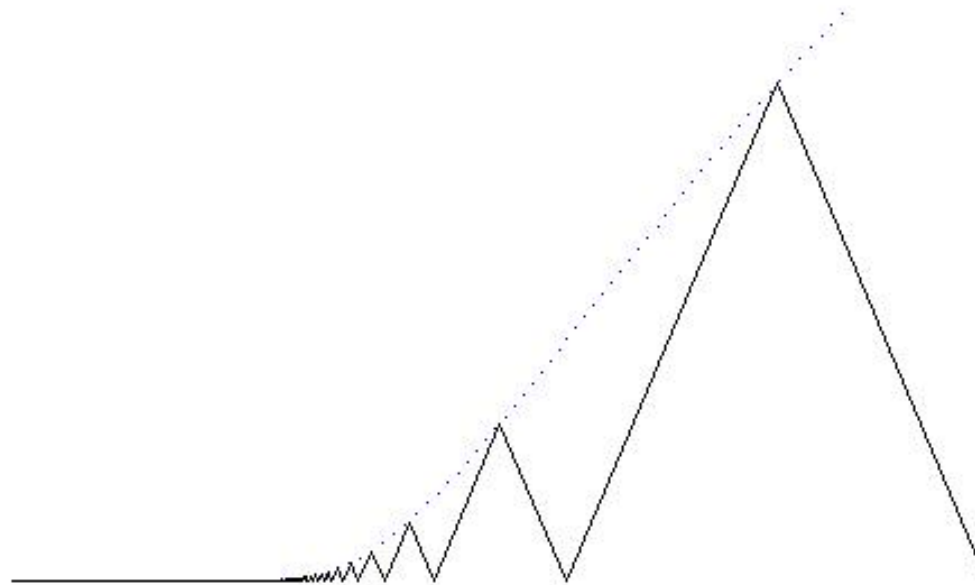
$$k^{-2/3} \lesssim \|S\| \lesssim k^{-1/2}.$$

If a $C^{2,1}$ line element with a point where the curvature vanishes, then

$$k^{-3/5} \lesssim \|S\| \lesssim k^{-1/2},$$

etc.

Lemma. If Γ has the form

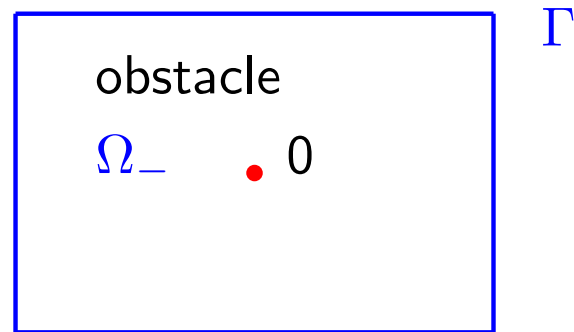


then, for every $\epsilon > 0$,

$$k^{1/2-\epsilon} \lesssim \|D\| \lesssim k^{1/2},$$

while if Γ is a polygon then $k^{1/4} \lesssim \|D\| \lesssim k^{1/2}$.

Bounding $\|A^{-1}\|$ for a Starlike Obstacle



Let $n(x)$ denote the outward unit normal at $x \in \Gamma$, and

$$R_0 := \max_{x \in \Gamma} |x|, \quad \delta_- := \text{ess. inf}_{x \in \Gamma} x \cdot n(x).$$

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Theorem. (C-W & Monk, to appear SIAM J. Math. Anal.) If Ω^- is a polyhedron which is starlike with respect to the origin (i.e. $\delta_- > 0$), or a more general piecewise smooth, Lipschitz, starlike domain, and if $kR_0 \geq 1$, then

$$\|A^{-1}\| \leq 1 + 2\theta + 2\theta^2 + \frac{k}{\eta}(3\theta + \theta^2),$$

where $\theta := R_0/\delta_-$.

Examples.

Circle/sphere: $\theta = 1$, $\|A^{-1}\| \leq 5 + 4\frac{k}{\eta}$.

Cube: $\theta = \sqrt{3}$, $\|A^{-1}\| \leq 10 + 8\frac{k}{\eta}$.

The Main Ingredients in the Proof

1. Green's theorem and a Rellich(-Payne-Weinberger-Nečas) type identity.
2. A property of radiating solutions of the Helmholtz equation, that, if v is radiating and Γ_R is the boundary of the sphere of radius R , then

$$\Re \int_{\Gamma_R} \bar{v} \frac{\partial v}{\partial r} ds + R \int_{\Gamma_R} \left(k^2 |v|^2 + \left| \frac{\partial v}{\partial r} \right|^2 - |\nabla_T v|^2 \right) ds \leq 2kR \Im \int_{\Gamma_R} \bar{v} \frac{\partial v}{\partial r} ds.$$

Summary of What is Known About $A = I + D - i\eta S$

1. Circle/Sphere

For $\eta \approx k$ and $k \gtrsim 1$,

$$\|A\| \approx k^{1/3}, \quad \|A^{-1}\| \approx 1, \quad \text{cond } A \approx k^{1/3}$$

and $\text{cond } A \lesssim k^{1/3}$ also for $\eta \approx k^\epsilon$, $\frac{2}{3} \leq \epsilon \leq 1$.

2. General Piecewise Smooth Lipschitz Domains

$$1 \leq \|A^{-1}\| \lesssim 1 + \frac{k}{\eta} \quad (\text{starlike case})$$

and, in 3D,

$$\|A\| \lesssim k + \eta.$$

so for $\eta \approx k$ and Γ starlike,

$$\text{cond } A \lesssim k.$$

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and, in 2D,

$$\|A\| \lesssim k^{1/2} + k^{-1/2}\eta.$$

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2. Polygon

$$1 \leq \|A^{-1}\| \lesssim 1 + \frac{k}{\eta} \quad (\text{starlike case})$$

and, in 2D, for $\eta \approx k$

$$\|A\| \approx k^{1/2}.$$

so for $\eta \approx k$ and Γ starlike,

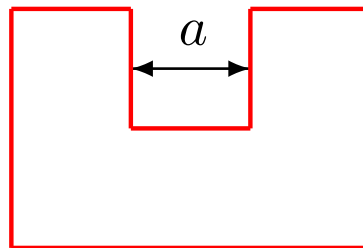
$$\text{cond } A \approx k^{1/2}.$$

What if Γ is not starlike?

In **2D**, if Γ contains two parallel line segments separated by the domain of propagation, distance a apart, then

$$ka \in \pi\mathbb{N} \Rightarrow \|A^{-1}\| \gtrsim k^{3/4} \text{ so } \text{cond } A \gtrsim k^{5/4} \text{ for } \eta \approx k .$$

Cf. $\text{cond } A \approx k^{1/3}$ for a circle/sphere.



k	$\ A\ $	p	$\ A^{-1}\ $	p
5	2.96	0.21	0.94	0.00
10	3.41	0.33	0.94	0.00
20	4.30	0.38	0.94	0.00
40	5.58	0.42	0.94	0.00
80	7.46	0.44	0.94	-0.00
160	10.12		0.94	

Square.

k	$\ A\ $	p	$\ A^{-1}\ $	p
5	4.58	0.04	1.84	0.54
10	4.70	0.16	2.68	0.57
20	5.27	0.18	3.97	0.65
40	5.98	0.24	6.23	0.72
80	7.05	0.27	10.24	0.72
160	8.49		16.92	

Trapping domain.

Open Problems

1. For smooth, strictly convex obstacle in 2D

$k^{-2/3} \lesssim \|S\| \lesssim k^{-1/2}$. Can we sharpen this, e.g. by

$$\|S\|_2 \leq \|S^* S\|_2^{1/2} \leq \max(\|S^* S\|_1^{1/2}, \|S^* S\|_\infty^{1/2})$$

(cf. Stein, Harmonic Analysis, 1993).

2. Sharper estimates than $\|S\| \lesssim 1$ for the 3D case

($\|S\| \lesssim k^{-2/3}$ for sphere).

3. Any wave-number-explicit upper bounds on $\|A^{-1}\|$ for non starlike obstacles.
4. Any wave-number-explicit bounds in the discrete case.
5. The case where η is replaced by an operator (see work of Antoine, Buffa, Bruno, Hiptmair, Levadoux, Sauter, etc.).