

Isaac Newton Institute, **HOP 2007**:

*Effective Computational Methods for Highly Oscillatory
Solutions*

**Open problems in the
computational solution of Volterra
functional equations with highly
oscillatory kernels**

Hermann Brunner

**Dept. of Mathematics and Statistics
Memorial University of Newfoundland
St. John's, NL**

Canada

and

**Dept. of Mathematics
Hong Kong Baptist University
Kowloon Tong**

Hong Kong, China

(Joint work with **Arieh Iserles** and **Syvert Nørsett**)

Volterra integral equations with HO kernels

Let

$$\mathbf{K}_{\omega,\alpha}(t, s) := (t - s)^{-\alpha} \mathbf{K}_0(t, s) e^{i\omega g(t-s)},$$

with $\omega \gg 1$, $0 \leq \alpha < 1$, and set

$$(\mathcal{V}_{\omega,\alpha} \mathbf{u})(t) := \int_0^t \mathbf{K}_{\omega,\alpha}(t, s) \mathbf{u}(s) ds .$$

Assume:

- \mathbf{K}_0 is smooth, **independent of** ω ;
- g is smooth; $g'(t) \neq 0$ on $I := [0, T]$.

Volterra functional equations:

$$\mathbf{u}(t) = \mathbf{f}(t) + (\mathcal{V}_{\omega,\alpha} \mathbf{u})(t), \quad t \in I;$$

$$\mathbf{u}'(t) = \mathbf{a}(t)\mathbf{u}(t) + \mathbf{f}(t) + (\mathcal{V}_{\omega,\alpha} \mathbf{u})(t), \quad t \in I;$$

$$(\mathcal{V}_{\omega,\alpha} \mathbf{u})(t) = \mathbf{f}(t), \quad t \in I \quad (\mathbf{f}(0) = \mathbf{0}).$$

Model problems: $g(t - s) = t - s$.

More general oscillating kernels

Motivating example:

$$\int_0^t \mathbf{J}_0(\omega(t-s))\mathbf{u}(s) \, ds = \mathbf{f}(t), \quad \omega \gg 1 \quad (\mathbf{f}(0) = 0).$$

\hookrightarrow Occurs as the (spatial) *Fourier transform* of a **retarded potential integral equation** (single layer potential for transient acoustic scattering from $2D$ surface).

(Details: **Davies & Duncan**, SINUM 42 (2004)).

For $f \in C^1(I)$ the (unique) **solution** is

$$\mathbf{u}(t) = \mathbf{f}'(t) + \omega \int_0^t \underbrace{\mathbf{J}_1(\omega(t-s))}_{\text{Bessel function of order 1}} \frac{\mathbf{f}(s)}{s} \, ds, \quad t \in I;$$

\mathbf{J}_0 and \mathbf{J}_1 denote, respectively, the **Bessel** functions of orders zero and one.

Solution representations:

$$u(t) = f(t) + \int_0^t \underbrace{(t-s)^{-\alpha} \mathbf{K}_0(t,s)}_{=:\mathbf{K}_{0,\alpha}(t,s)} e^{i\omega(t-s)} u(s) ds :$$

Let $\mathbf{K}_0 \in \mathbf{C}(D)$ ($D := \{0 \leq s \leq t \leq T\}$) and $0 \leq \alpha < 1$. For $f \in \mathbf{C}(I)$ the (unique) **solution** $u \in \mathbf{C}(I)$ has the form

$$u(t) = f(t) + \int_0^t \mathbf{R}_{\omega,\alpha}(t,s) f(s) ds, \quad t \in I,$$

with

$$\mathbf{R}_{\omega,\alpha}(t,s) := \mathbf{R}_{0,\alpha}(t,s) e^{i\omega(t-s)} .$$

Here,

$$\mathbf{R}_{0,\alpha}(t,s) = (t-s)^{-\alpha} \mathbf{Q}_{0,\alpha}(t,s)$$

is the **resolvent kernel** associated with the **non-oscillatory** kernel

$$\mathbf{K}_{0,\alpha}(t-s) := (t-s)^{-\alpha} \mathbf{K}_0(t,s) .$$

Illustration: $K_0(t, s) = \lambda = \text{const}$, $\alpha = 0$

$$\hookrightarrow u(t) = f(t) + \lambda \int_0^t e^{i\omega(t-s)} u(s) ds, \quad t \in I.$$

\Rightarrow Resolvent kernel of $K_{\omega,0}(t, s) = \lambda e^{i\omega(t-s)}$ is

$$R_{\omega,0}(t, s) = \lambda e^{\lambda(t-s)} e^{i\omega(t-s)}.$$

Hence, the **solution** has the form

$$u(t) = f(t) + \int_0^t R_{\omega,0}(t, s) f(s) ds, \quad t \in [0, T],$$

or, if $f \in C^1(I)$,

$$u(t) = f(t) + \frac{\lambda}{\lambda + i\omega} \left(-f(t) + e^{(\lambda+i\omega)t} f(0) \right) \\ + \frac{\lambda}{\lambda + i\omega} \int_0^t e^{(\lambda+i\omega)(t-s)} f'(s) ds.$$

Remark: Behaviour of solution $u(t)$ as $\omega \rightarrow \infty$: Analogous result to the one by **Ursell** (1968) for **highly oscillatory Fredholm integral equation**,

$$u(x) = f(x) + \mu \int_a^b K_0(x, y) e^{i\omega|x-y|} u(y) dy.$$

Volterra integro-differential equations

$$u'(t) = a(t)u(t) + (\mathcal{V}_{\omega, \alpha} u)(t) + f(t), \quad u(0) = u_0,$$

with

$$(\mathcal{V}_{\omega, \alpha} u)(t) := \int_0^t (t-s)^{-\alpha} \mathbf{K}_0(t, s) e^{i\omega g(t-s)} u(s) ds .$$

Equivalent Volterra integral equation:

$$u(t) = f_0(t) + \int_0^t \mathbf{H}_{\omega, \alpha}(t, s) u(s) ds,$$

Here,

$$\mathbf{H}_{\omega, \alpha}(t, s) := a(s) + \int_s^t (v-s)^{-\alpha} \mathbf{K}_0(v, s) e^{i\omega g(v-s)} dv .$$

\hookrightarrow Special case:

$$g(t-s) = t-s, \quad \alpha = 0, \quad \mathbf{K}_0(t, s) = \lambda$$

$$\Rightarrow \mathbf{H}_{\omega, 0}(t, s) = a(s) + \frac{\lambda}{i\omega} \left(e^{i\omega(t-s)} - 1 \right) .$$

Neutral delay VIDEs:

$$\frac{d}{dt}[\mathbf{u}(t) - (\mathcal{W}_{\omega, \alpha} \mathbf{u})(t)] = \mathbf{a}(t)\mathbf{u}(t) + \mathbf{b}(t)\mathbf{u}(\theta(t)), \quad t \geq 0,$$

with $\mathbf{u}(t) = \phi(t)$ if $t \leq 0$, and

$$(\mathcal{W}_{\omega, \alpha} \mathbf{u})(t) := \int_0^{\theta(t)} (t-s)^{-\alpha} \mathbf{K}_0(t-s) e^{i\omega \mathbf{g}(t-s)} \mathbf{u}(s) ds .$$

Non-vanishing delay: $\theta(t) := t - \tau(t)$, $\tau(t) \geq \tau_0 > 0$.

Let $\mathbf{z}(t) := \mathbf{u}(t) - (\mathcal{W}_{\omega, \alpha} \mathbf{u})(t)$.

Since the delay function $\theta(t)$ induces **primary discontinuity points** $\{\xi_\mu\}$ by

$$\theta(\xi_\mu) = \xi_{\mu-1}, \quad \mu \geq 1 \quad (\xi_0 := 0),$$

the given NVIDE is equivalent to the (local) ODEs with **highly oscillatory forcing terms**,

$$\mathbf{z}'(t) = \mathbf{a}(t)\mathbf{z}(t) + \underbrace{\mathbf{F}_{\omega, \alpha}(t)} + \mathbf{b}(t)\mathbf{u}(\theta(t)), \quad t \in [\xi_\mu, \xi_{\mu+1}],$$

with known $\mathbf{z}(\xi_\mu)$ ($\mu = 0, 1, \dots$). Here,

$$\mathbf{F}_{\omega, \alpha}(t) := \mathbf{a}(t) \int_0^{\theta(t)} (t-s)^{-\alpha} \mathbf{K}_0(t-s) e^{i\omega \mathbf{g}(t-s)} \mathbf{u}(s) ds .$$

For known $\mathbf{z}(t)$ on $[\xi_\mu, \xi_{\mu+1}]$ the solution on $[\xi_\mu, \xi_{\mu+1}]$ is

$$\mathbf{u}(t) = \mathbf{z}(t) + \underbrace{(\mathcal{W}_{\omega, \alpha} \mathbf{u})(t)}, \quad t \in [\xi_\mu, \xi_{\mu+1}] .$$

First-kind Volterra integral equations

$$(\mathcal{V}_{\omega,\alpha}\mathbf{u})(t) = \mathbf{f}(t), \quad t \in I \quad (\mathbf{f}(0) = \mathbf{0}) :$$

Equivalent **regular** first-kind VIE:

$$\int_0^t \mathbf{H}_{\omega,\alpha}(t, s) \mathbf{u}(s) ds = \mathbf{f}_\alpha(t),$$

with **smooth** kernel $\mathbf{H}_{\omega,\alpha}(t, s)$ given by

$$\int_0^1 (1-z)^{\alpha-1} z^{-\alpha} \underbrace{\mathbf{K}_0(s + (t-s)z, s)}_{\mathbf{K}_0(s + (t-s)z, s)} e^{i\omega g((t-s)z)} dz$$

and **non-smooth** right-hand side

$$\mathbf{f}_\alpha(t) := \int_0^t (t-s)^{\alpha-1} \mathbf{f}'(s) ds .$$

Note that

$$\mathbf{H}_{\omega,\alpha}(t, t) = \mathbf{K}_0(t, t) \underbrace{\int_0^1 (1-z)^{\alpha-1} z^{-\alpha} dz}_{=\Gamma(\alpha, 1-\alpha)} .$$

If $\mathbf{K}_0(t, t) \neq \mathbf{0}$ on I then the given V1 is equivalent to a second-kind Volterra integral equation with regular (highly oscillatory) kernel. **BUT:**

Solution of **V1** with highly oscillatory kernel is not necessarily highly oscillatory!

Example:

$$\int_0^t e^{i\omega(t-s)} u(s) ds = f(t), \quad t \in [0, T] \quad (f(0) = 0) :$$

↪ Equivalent **second-kind** Volterra equation is

$$u(t) = f'(t) + \int_0^t \underbrace{(-i\omega)e^{i\omega(t-s)}}_{=K_{\omega,0}(t,s)} u(s) ds ,$$

where the kernel $K_0(t,s) = -i\omega$ **depends on** ω . The resolvent of the kernel $K_{\omega,0}(t,s)$ is

$$R_{\omega,0}(t,s) = -i\omega ,$$

and hence the solution of **V1** is

$$u(t) = f'(t) - i\omega \cdot f(t), \quad t \in [0, T] .$$

Collocation solutions

$$u(t) = f(t) + \int_0^t K_{\omega, \alpha}(t, s) u(s) ds, \quad t \in [0, T] :$$

Let $I_h := \{t_n : 0 = t_0 < t_1 < \dots < t_N = T\}$, with

$$e_n := (t_n, t_{n+1}], \quad h_n := t_{n+1} - t_n, \quad h := \max_{(n)} \{h_n\}.$$

- **Collocation space:**

$$S_{m-1}^{(-1)}(I_h) := \{v : v|_{e_n} \in \pi_{m-1} \quad (0 \leq n \leq N)\}.$$

- **Collocation points:**

$$X_h := \{t_n + c_k h_n : 0 \leq n \leq N - 1\},$$

with $0 \leq c_1 < \dots < c_m \leq 1$.

- **Collocation equation:** Find $u_h \in S_{m-1}^{(-1)}(I_h)$ so that

$$u_h(t) = f(t) + (\mathcal{V}_{\omega, \alpha} u_h)(t) \quad \text{for } \underline{t \in X_h}.$$

\hookrightarrow Time-stepping: At $t = t_n + c_j h_n \in e_n$,

$$u_h(t) = f(t) + \Phi_n(t)$$

$$+ h_n \int_0^{c_j} K_{\omega, \alpha}(t, t_n + s h_n) u_h(t_n + s h_n) ds,$$

with *memory term*

$$\Phi_n(t) := \int_0^{t_n} K_{\omega, \alpha}(t, s) u_h(s) ds.$$

For local (Lagrange) basis $\{\phi_{n,k}\}$ of $S_{m-1}^{(-1)}(\mathbf{I}_h)$, need to compute the **local oscillatory integrals**

$$\int_0^1 \mathbf{K}_{\omega,\alpha}(t, t_\ell + sh_\ell) \phi_{\ell,k}(s) ds \quad (\ell < n)$$

and

$$\int_0^{c_j} \mathbf{K}_{\omega,\alpha}(t, t_n + sh_n) \phi_{n,k}(s) ds \quad (j = 1, \dots, m),$$

where

$$\mathbf{K}_{\omega,\alpha}(t, s) = (t - s)^{-\alpha} \mathbf{K}_0(t, s) e^{i\omega g(t-s)}.$$

Case I: ω small :

\hookrightarrow Collocation with $\{c_k\}$ given by **Radau II** points ($c_m = 1$) or **Lobatto** points ($c_1 = 0, c_m = 1$) yields the classical (optimal) estimates (for $\alpha = 0$),

$$\max\{|\mathbf{u}(t) - \mathbf{u}_h(t)| : t \in \mathbf{I}_h\} \leq \mathbf{Q}_\kappa(\omega) h^{2m-\kappa},$$

with $\kappa = 1$ (Radau II) and $\kappa = 2$ (Lobatto), and ‘small’ constant $\mathbf{Q}_\kappa(\omega)$.

(These estimates also hold for *fully discretised* collocation, provided the quadrature abscissas are the collocation points.)

Case II: $\omega \gg 1$: $\mathbf{u}_h \in \mathbf{S}_h(\mathbf{I}_h) \hookrightarrow$ defect δ_h
given by

$$\delta_h(\mathbf{t}) = -\mathbf{u}_h(\mathbf{t}) + \mathbf{f}(\mathbf{t}) + (\mathcal{V}_{\omega,\alpha}\mathbf{u}_h)(\mathbf{t}), \quad \underline{\mathbf{t}} \in \mathbf{I},$$

with

$$\underline{\delta_h(\mathbf{t})} = \mathbf{0} \quad \text{for} \quad \underline{\mathbf{t}} \in \mathbf{X}_h.$$

Collocation error $\mathbf{e}_h := \mathbf{u} - \mathbf{u}_h$:

$$\mathbf{e}_h(\mathbf{t}) = \delta_h(\mathbf{t}) + \int_0^{\mathbf{t}} \mathbf{R}_{\omega,\alpha}(\mathbf{t}, \mathbf{s}) \delta_h(\mathbf{s}) \, d\mathbf{s}. \quad \mathbf{t} \in I,$$

with

$$\mathbf{R}_{\omega,\alpha}(\mathbf{t}, \mathbf{s}) = \mathbf{R}_{0,\alpha}(\mathbf{t}, \mathbf{s}) e^{i\omega(\mathbf{t}-\mathbf{s})}.$$

At $\underline{\mathbf{t}} = \mathbf{t}_n + \mathbf{v}\mathbf{h}_n$ ($\mathbf{v} \in (0, 1]$) :

$$\begin{aligned} \delta_h(\mathbf{t}) = & -\mathbf{u}_h(\mathbf{t}) + \sum_{\ell=0}^{n-1} \mathbf{h}_\ell \int_0^1 \underbrace{\mathbf{K}_{\omega,\alpha}(\mathbf{t}, \mathbf{t}_\ell + \mathbf{s}\mathbf{h}_\ell)}_{\mathbf{K}_{\omega,\alpha}(\mathbf{t}, \mathbf{t}_\ell + \mathbf{s}\mathbf{h}_\ell)} \mathbf{u}_h(\dots) \, d\mathbf{s} \\ & + \mathbf{h}_n \int_0^{\mathbf{v}} \mathbf{K}_{\omega,\alpha}(\mathbf{t}, \mathbf{t}_n + \mathbf{s}\mathbf{h}_n) \mathbf{u}_h(\mathbf{t}_n + \mathbf{s}\mathbf{h}_n) \, d\mathbf{s} + \mathbf{f}(\mathbf{t}), \end{aligned}$$

and

$$\begin{aligned} \mathbf{e}_h(\mathbf{t}) = & \delta_h(\mathbf{t}) + \sum_{\ell=0}^{n-1} \mathbf{h}_\ell \int_0^1 \underbrace{\mathbf{R}_{\omega,\alpha}(\mathbf{t}, \mathbf{t}_\ell + \mathbf{s}\mathbf{h}_\ell)}_{\mathbf{R}_{\omega,\alpha}(\mathbf{t}, \mathbf{t}_\ell + \mathbf{s}\mathbf{h}_\ell)} \delta_h(\dots) \, d\mathbf{s} \\ & + \mathbf{h}_n \int_0^{\mathbf{v}} \mathbf{R}_{\omega,\alpha}(\mathbf{t}, \mathbf{t}_n + \mathbf{s}\mathbf{h}_n) \delta_h(\mathbf{t}_n + \mathbf{s}\mathbf{h}_n) \, d\mathbf{s}. \end{aligned}$$

Questions:

- **Choice of collocation points X_h ?**

↪ **Lobatto** points:

$$X_h = \{t_n + c_k h_n : \underline{0} = c_1 < \dots < \underline{c_m} = 1\}$$

(possibly with *multiplicities* greater than one, depending on complexity of kernel $K_{0,\alpha}(t,s)$).

- **Evaluation of highly oscillatory integrals ?**

↪ *Filon-type methods:*

Iserles and **Nørsett** (2005); **S. Olver** (2006). The latter method (extending **D. Levin** (1997)) does not require computation of moments.

For integrands given by **Bessel functions**, e.g. in collocation equations for

$$\int_0^t J_0(\omega(t-s))u(s) ds = f(t) ,$$

use approach of **D. Levin** (1997).

- **Choice of basis functions ?**

Some open problems

- **Pantograph-type integral equations:**

$$u(t) = f(t) + \int_0^{qt} (t-s)^{-\alpha} K_0(t,s) e^{i\omega g(t-s)} u(s) ds,$$

with $0 < q < 1$, $0 \leq \alpha < 1$, and $\omega \gg 1$.

\hookrightarrow *Proportional delay* vanishing at $t = 0$.

- Irregular oscillators $g(t-s)$ with **stationary points** ?

(See e.g.: **D. Levin** (1997), **Iserles & Nørsett** (2004), **Iserles** (2005), **S. Olver** (2006), **Huybrechs and Vandewalle** (2006)).

- Semi-discretised **discontinuous Galerkin** methods for

$$\int_0^t J_0(\omega(t-s)) u(s) ds = f(t) \quad (\omega \gg 1)$$

(**B., Davies & Duncan** (2007)).

Choice of quadrature (for inner products) / connection with **collocation solution** in $S_{m-1}^{(-1)}(\mathbf{I}_h)$?

(**D. Levin** (1997))

\hookrightarrow **Stability** and **convergence properties** of *semi-discretised* dG solution depend strongly on the **quadrature method** !