

Experimental Designs for Estimating Variance Components

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- ▶ Background
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Example. Bioassay validation



Figure: Plates for fluorescence/ luminescence-based immuno-assays and binding assays (white, black and clear)

Example. Bioassay validation

Aim

- ▶ Set up the main study
- ▶ Estimate variance components
- ▶ Identify best conditions
- ▶ Power calculations
- ▶ Tested compounds not important!

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Aim

- ▶ Set up the main study
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-
- ▶ How many plates?
 - ▶ How many occasions?
 - ▶ What compounds to test?

Background

- ▶ Herzberg & Cox (1969): less than 3% of the approximately 800 cited articles were classified as dealing with designs for variance components estimation
- ▶ Since then - no much change!

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 - Khuri (2001)

Background

- ▶ Herzberg & Cox (1969): less than 3% of the approximately 800 cited articles were classified as dealing with designs for variance components estimation
- ▶ Since then - no much change!
- ▶ Useful reviews:
Khuri & Sahai (1985)
Khuri (2001)
- ▶ Common features of past research:
 - devoted to specific problems
 - fragmented
- ▶ Recognized: **the optimum design depends on the unknown true values of the variance components!**

Some references

- ▶ Staggered nested designs - Bainbridge, T. R. (1965)
- ▶ Experimental designs for mean and variance components models - Giovagnoli, A. and Sebastiani, P. (1989)
- ▶ Computer search - Delgado, J. and Iyer, H. (1999)
- ▶ Split-factorial designs - Ankenman, B. E., Liu, H., Karr, A. F., and Picka, J. D. (2002)
- ▶ Assembled designs - Ankenman, B. E., Aviltes, A. I., and Pinheiro, J. C. (2003)

Linear mixed effect model

- ▶ Model

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{Z}\boldsymbol{\gamma} + \boldsymbol{\epsilon},$$

- ▶ \mathbf{y} - vector of N observations
- ▶ $\boldsymbol{\epsilon}$ - vector of experimental errors
- ▶ $\boldsymbol{\beta}$ & $\boldsymbol{\gamma}$ - vectors of p fixed and r random effects
- ▶ \mathbf{X} & \mathbf{Z} - the design matrices for the fixed and the random effects
- ▶ Combining $\mathbf{Z}\boldsymbol{\gamma} + \boldsymbol{\epsilon}$

$$\mathbf{Z}\boldsymbol{\gamma} = \sum_{i=0}^r \mathbf{Z}_i \boldsymbol{\gamma}_i$$

where

$$\mathbf{Z}_0 = \mathbf{I}_N \quad \boldsymbol{\gamma}_0 = \boldsymbol{\epsilon}$$

Model assumptions

$$E(\mathbf{y}) = \mathbf{X}\boldsymbol{\beta}, \quad E(\boldsymbol{\epsilon}) = \mathbf{0}, \quad E(\boldsymbol{\gamma}_i) = \mathbf{0}, \quad \text{var}(\boldsymbol{\epsilon}) = \sigma_\epsilon^2 \mathbf{I}_N$$

$$\text{var}(\boldsymbol{\gamma}) = \begin{bmatrix} \sigma_1^2 \mathbf{I}_{q_1} & & & \\ & \sigma_2^2 \mathbf{I}_{q_2} & & \\ & & \ddots & \\ & & & \sigma_r^2 \mathbf{I}_{q_r} \end{bmatrix} \text{ is a block diagonal matrix}$$

Also

$$\text{var}(\mathbf{y}) = \mathbf{V} = \sum_{i=0}^r \sigma_i^2 \mathbf{z}_i \mathbf{z}_i^T.$$

Maximum Likelihood Estimation

- ▶ Model

$$\mathbf{y} \sim N_N(\mathbf{X}\boldsymbol{\beta}, \mathbf{V})$$

- ▶ Likelihood

$$L = L(\boldsymbol{\beta}, \mathbf{V}|\mathbf{y}) = \frac{\exp\left(-\frac{1}{2}(\mathbf{y} - \mathbf{X}\boldsymbol{\beta})^T \mathbf{V}^{-1}(\mathbf{y} - \mathbf{X}\boldsymbol{\beta})\right)}{(2\pi)^{\frac{1}{2}N} |\mathbf{V}|^{\frac{1}{2}}}$$

- ▶ Log-likelihood

$$l = \log(L)$$

Maximum Likelihood Estimation

- ▶ Fisher information matrix

$$\mathbf{M} \begin{bmatrix} \beta \\ \sigma^2 \end{bmatrix} = \begin{bmatrix} \mathbf{X}^T \mathbf{V}^{-1} \mathbf{X} & \mathbf{0} \\ \mathbf{0} & \frac{1}{2} \text{tr} \left(\mathbf{V}^{-1} \mathbf{Z}_i \mathbf{Z}_i^T \mathbf{V}^{-1} \mathbf{Z}_j \mathbf{Z}_j^T \right) \end{bmatrix} \quad i, j = 0, \dots, r.$$

Maximum Likelihood Estimation

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- ▶ Optimizing designs for β and for σ^2 can be done independently

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- ▶ Optimality of designs for β does not depend on β

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- ▶ Optimality of designs for σ^2 does depend on $\sigma^2 = (\sigma_\epsilon^2, \sigma_1^2, \sigma_2^2, \dots, \sigma_r^2)$

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- ▶ Optimizing designs for β and for σ^2 can be done independently
- ▶ Optimality of designs for β does not depend on β
- ▶ Optimality of designs for σ^2 does depend on $\sigma^2 = (\sigma_\epsilon^2, \sigma_1^2, \sigma_2^2, \dots, \sigma_r^2)$
- ▶ **Hence, the design problem for σ^2 is similar to that for nonlinear models!**

V class of criteria of design optimality

- ▶ Let

$$\mathbf{M}(\boldsymbol{\sigma}^2) = \frac{1}{2} \text{tr} \left(\mathbf{V}^{-1} \mathbf{Z}_i \mathbf{Z}_i^T \mathbf{V}^{-1} \mathbf{Z}_j \mathbf{Z}_j^T \right) \quad i, j = 0, \dots, r$$

- ▶ Local \mathcal{D} -optimality requires

$$\mathcal{D}_V = \min \left| \mathbf{M}^{-1}(\boldsymbol{\sigma}^2) \right| \Big|_{\boldsymbol{\sigma}^2 = \boldsymbol{\sigma}_0^2}$$

- ▶ Bayesian \mathcal{D} -optimality requires

$$\mathcal{D}_V = \min \left| \mathbf{M}^{-1}(\boldsymbol{\sigma}^2) \right| \Big|_{\boldsymbol{\sigma}^2 \in \Sigma}$$

V class of criteria of design optimality

- ▶ Local \mathcal{A}_V -optimality requires

$$\min tr \mathbf{M}^{-1}(\boldsymbol{\sigma}^2) \Big|_{\boldsymbol{\sigma}^2 = \boldsymbol{\sigma}_0^2}$$

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Similarity

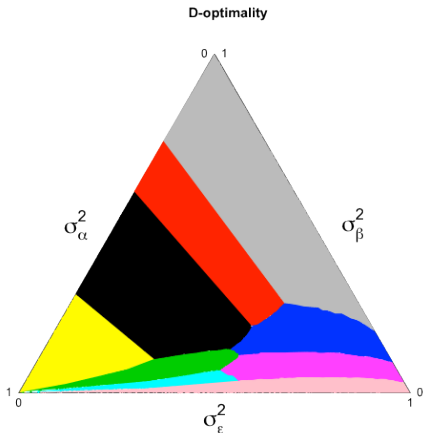
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V class of criteria of design optimality

c_V -optimality:

Interest in functions of the model parameters $g(\hat{\sigma}^2)$.

Example 1. Two-Way Crossed Model (No Interaction)

The model is

$$\begin{aligned}y_{ijk} &= \mu + \alpha_i + \beta_j + e_{ijk} \\ &= \mu \mathbf{1} + \mathbf{Z}_1 \boldsymbol{\alpha} + \mathbf{Z}_2 \boldsymbol{\beta} + \mathbf{Z}_0 \boldsymbol{\epsilon}\end{aligned}$$

$$i = 1 \dots a, \quad j = 1 \dots b$$

$$k = \begin{cases} 1 \dots n_{ij} \\ 1 \dots n \end{cases} \quad N = \begin{cases} \sum_i^a \sum_j^b n_{ij} & \text{Unbalanced} \\ abn & \text{Balanced} \end{cases}$$

Example 1. Two-Way Crossed Model (No Interaction)

Information matrix

$$\mathbf{M} \begin{bmatrix} \hat{\sigma}_\epsilon^2 \\ \hat{\sigma}_\alpha^2 \\ \hat{\sigma}_\beta^2 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} t_{\epsilon\epsilon} & t_{\alpha\alpha}/bn & t_{\beta\beta}/n \\ & t_{\alpha\alpha} & abn^2/\theta_4^2 \\ & & t_{\beta\beta} \end{bmatrix},$$

where

$$t_{\alpha\alpha} = b^2 n^2 \left(\frac{a-1}{\theta_{11}^2} + \frac{1}{\theta_4^2} \right) \quad t_{\beta\beta} = a^2 n^2 \left(\frac{b-1}{\theta_1^2} + \frac{1}{\theta_4^2} \right)$$

$$t_{\epsilon\epsilon} = \frac{abn - a - b + 1}{\theta_0^2} + \frac{a-1}{\theta_{11}^2} + \frac{b-1}{\theta_{12}^2} + \frac{1}{\theta_4^2}$$

$$\theta_0 = \sigma_\epsilon^2 \quad \theta_{11} = \sigma_\epsilon^2 + bn\sigma_\alpha^2$$

$$\theta_{12} = \sigma_\epsilon^2 + an\sigma_\beta^2 \quad \theta_4 = \sigma_\epsilon^2 + bn\sigma_\alpha^2 + an\sigma_\beta^2$$

Example 2. Two-Way Nested Balanced Model

The model

$$\begin{aligned}y_{ijk} &= \mu + \alpha_i + \beta_{ij} + e_{ijk} \\ &= \mu \mathbf{1} + \mathbf{Z}_1 \boldsymbol{\alpha} + \mathbf{Z}_2 \boldsymbol{\beta} + \mathbf{Z}_0 \boldsymbol{\epsilon}\end{aligned}$$

$$i = 1 \dots a, \quad j = 1 \dots b$$

$$k = \begin{cases} 1 \dots n_{ij} \\ 1 \dots n \end{cases} \quad N = \begin{cases} \sum_i^a \sum_j^b n_{ij} & \text{Unbalanced} \\ abn & \text{Balanced} \end{cases}$$

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where

$$t_{\alpha\alpha} = \frac{ab^2n^2}{\theta_{11}^2} \quad t_{\beta\beta} = an^2 \left(\frac{b-1}{\theta_1^2} + \frac{1}{\theta_{11}^2} \right)$$

$$t_{\epsilon\epsilon} = \frac{ab(n-1)}{\theta_0^2} + \frac{a(b-1)}{\theta_1^2} + \frac{a}{\theta_{11}^2}$$

$$\theta_0 = \sigma_\epsilon^2 \quad \theta_{11} = \sigma_\epsilon^2 + n\sigma_\beta^2 + bn\sigma_\alpha^2$$

$$\theta_1 = \sigma_\epsilon^2 + n\sigma_\beta^2$$

Example 3. Functions of variance components: Ratios

- ▶ In some applications, the interest is in functions of the variance components.
- ▶ Define the ratios as

$$\eta_i = \frac{\sigma_i^2}{\sigma_\epsilon^2} \quad i = \alpha, \beta.$$

Then,

$$\eta_\alpha = \frac{\sigma_\alpha^2}{\sigma_\epsilon^2} \quad \eta_\beta = \frac{\sigma_\beta^2}{\sigma_\epsilon^2}.$$

Example 1(cont). Bioassay as a Two-Way Crossed Model

A bioassay is performed over different occasions \implies days

The plates wells (exp. units) are measured in different sets of equipment \implies readers

The experiment consists of taking measurements on n plates, using b different readers in a different days.

The model is

$$\mathbf{y} = \mu \mathbf{1} + \mathbf{Z}_1 \boldsymbol{\alpha} + \mathbf{Z}_2 \boldsymbol{\beta} + \mathbf{Z}_0 \boldsymbol{\epsilon}$$

$\mu \implies$ overall mean $\boldsymbol{\alpha} \implies$ day effects

$\boldsymbol{\epsilon} \implies$ random error $\boldsymbol{\beta} \implies$ reader effects

Example 1(cont). Bioassay as a Two-Way Crossed Model

For the locally optimum designs, the space

$$\boldsymbol{\sigma}^2 = (\sigma_\epsilon^2, \sigma_\alpha^2, \sigma_\beta^2)$$

$$\sigma_r^2 = [0, 1] \quad r = \epsilon, \alpha, \beta$$

is mapped in a fine grid.

For one design and for each of 50000 $\boldsymbol{\sigma}^2$ triplets,

- ▶ the information matrix is computed
- ▶ the design optimality criterion value is calculated

The criterion values are compared across the candidate designs, and the best design is chosen for each $\boldsymbol{\sigma}^2$.

Example 1(cont). Bioassay as a Two-Way Crossed Model

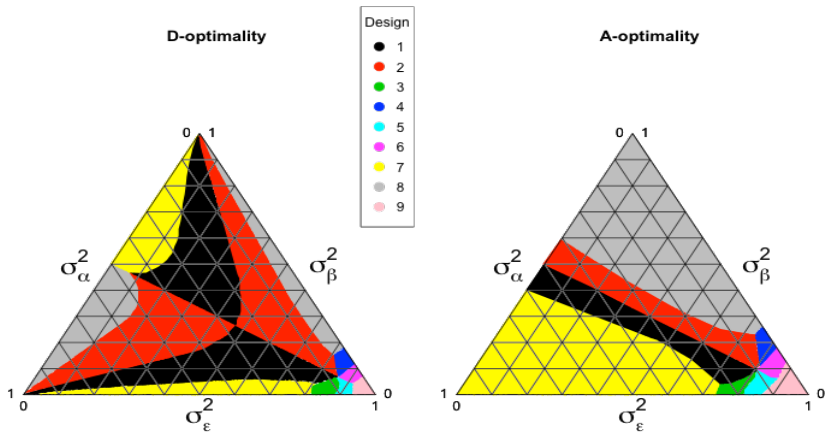
Consider a balanced design.

For $N = 24$, the triplet (a, b, n) can generate 9 candidate designs

	D1	D2	D3	D4	D5	D6	D7	D8	D9
a	4	3	4	2	3	2	6	2	2
b	3	4	2	4	2	3	2	6	2
n	2	2	3	3	4	4	2	2	6

Example 1(cont). Bioassay as a Two-Way Crossed Model

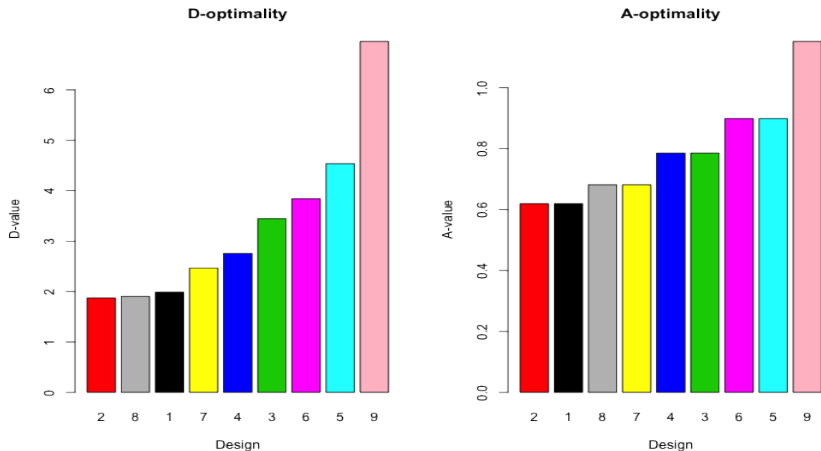
For individual variance components:



	D1	D2	D3	D4	D5	D6	D7	D8	D9
a	4	3	4	2	3	2	6	2	2
b	3	4	2	4	2	3	2	6	2
n	2	2	3	3	4	4	2	2	6

Example 1(cont). Bioassay as a Two-Way Crossed Model

Case 1: No specific information about σ^2 is available.

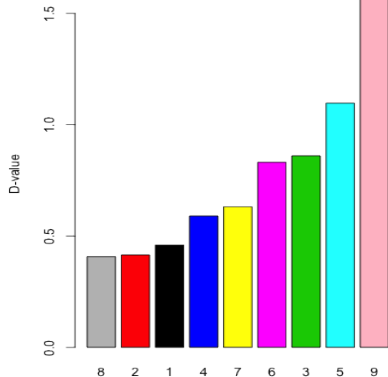


	Design	D1	D2	D3	D4	D5	D6	D7	D8	D9
a		4	3	4	2	3	2	6	2	2
b		3	4	2	4	2	3	2	6	2
n		2	2	3	3	4	4	2	2	6

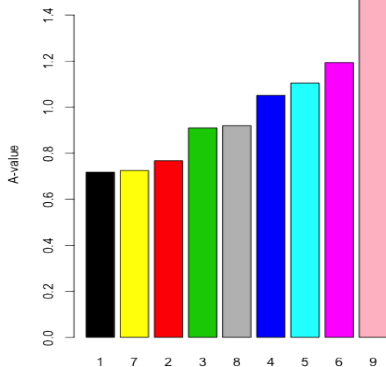
Example 1(cont). Bioassay as a Two-Way Crossed Model

Case 2: $\sigma_{\alpha}^2 > \sigma_{\beta}^2 > \sigma_{\epsilon}^2$

D-optimality



A-optimality



Design

	D1	D2	D3	D4	D5	D6	D7	D8	D9
a	4	3	4	2	3	2	6	2	2
b	3	4	2	4	2	3	2	6	2
n	2	2	3	3	4	4	2	2	6

Design

Example 2(cont). Bioassay as a Two-Way Nested Model

The bioassay is performed over different occasions \implies days.

Different plates are used in every experimental run.

This creates a nesting structure. Plates nested in Days.

The experiment consists of taking n measurements on b different plates in a different days.

The model is

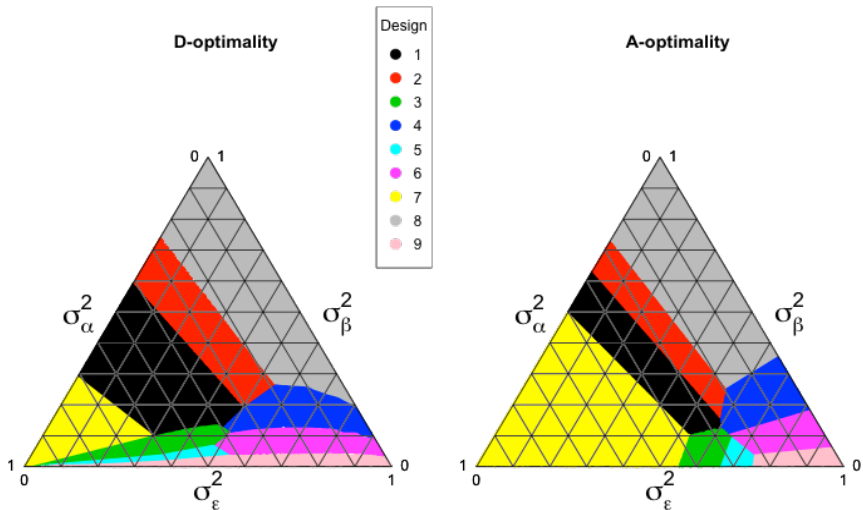
$$\mathbf{y} = \mu\mathbf{1} + \mathbf{Z}_1\boldsymbol{\alpha} + \mathbf{Z}_2\boldsymbol{\beta} + \mathbf{Z}_0\boldsymbol{\epsilon}$$

$\mu \implies$ overall mean $\boldsymbol{\alpha} \implies$ day effects

$\boldsymbol{\epsilon} \implies$ random error $\boldsymbol{\beta} \implies$ plate effects in Days

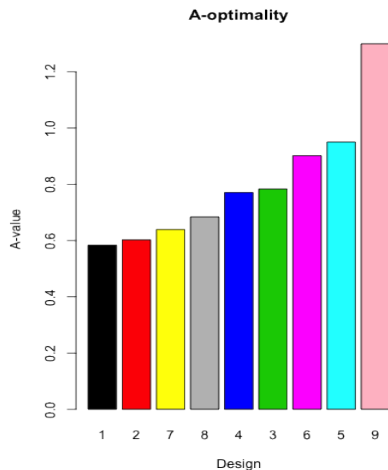
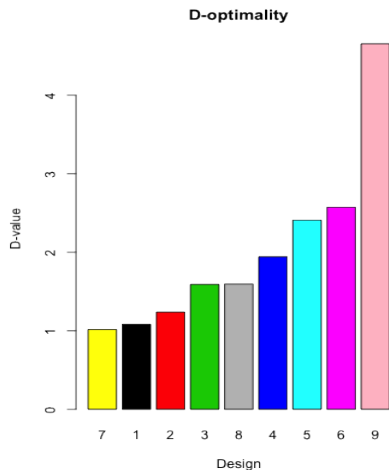
Example 2(cont). Bioassay as a Two-Way Nested Model

For individual variance components



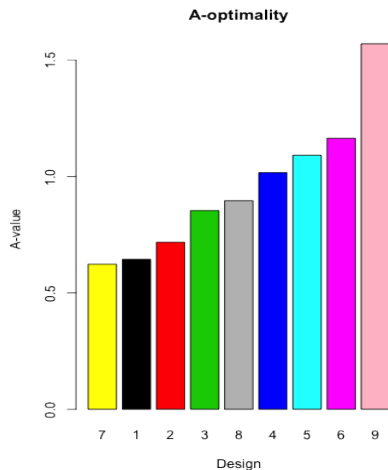
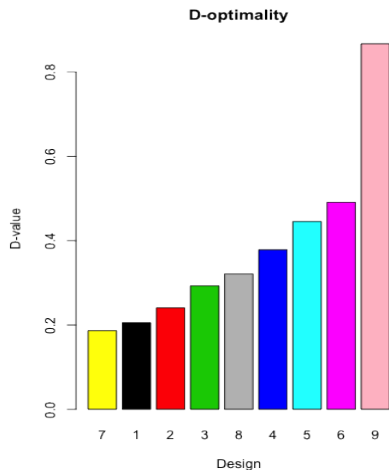
Example 2(cont). Bioassay as a Two-Way Nested Model

Case 1: No specific information about σ^2 is available.



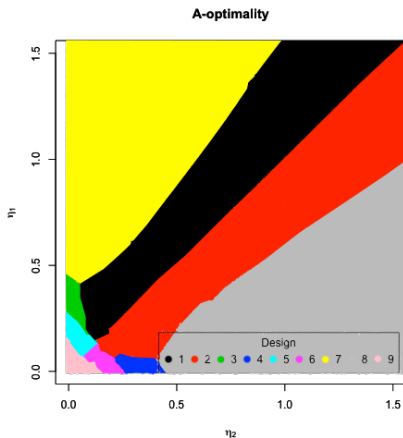
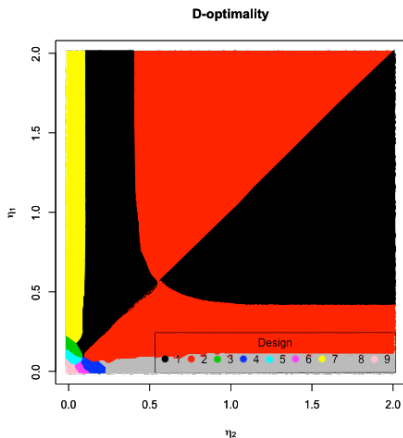
Example 2(cont). Bioassay as a Two-Way Nested Model

Case 2: $\sigma_{\alpha}^2 > \sigma_{\beta}^2 > \sigma_{\epsilon}^2$



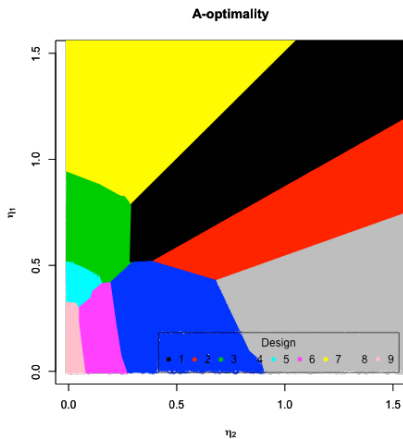
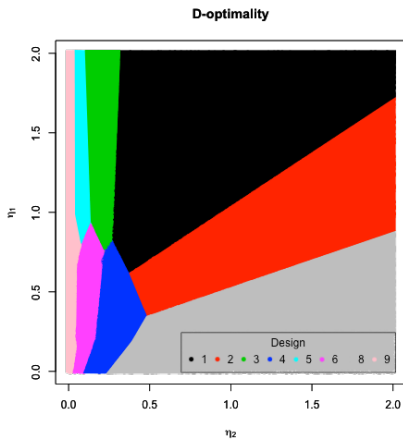
Example 3a(cont). Variance Components Ratios in the Two-Way Crossed Model

For ratios of variances $\eta_i = \frac{\sigma_i^2}{\sigma_\epsilon^2}$ $i = 1 \dots$



Example 3b(cont). Variance Components Ratios in the Two-Way Nested Model

For ratios of variances $\eta_i = \frac{\sigma_i^2}{\sigma_\epsilon^2}$ $i = 1 \dots$



Conclusions

- ▶ Methodology ready to *add* to the Optimum Design Theory
- ▶ Easy way to identify the best design
- ▶ Easy to extended to different models
- ▶ Easy interpretation

Further work

- ▶ Easy to extend for optimality of both fixed effects and variance components
- ▶ ... more types of Split-Plot designs
- ▶ ... many possible functions of the variance components
- ▶ ... variance models
- ▶ ... nonlinear model for the fixed effect
- ▶ ...