

Information in a Two-Stage Adaptive Optimal Design

Nancy Flournoy

Department of Statistics, University of Missouri

Designed Experiments:

Recent Advances in Methods and Applications

DEMA 2011

Isaac Newton Institute for the Mathematical Sciences

Stanford University, June 14-16, 2011

Motivating Question

For adaptive designs,

- ▶ How does the selection of sequential treatments affect the properties of estimators?
- ▶ Even if the design is ancillary to the experiment, can it be ignored?

Heuristics Behind Adaptive Optimal Designs

- ▶ Optimal designs (e.g., designs that minimize the variance of best dose) are functions of the unknown parameters for nonlinear response functions. So they need to be estimated.
- ▶ If MLEs are consistent, in the limit MLEs of the optimal designs will be consistent.
- ▶ Hence estimating the optimal design with accruing data from sequential cohorts of subjects will provide increasing efficient designs, and a reasonable overall strategy for treatment allocation.
- ▶ This strategy has been proposed frequently in the optimal design literature starting with (before?) Box and Hunter (1963).

Outline: Information in a Two-stage model

1. One Parameter Regression Model with Exponential Mean Function
2. Basic Review for Independent Observations
3. A Two-Stage Design
4. Illustration with Exponential Mean Function
5. Conclusions

Notation

treatments/stages $x_i, i = 1, 2;$

total sample size $n = \sum n_i;$

sample weights $w_i = n_i/n; \sum w_i = 1$

design $\{w_i, x_i\}, n$ fixed;

responses $\mathbf{y}_i = (y_{i1}, \dots, y_{in_i});$

expected response $\eta_i = \eta(x_i, \theta);$

mean response $\bar{y}_i = n_i^{-1} \sum_{j=1}^{n_i} y_{ij}$

A Regression Model with Exponential Mean Function

$$y = \eta(x, \theta) + \epsilon, \quad \epsilon \sim \mathcal{N}(0, 1)$$

$$\eta(x, \theta) = \exp(-\theta x), \quad \theta \in (-\infty, \infty), \quad 0 < x \leq \bar{b} < \infty$$

- ▶ Observe responses $\mathbf{y}_i = (y_{i1}, \dots, y_{in_i})$ at x_i .
- ▶ For two treatments, in canonical exponential family form:

$$\begin{aligned} \mathcal{L}(\theta, \mathbf{y}_1, \mathbf{y}_2 | x_1, x_2) &= \prod_{i=1}^2 f(\theta, \mathbf{y}_i | x_i) \propto \prod_{i=1}^2 \exp \left\{ -\frac{1}{2} \sum_{j=1}^{n_i} (y_{ij} - \eta_i)^2 \right\} \\ &\propto \exp \left\{ \sum_{i=1}^2 n w_i \left(\eta_i \bar{y}_i - \frac{1}{2} \eta_i^2 (x_i, \theta) \right) \right\} \end{aligned}$$

A Regression Model

- ▶ The probabilities of estimates on the boundaries goes to zero as $n \rightarrow \infty$,
- ▶ so I refer just to the interior for clarity of exposition.

Notation and Basic Elements: j th subject in i th stage

single unit score function $s_{ij} = s_{ij}(y_{ij}|x_i, \theta) = \frac{d}{d\theta} \ln f(\theta, y_{ij}|x_i) = (y_{ij} - \eta_i) \frac{d\eta_i}{d\theta} = (y_{ij} - \eta_i) x_i \eta_i$

within-stage scores $S_i = \sum_{j=1}^{n_i} s_{ij}$;

total score $S = \sum_{i=1}^2 S_i = \sum_{i=1}^2 n_i (\bar{y}_i - \eta_i) \frac{d\eta_i}{d\theta}$

expected unit information

$$\begin{aligned} \mu_i &= \mu(x_i, \theta) = \text{Var}_{y_{ij}|x_i}[s_{ij}] = E_{y_{ij}|x_i} \left[-\frac{d}{d\theta} s_{ij} \mid x_i \right] = \\ &E_{y_{ij}|x_i} \left[\left(\frac{d\eta_i}{d\theta} \right)^2 - (y_{ij} - \eta_i) \frac{d^2\eta_i}{d\theta^2} \mid x_i \right] = \left(\frac{d\eta_i}{d\theta} \right)^2 = x_i^2 \eta_i^2 \end{aligned}$$

per unit expected information

$$\mathcal{M}(\xi, \theta) = \frac{1}{n} \text{Var}[S] = \sum_{i=1}^2 w_i \mu_i = \sum_{i=1}^2 w_i x_i^2 \eta_i^2.$$

MLE approximation

1. $\ln\{\mathcal{L}_n\}$ is twice differentiable in the neighborhood of the true parameter θ_t , so a Taylor expansion of $\ln\{\mathcal{L}_n\}$ yields

$$\ln\{\mathcal{L}_n\} = \ln\{\mathcal{L}_n\} \Big|_{\theta=\theta_t} + (\theta - \theta_t) (S_{\theta=\theta_t}) + \frac{1}{2} (\theta - \theta_t)^2 \left(\frac{dS}{d\theta} \Big|_{\theta=\tilde{\theta}} \right),$$

where $\tilde{\theta} \in (\theta_t, \hat{\theta}_n)$.

2. $\text{Max}_{\theta}\{\ln\{\mathcal{L}_n\}\}$ occurs where $S + (\theta - \theta_t) \frac{dS}{d\theta} = 0$.
3. Taking the derivative of $\ln\{\mathcal{L}_n\}$ and rearranging terms, for $\theta = \hat{\theta}$ in the neighborhood of θ_t ,

$$\sqrt{n} (\hat{\theta}_n - \theta_t) \approx \left(-\frac{1}{n} \frac{dS}{d\theta} \right)^{-1} \frac{1}{\sqrt{n}} S.$$

Asymptotic Normality of the MLE - Given x_1 and x_2

$$\frac{1}{\sqrt{n}} S = \frac{1}{\sqrt{n}} \left(\sqrt{w_1} \frac{\sum_{j=1}^{n_1} s_{1j}}{\sqrt{n_1}} + \sqrt{w_2} \frac{\sum_{j=1}^{n_2} s_{2j}}{\sqrt{n_2}} \right) \\ \sim \mathcal{N}(0, w_1 \mu_1 + w_2 \mu_2).$$

$$\left(-\frac{1}{n} \frac{d S}{d \theta} \right) = w_1 \frac{\sum_{j=1}^{n_1} \frac{d}{d \theta} s_{1j}}{n_1} + w_2 \frac{\sum_{j=1}^{n_2} \frac{d}{d \theta} s_{2j}}{n_2} \quad \text{LLN} \\ \xrightarrow[n \rightarrow \infty]{as} w_1 \mu_1 + w_2 \mu_2.$$

By Slutsky's theorem,

$$\left(-\frac{1}{n} \frac{d S}{d \theta} \right)^{-1} \frac{1}{\sqrt{n}} S \xrightarrow[n \rightarrow \infty]{\mathcal{D}} \mathcal{N} \left(0, [w_1 \mu_1 + w_2 \mu_2]^{-1} \right).$$

Adaptively Selecting the Stage 2 Design Point

Observe \mathbf{y}_1 at fixed x_1 . Then select the stage 2 design point as

$$\begin{aligned}x_2 &= \arg \max_x \text{Var}_{y_{2j}|x_2}[s_{2j}] \Big|_{\theta=\hat{\theta}_1} \\ &= \arg \max_x \left(x^2 \exp \left\{ -2\hat{\theta}_1 x \right\} \right) = \min \left\{ \hat{\theta}_1^{-1}, \bar{b} \right\}.\end{aligned}$$

The MLE from the stage 1 data is

$$\hat{\theta}_1 = -\ln \bar{y}_1 / x_1,$$

if $0 < \bar{y}_1 < 1$; at bounds else

The Adaptive Likelihood

Assuming responses given the treatment are independent of the past, i.e., $f(\mathbf{y}_2|x_2, x_1, \mathbf{y}_1, \theta) = f(\mathbf{y}_2|x_2, \theta)$,
the total likelihood after stage 2 is

$$\mathcal{L}(x_1, x_2, \mathbf{y}_1, \mathbf{y}_2, \theta) = f(\mathbf{y}_2|x_2, \theta)f(x_2|x_1, \mathbf{y}_1, \theta)f(\mathbf{y}_1|x_1, \theta).$$

So long as x_2 is a completely determined by x_1 and \mathbf{y}_1 ,
 $f(x_2|x_1, \mathbf{y}_1, \theta)$ is a delta function; the design is ancillary.
Note density is no longer member of exponential family:

$$\begin{aligned} \mathcal{L}(x_1, x_2, \mathbf{y}_1, \mathbf{y}_2, \theta) &= f(\mathbf{y}_2|x_2, \theta)f(\mathbf{y}_1|x_1, \theta) \\ &\propto \exp \left\{ nw_1 \left(\eta_1 \bar{y}_1 - \frac{1}{2} \eta_1^2 \right) + nw_2 \left(\eta_2 (\bar{y}_1, x_1) \bar{y}_2 - \frac{1}{2} \eta_2^2 (\bar{y}_1, x_1) \right) \right\}. \end{aligned}$$

Adaptive Expected Information: $\text{Var} [s_{ij}] = \text{E} \left[-\frac{1}{n_i} \frac{d}{d\theta} s_{ij} \right]$

$$\begin{aligned} \text{E}_{y_{ij}|x_i} \left[-\frac{1}{n_i} \frac{d}{d\theta} s_{ij} \right] &= \text{E}_{y_{ij}|x_i} \left[\left(\frac{d\eta_i}{d\theta} \right)^2 - (y_{ij} - \eta_i) \frac{d^2\eta_i}{d\theta^2} \middle| x_i \right] \\ &= x_i^2 \eta_i^2 = \mu(x_i, \theta). \end{aligned}$$

$$\mu(x_2, \theta) = x_2^2 \exp^{-2\theta x_2} = \left(\frac{-x_1}{\ln \bar{y}_1} \right)^2 \exp \left\{ -2\theta \left(\frac{-x_1}{\ln \bar{y}_1} \right) \right\}.$$

$$\text{E} \left[-\frac{1}{n_i} \frac{d}{d\theta} s_{ij} \right] = \begin{cases} \mu(x_1, \theta) & \text{if } i = 1 \\ \text{E}_{\bar{y}_1} [\mu(\bar{y}_1, \theta)] & \text{if } i = 2. \end{cases}$$

Second stage information

NOTE:

- ▶ $\mu(x_2, \theta)$ is random function of \bar{y}_1 !
- ▶ $\mu(x_2, \theta)$ will only converge to a constant only as \bar{y}_1 converges to a constant.
- ▶ Conditioning on x_2 is equivalent to conditioning of stage 1 responses!!!!

$$\sqrt{n} \left(\hat{\theta}_n - \theta_t \right) \approx \left(-\frac{1}{n} \frac{dS}{d\theta} \right)^{-1} \frac{1}{\sqrt{n}} S$$

$$f(S) = \int f(S|\bar{y}_1) f(\bar{y}_1) d\bar{y}_1.$$

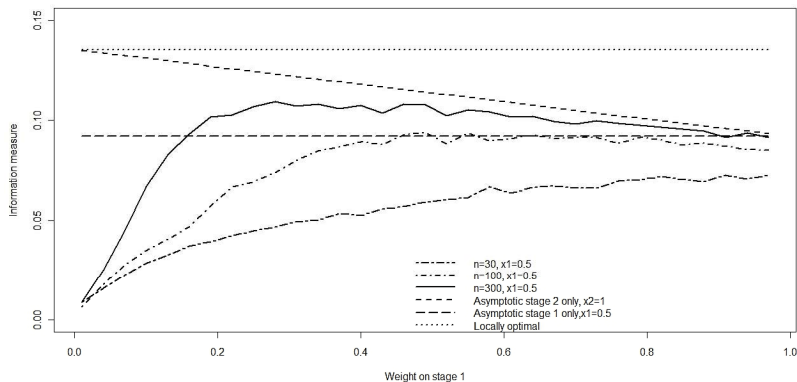
$$\begin{aligned} \frac{1}{\sqrt{n}} S \Big|_{\bar{y}_1} &= \frac{1}{\sqrt{n}} \left(\sqrt{w_1} \frac{\sum_{j=1}^{n_1} s_{1j}}{\sqrt{n_1}} + \sqrt{w_2} \frac{\sum_{j=1}^{n_2} s_{2j}}{\sqrt{n_2}} \right) \Big|_{\bar{y}_1} \\ &= \frac{1}{\sqrt{n}} \sqrt{w_1} \frac{\sum_{j=1}^{n_1} s_{1j}}{\sqrt{n_1}} + \mathcal{N}(0, w_2 \mu_2) \end{aligned}$$

$$\begin{aligned} \left(-\frac{1}{n} \frac{dS}{d\theta} \right) &= w_1 \frac{\sum_{j=1}^{n_1} \frac{d}{d\theta} s_{1j}}{n_1} + w_2 \frac{\sum_{j=1}^{n_2} \frac{d}{d\theta} s_{2j}}{n_2} \\ &\xrightarrow[n \rightarrow \infty]{\text{as}} w_1 \mu_1 + w_2 \mu_2 \end{aligned}$$

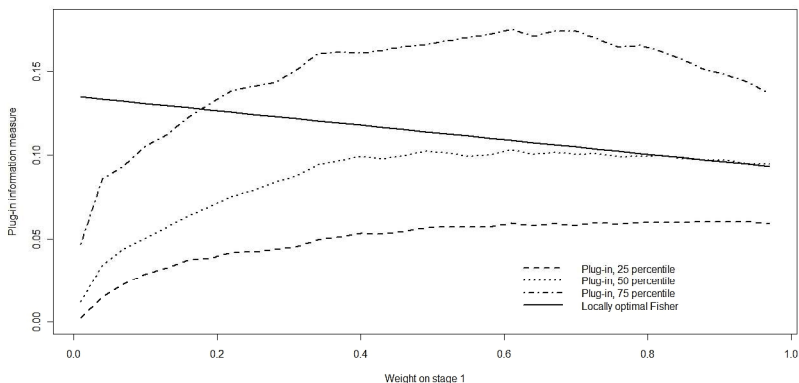
Illustration: $\theta = 1$, $x \in (.01, 100)$

- ▶ $x_1 = 0.5$
- ▶ optimal $x_2 = \arg \max_x \text{Var}_{y_{2j}|x_2}[s_{2j}] \Big|_{\theta=1} = 1.0$;
- ▶ adaptive $x_2 = \arg \max_x \text{Var}_{y_{2j}|x_2}[s_{2j}] \Big|_{\theta=\hat{\theta}_1}$

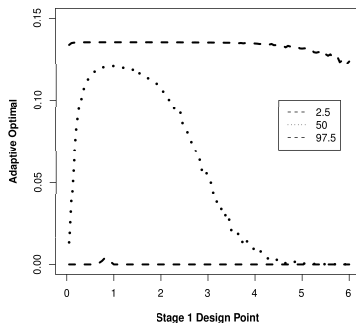
Asymptotic Fisher for $x = .5$ and $x = 1.0$ alone;
 two-sample locally optimal and median two-stage plug-in
 estimates for $n = 30, 100, 300$ versus w_1 at $x = .5$.



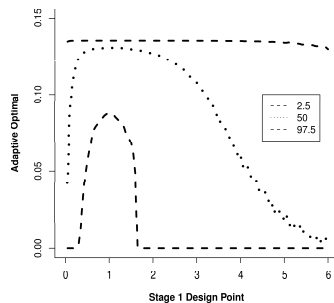
Two-sample locally optimal Fisher and percentiles of two-stage plug in estimates for $n = 1000$ versus w_1 at $x = .5$.



Stage 2 2.5th, 50th and 97.5th Percentiles of μ_2 ; $n_1 = n_2 = .5$



(a) $n_i = 30$



(b) $n_i = 100$

Conclusions

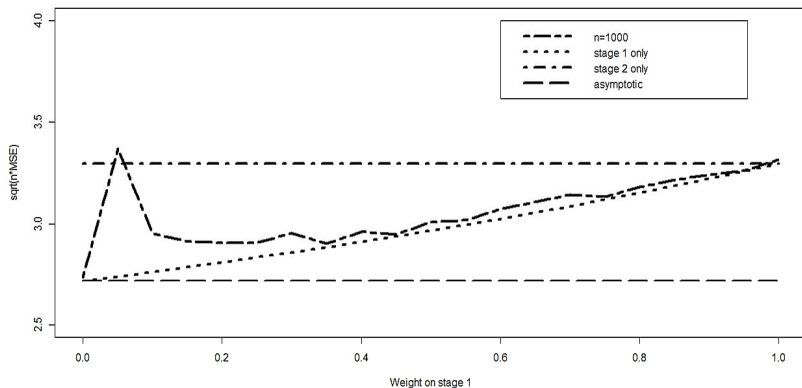
- ▶ The locally optimal adaptive design is ancillary, but informative.
- ▶ The conditional incremental information after the first stage is a random variable depending on stage one observations.
- ▶ The conditional incremental information does not achieve the Cramer-Rao Bound
- ▶ MLEs from the locally optimal adaptive design do not have the hoped for optimality, and if the stage one design has a small sample size, their variance is random.

Thank you!

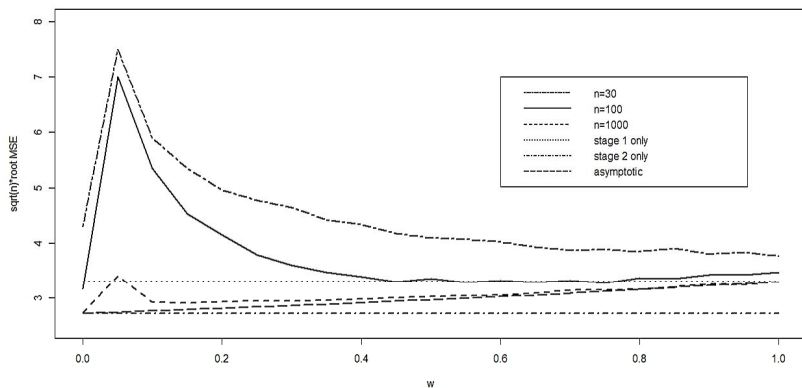
References

Yao, P, Flournoy, N. (2010) Information in a Two-stage Adaptive Optimal Design for Normal Random Variables having a One Parameter Exponential Mean Function. MoDa 9 229-236. Springer (eds. Giovagnoli, A., Atkinson, A.C., Torsney, B., May, C.).

Asymptotic Fisher⁻¹ for $x = .5$ and $x = 1.0$ alone;
 two-sample locally optimal and two-stage
 $\sqrt{n} \times \text{MSE}(\hat{\theta})$, $n = 1000$ versus w_1 at $x = .5$.



Asymptotic Fisher⁻¹ for $x = .5$ and $x = 1.0$ alone;
 two-sample locally optimal and two-stage
 $\sqrt{n} \times \text{MSE}(\hat{\theta})$, $n = 30, 100, 1000$ versus w_1 at $x = .5$.



Remarks

- ▶ The $\max_{x_1} \{\mu_2\} = 0.135$, which is the asymptotic Fisher's information.
- ▶ The 97.5th percentiles of μ_2 attain 0.135 at all but the highest values of x_1 for $n = 100$ and 30.
- ▶ In contrast, the 97.5th percentile of $-\frac{d}{d\theta}s_{2j}$ is greater than 0.135 except for values of x_1 somewhat less than one.
- ▶ Furthermore, $-\frac{d}{d\theta}s_{2j}$ is negative with high probability.

Remarks

- ▶ The median of μ_2 , attains its maximum value when $x_1 = 1$ for $n = 100$ and 30 .
- ▶ The median of μ_2 comes closer to 0.135 at $x_1 = 1$ as the sample size increases.
- ▶ Indeed, the median of μ_2 is close to 0.135 for a range of values of x_1 that includes $x_1 = 1$; this range is larger for $n = 100$ than for $n = 30$.
- ▶ For $n = 30$, the 2.5th percentile of μ_2 is zero, except for a very small blip for x_1 just less than one; however, for $n = 100$, the 2.5th percentile of μ_2 is nearly quadratic for $x_1 \in (0.2, 1.8)$ with its maximum approximately 50% of 0.135 .