

# Inverse Problems in Science and Engineering

Isaac Newton Institute for Mathematical Sciences

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## *Inversion of Pressure Transient Testing Data*

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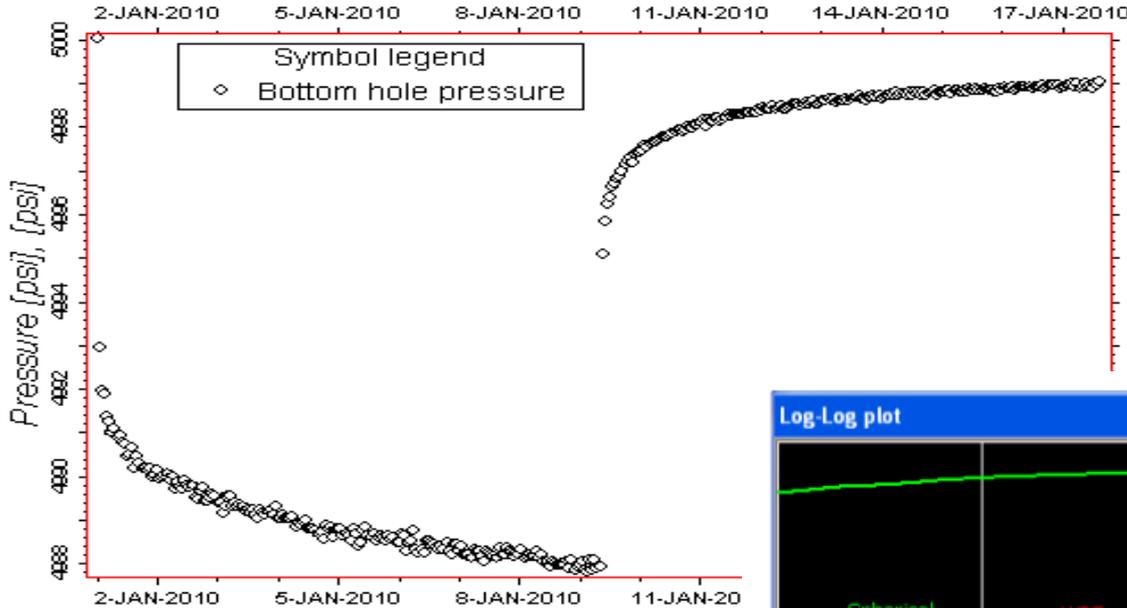
# Outline

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- What is a pressure-transient test?
  - What information can be obtained from the data.
- Simple prior model.
- Gradient-free methods.
- Gradient based methods.
  - Adjoint gradients necessary.
  - Separation of prior/likelihood.
  - Uncertainty?
- Gradient based sampling.
  - Langevin method.

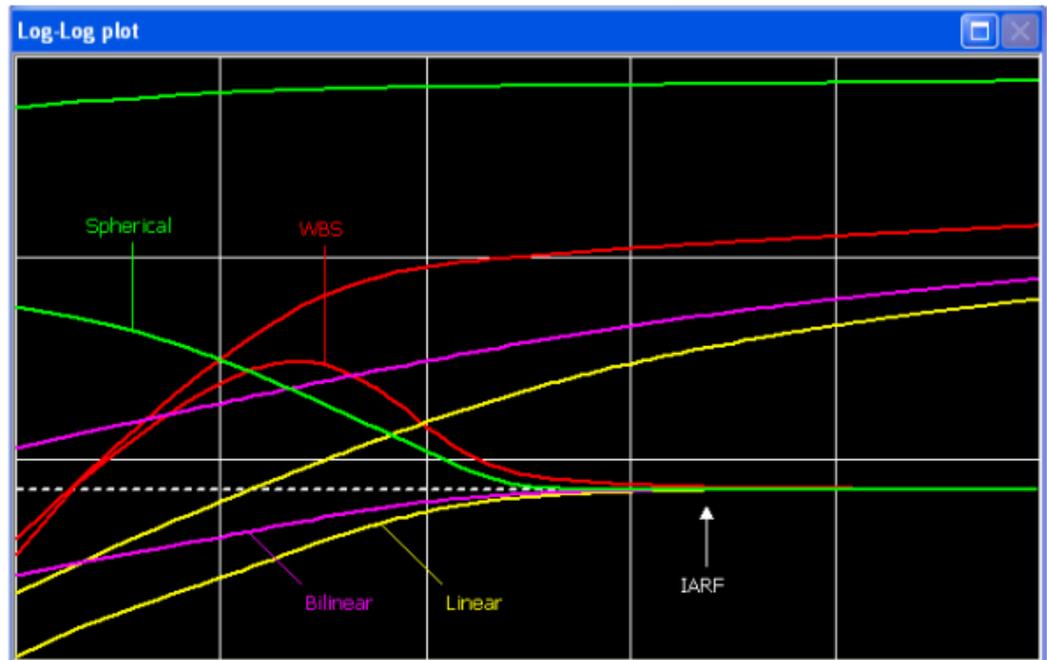
# Pressure Transient Testing (PTT)

## Production Well: Downhole Tubing Pressure



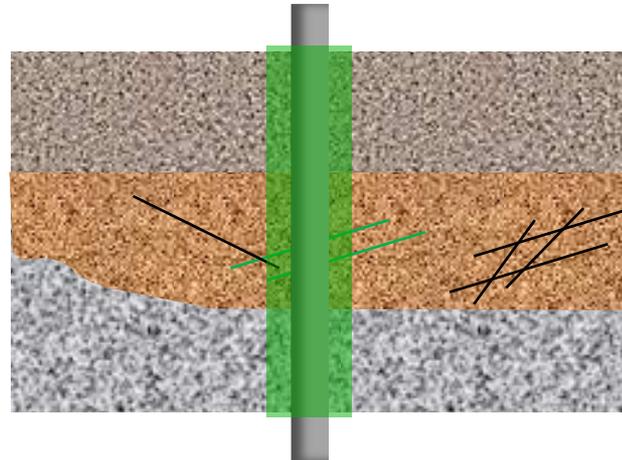
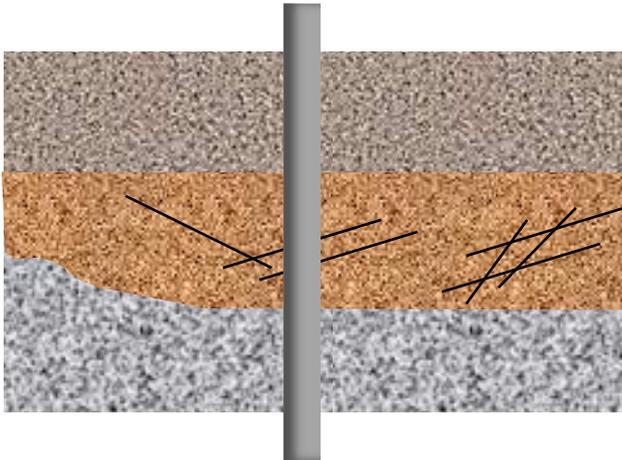
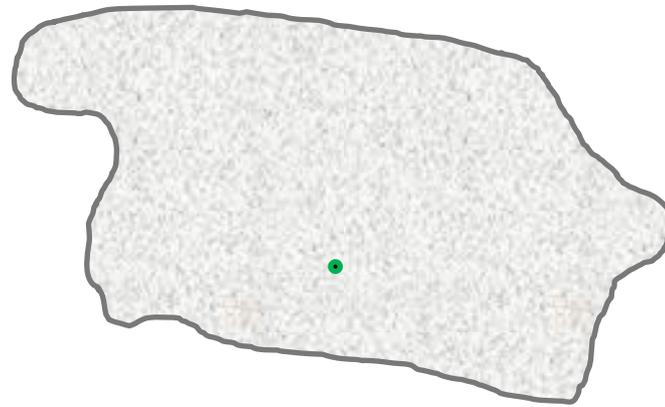
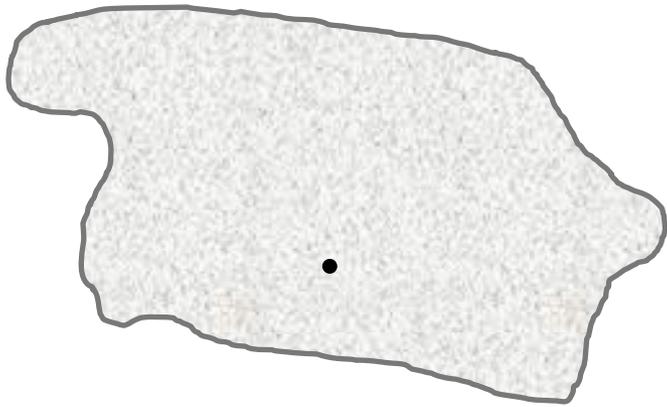
- Pressure response during draw-down and build-up
- Response is typically matched to analytical models

- In-situ, direct measurement of permeability
- Time scale is much shorter than for production history matching.

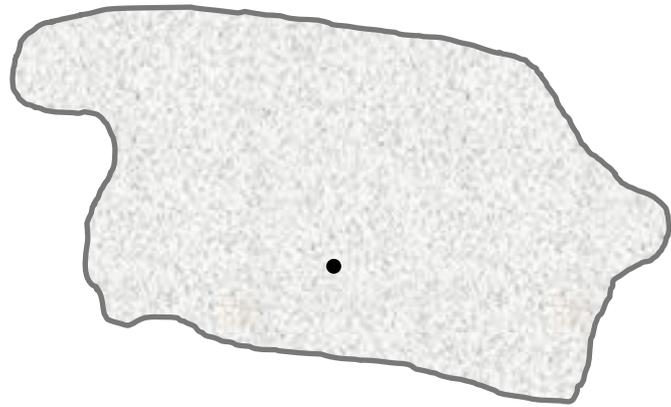


# Resolution of inversion by data source

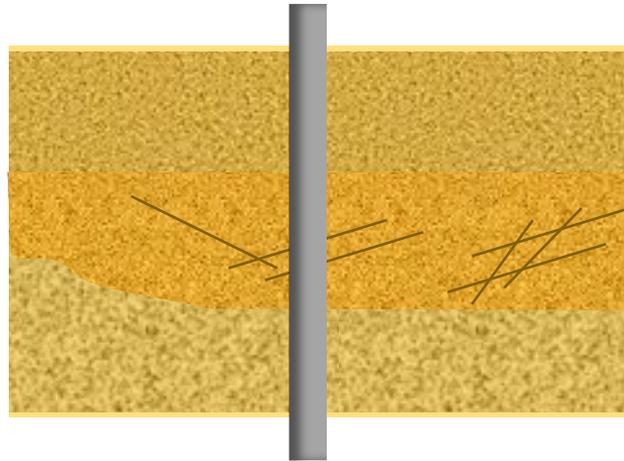
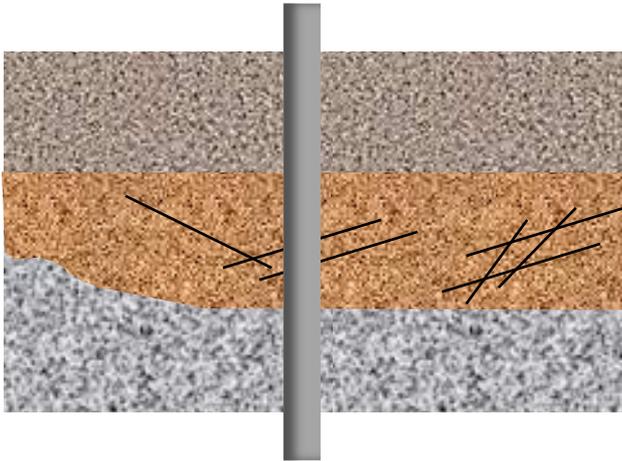
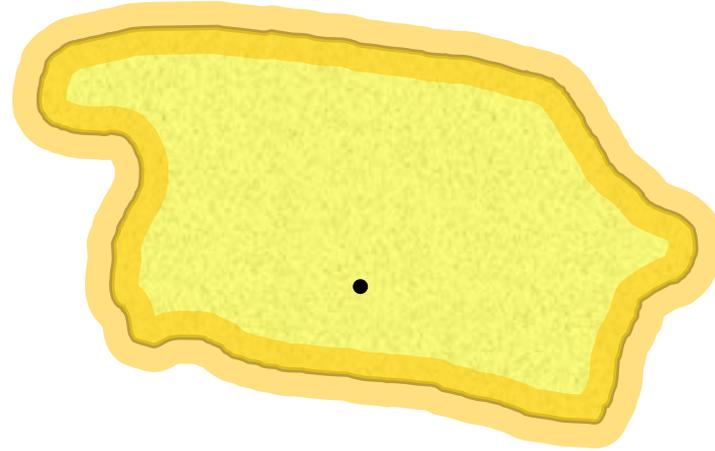
Cores/Logs



# Resolution of inversion by data source

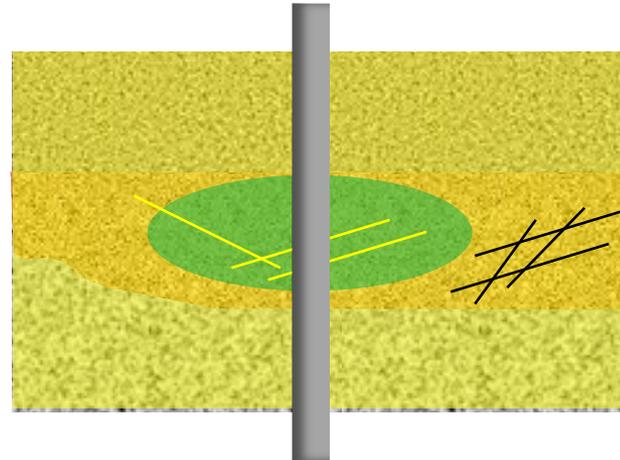
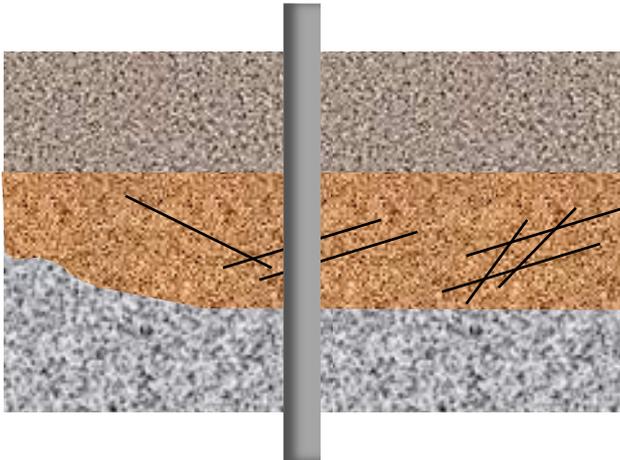
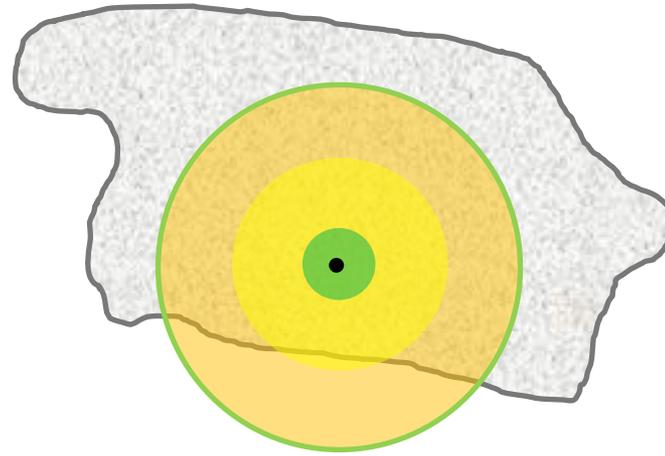
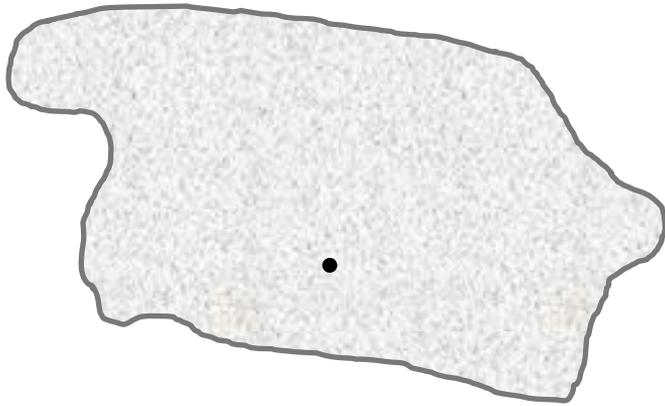


Seismic



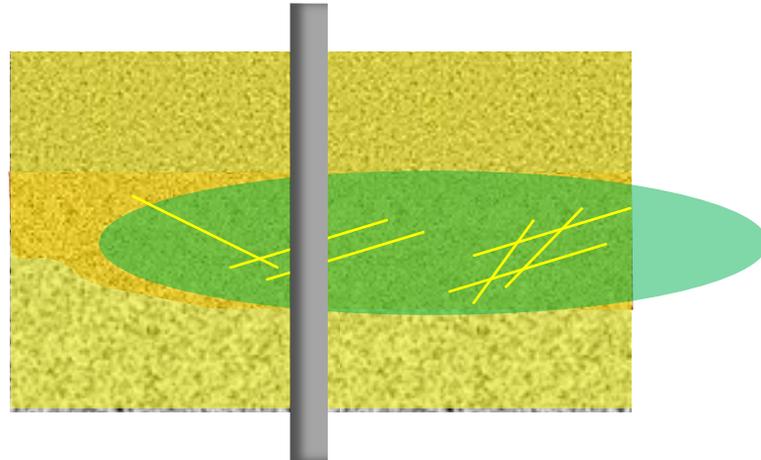
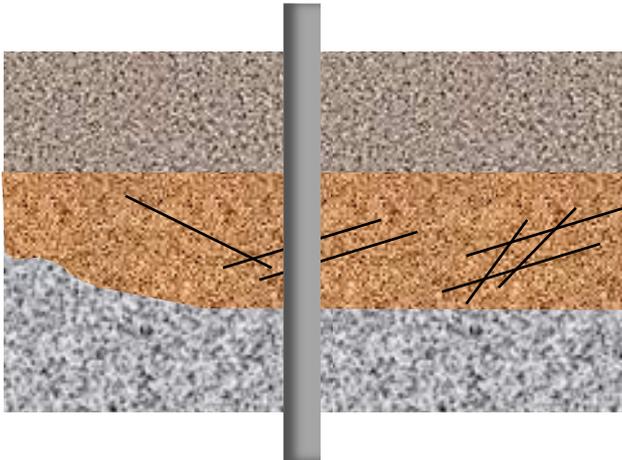
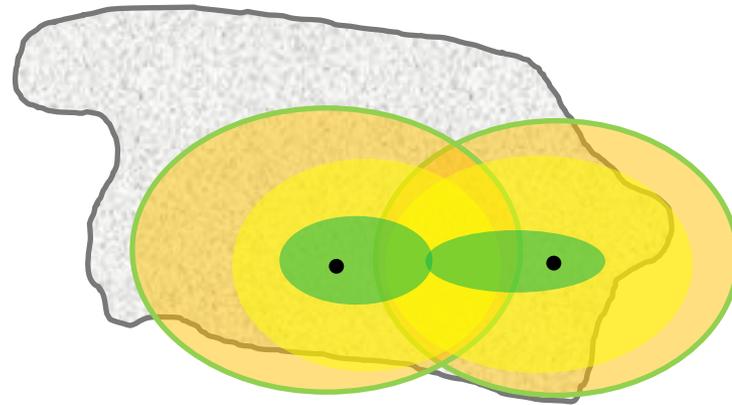
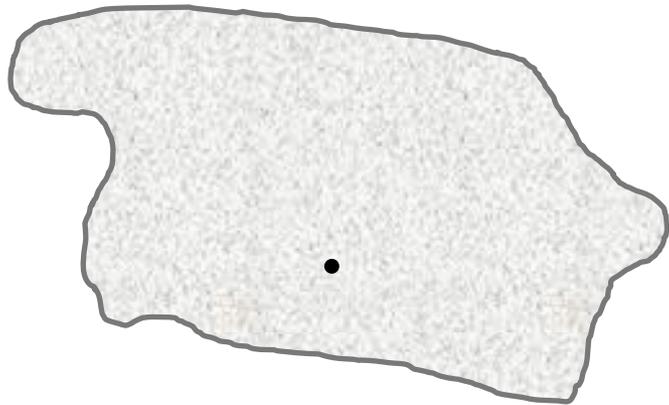
# Resolution of inversion by data source

Single well PTT



# Resolution of inversion by data source

Multiwell interference PTT



# Confidence in property by data source

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## To determine lithology:

- Cores, cuttings, well-logs are most direct, therefore most reliable.
- Velocity is closely related to lithology, seismic is also useful.
- PTT measures permeability (and porosity), less closely related to lithology and so less useful.

## To determine permeability:

- PTT is direct, in-situ measurement – most reliable.
- Measured from cores in labs, or from lithology – less reliable.
- Velocity is weakly related to permeability, chiefly via lithology – seismic is least reliable.

# Confidence in property by data source

To determine lithology:

- Cores, cuttings and logs are most direct, therefore most reliable. **CORES**

- Velocity is closely related to lithology, seismic is also useful. **SEISMIC**

- PTT measures permeability (and porosity), less directly related to lithology and so less useful. **PTT**

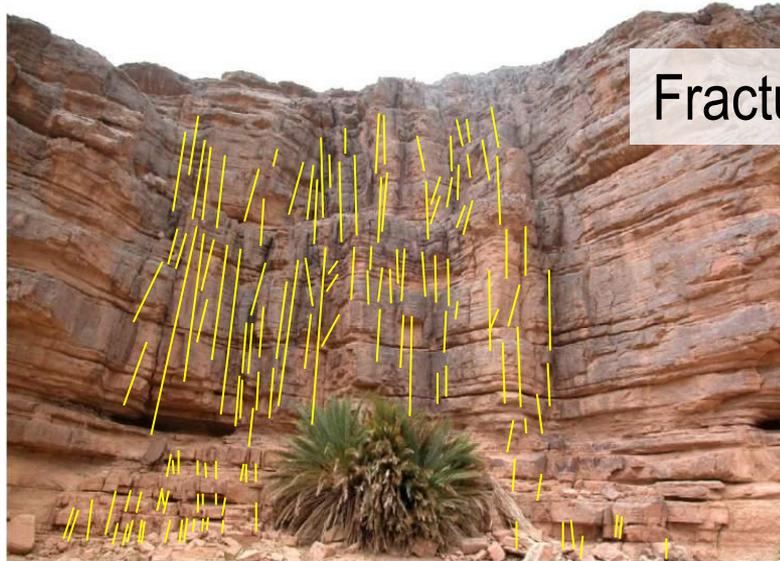
To determine permeability:

- PTT is direct, PTT measurement – most reliable. **PTT**

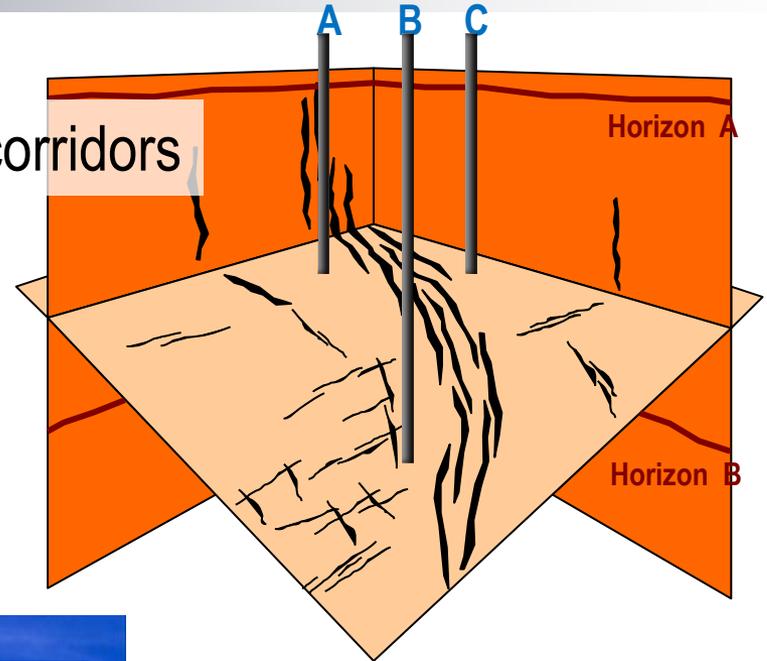
- Measured from cores in labs, or from lithology – less reliable. **CORES**

- Velocity is weakly related to permeability, therefore lithology – seismic is least reliable. **SEISMIC**

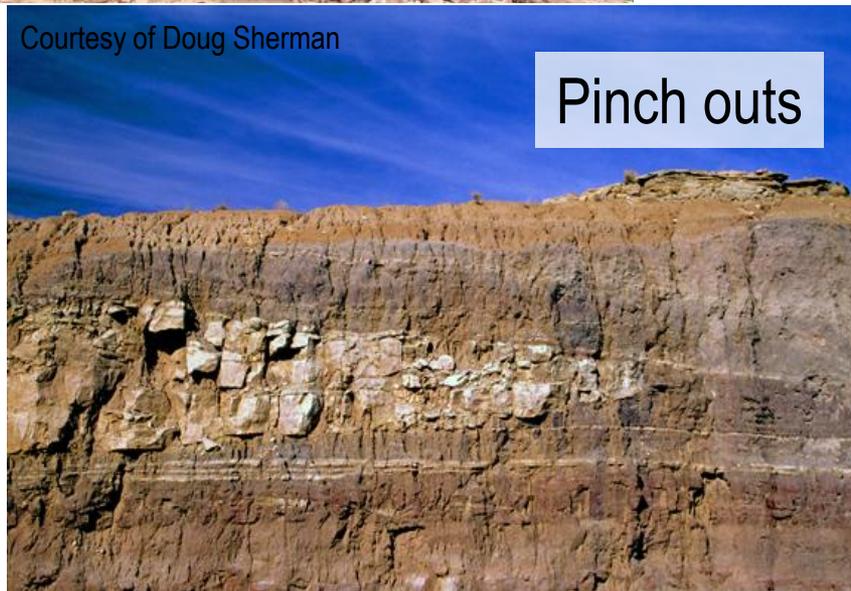
# Reservoir Features



Fracture corridors



Courtesy of Doug Sherman



Pinch outs

Sub-seismic faults  
and lithology  
changes

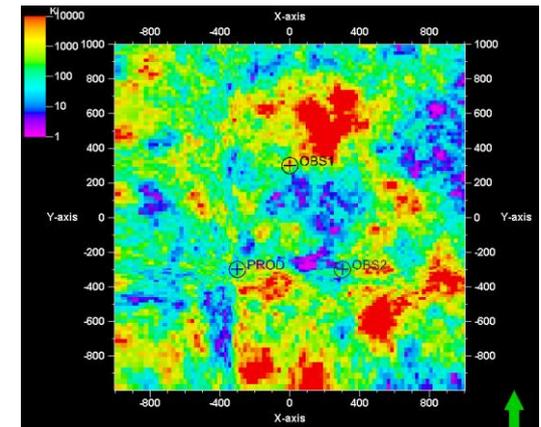
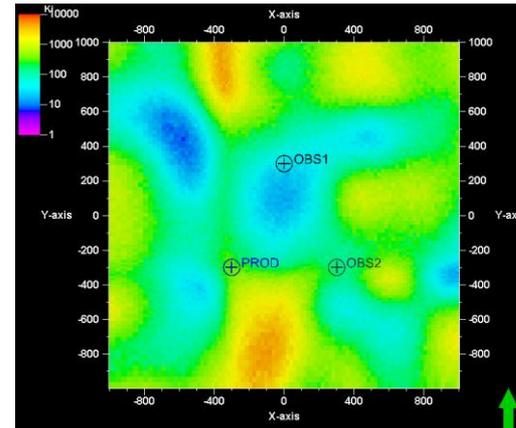
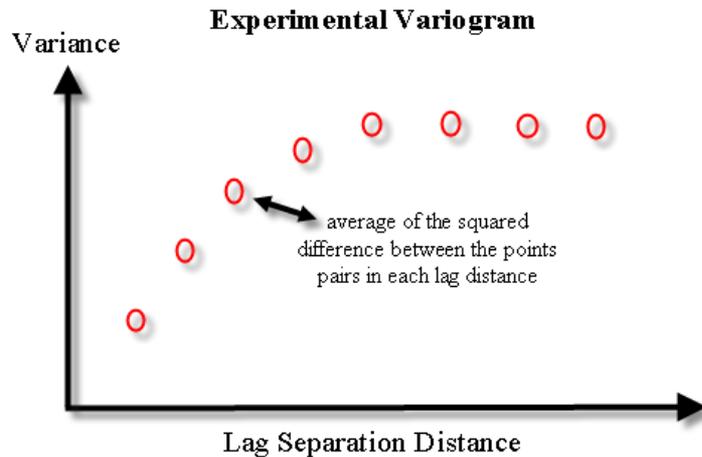
# Bayesian model for PTT inversion

- Never enough data for exact inversion
  - Symmetries – radial or vertical.
  - Upscaling – small scale features can't be detected.

$$\underbrace{\pi[\mathbf{u}|\mathcal{M}]}_{\text{What we know after the test (Posterior)}} \propto \underbrace{\pi_m[\mathcal{M}|\mathbf{u}]}_{\text{How likely is a set of parameters to give the data (Update)}} * \underbrace{\pi_0[\mathbf{u}]}_{\text{What we 'knew' before the test (Prior)}}$$

# Prior model

- In absence of specific geological model or training images, use simple pixel-based Gaussian model.
- Variogram :



# Prior model - approximation

$$\pi(\mathbf{u}) \propto \exp(-\mathbf{u}^T \mathbf{A} \mathbf{u})$$

$$\pi[u(\mathbf{x})] \propto \exp\left(-\int u(\mathbf{x}) \mathcal{L}u(\mathbf{x}) \, d\mathbf{x}\right)$$

$$\mathcal{L}u = a_0 u - a_1 \nabla^2 u + a_2 \nabla^4 u$$

$$\mathcal{L}u = \frac{4\pi\rho^2\sqrt{1-S^2}}{\sigma^2 \cos^{-1}(S)} (\rho^4 \nabla^4 u - 2S\rho^2 \nabla^2 u + u)$$

- Tikhonov regularization
- Variogram approximated with few parameters
  - Can be rewritten in terms of physically relevant parameters – log-permeability variance, correlation length(s)
- Rational approximation in Fourier space
- Replacing  $\mathbf{A}$  with a **sparse** approximant.

# Approaches to inversion

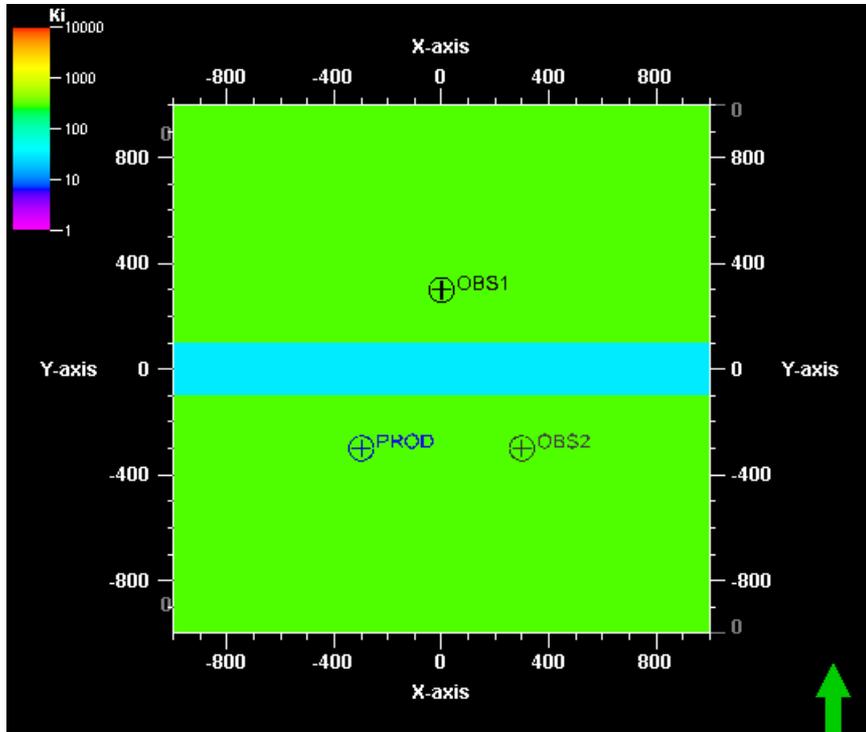
## Derivative-free methods

- Naïve MCMC
  - Curse of dimensionality.
- Filtering methods
  - Data assimilation – efficient simulation.
  - How bad is Gaussian approximation (for EnKF)?
  - Unlike other applications, here geological uncertainty is **not** time-dependent.

## Derivative-based methods

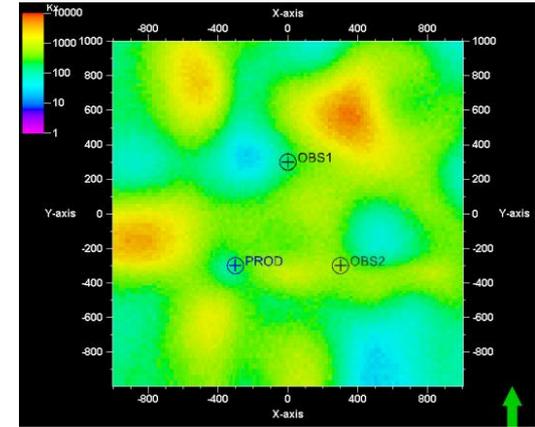
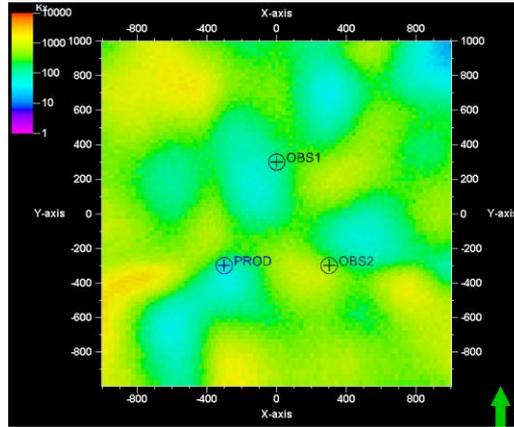
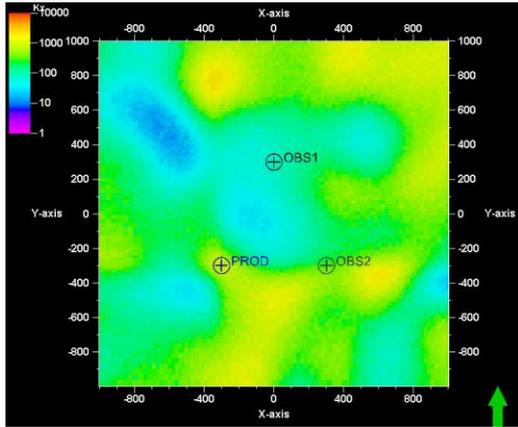
- Can find (locally) most likely parameters for any posterior distribution.
- How do we find the derivatives?
- What about uncertainty?
- Can we produce samples?

# Application of EnKF

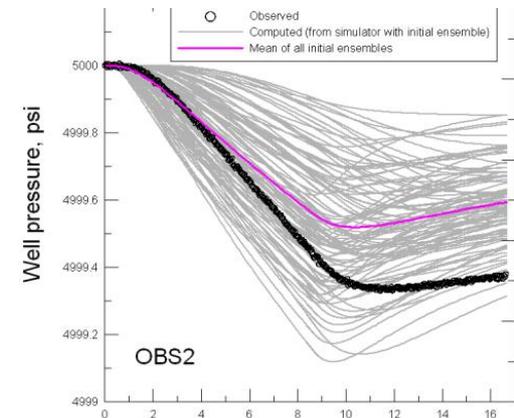
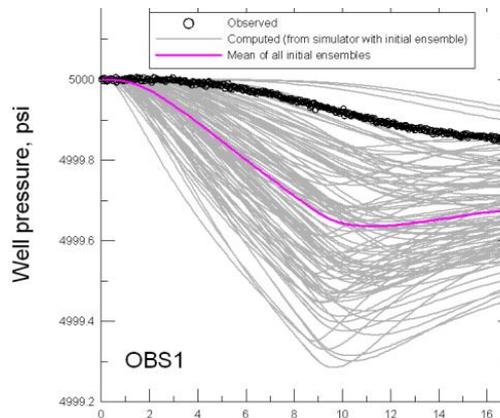
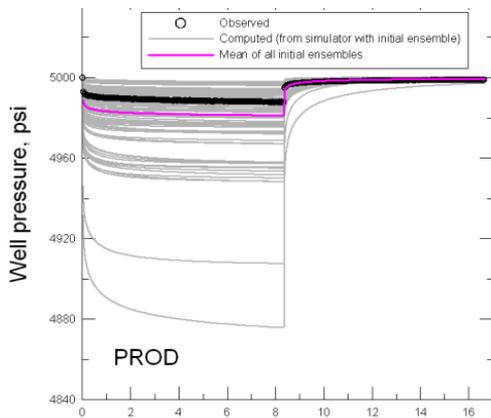


- Truth model
- One producer, two observation wells.
- Band of low permeability separates one of the observation wells from the producer.
- Draw-down (producing) followed by build-up (not-producing).

# Application of EnKF

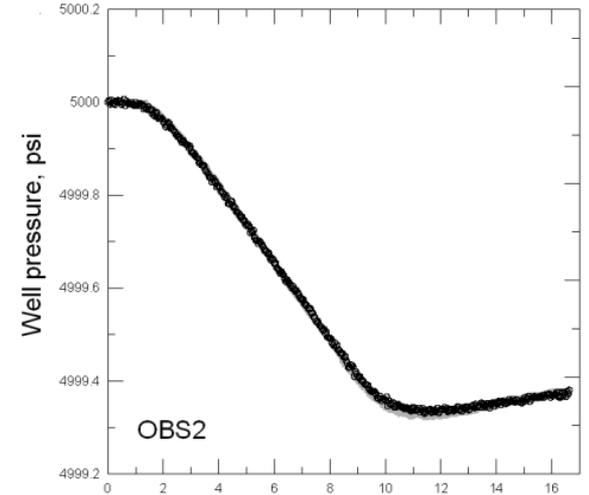
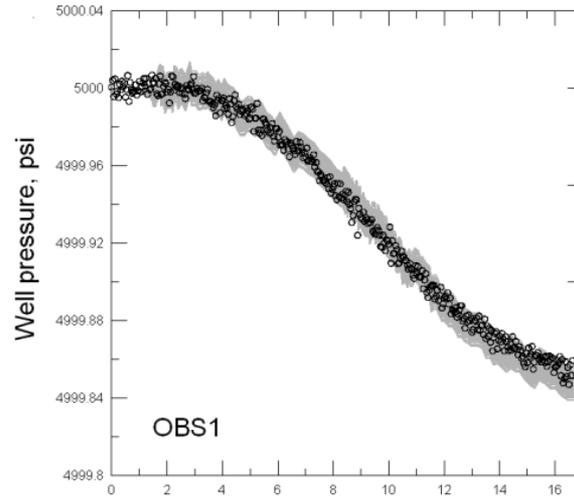
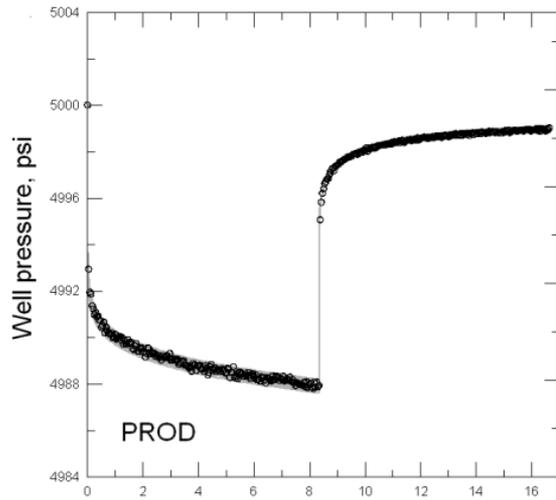


- 3 of 100 ensemble members: Gaussian variogram, range (l) = 500ft.



- Simulated well pressure response for prior ensemble.

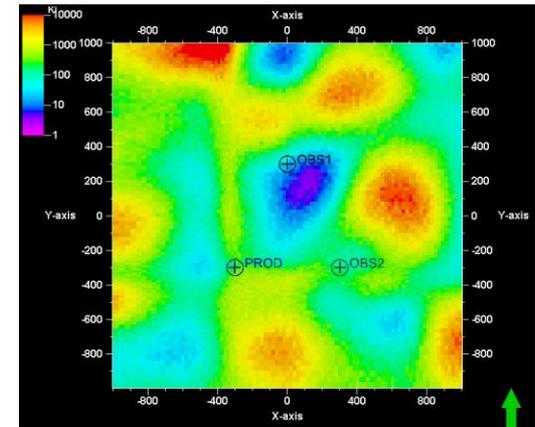
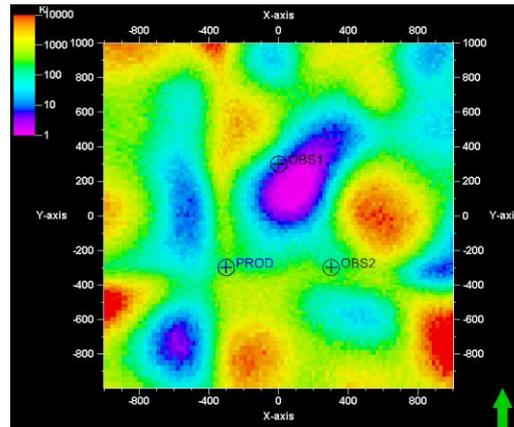
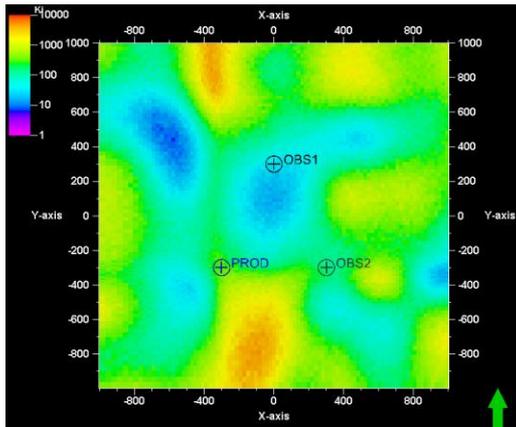
# EnKF



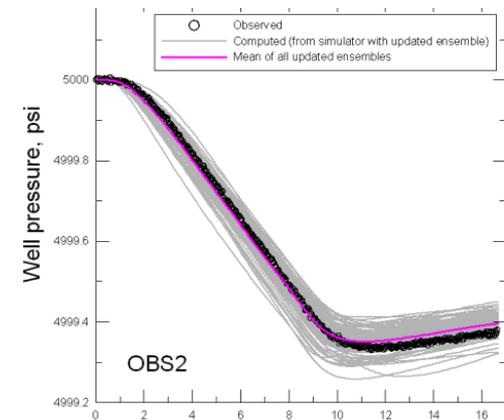
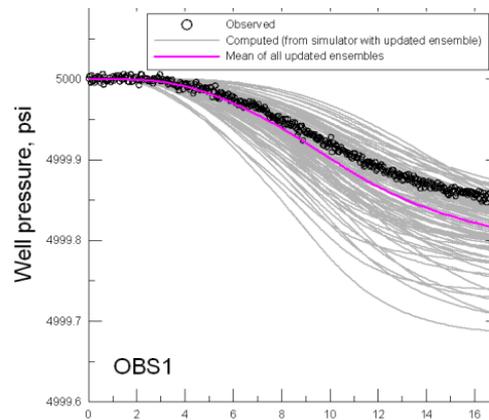
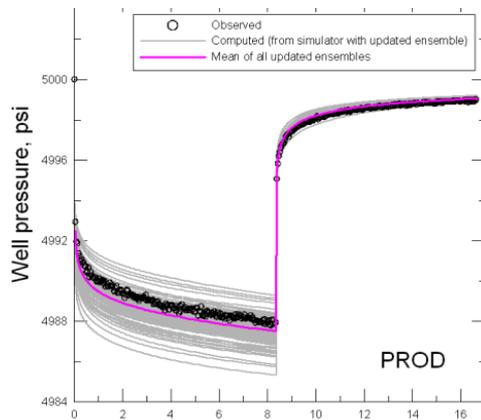
- Exact history match during assimilation.

# EnKF

## Samples from posterior distribution.



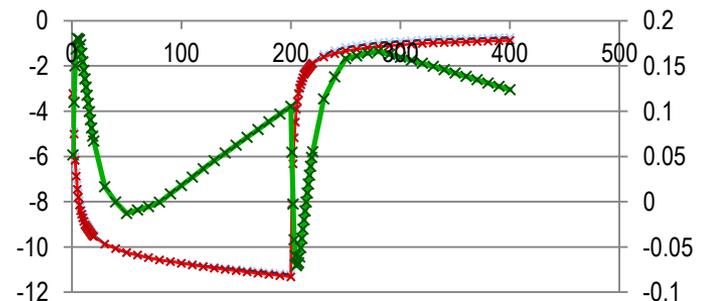
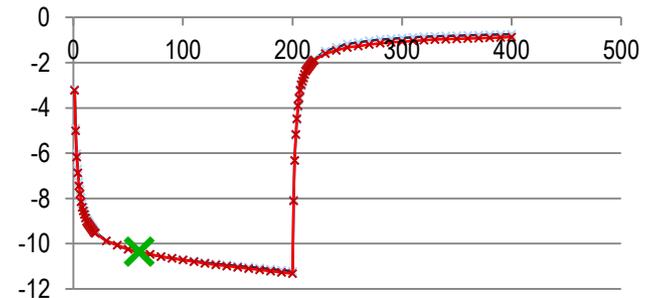
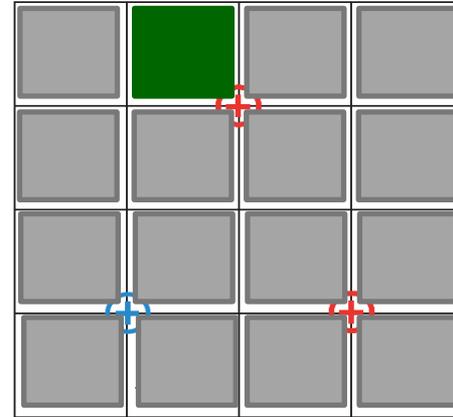
- 3 of 100 updated ensemble members: Gaussian variogram,  $l = 500\text{ft}$ .



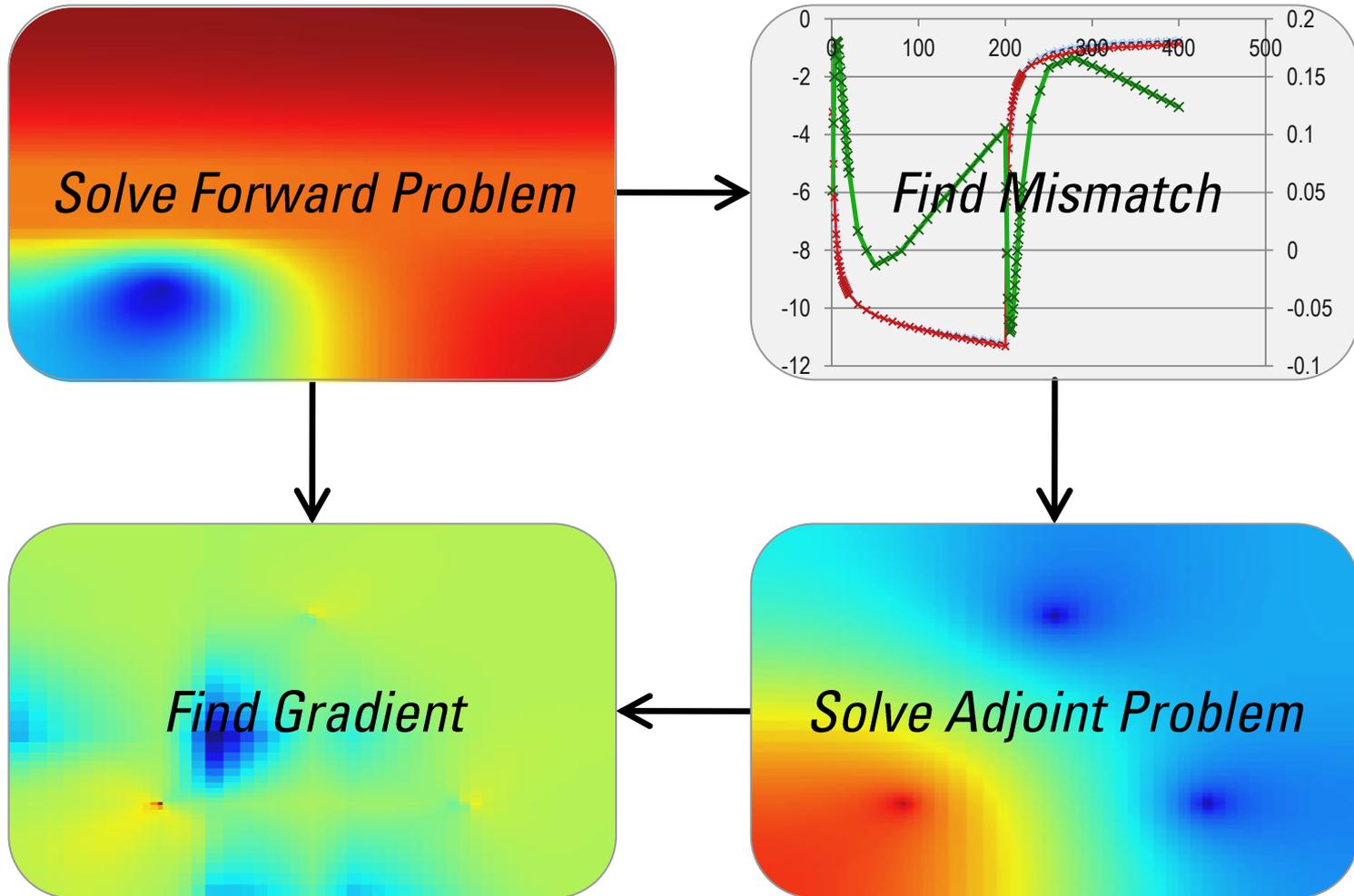
- Simulated well pressure response for updated ensemble & mean.

# Calculating derivatives

- Direct, finite difference
  - Expensive, extra simulation for each parameter.
  - Inaccurate
- Adjoint method for Jacobian
  - Extra simulation for each measurement.
- Adjoint method for gradient
  - One extra simulation, adjoint wrt all measurements at once.
  - Only obtain the gradient – not the Jacobian.



# Adjoint method for gradients



# Separation of prior and likelihood

$$\begin{array}{ccccc} & \nearrow & H[\mathbf{u}] & = & I[\mathbf{u}] & + & R[\mathbf{u}] & \nwarrow \\ & & \text{log-posterior} & & \text{log-likelihood} & & \text{log-prior} & \end{array}$$

- Steepest descent:

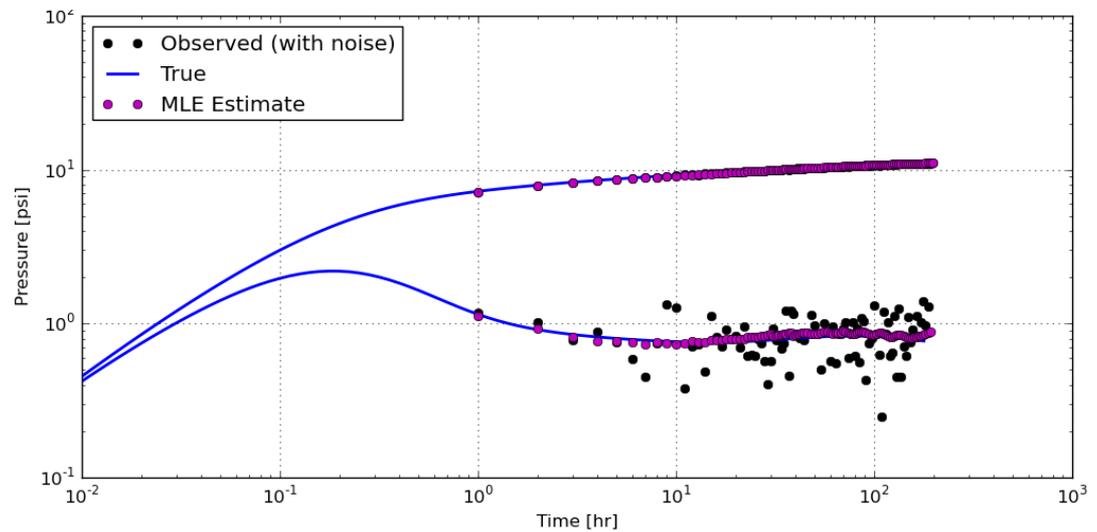
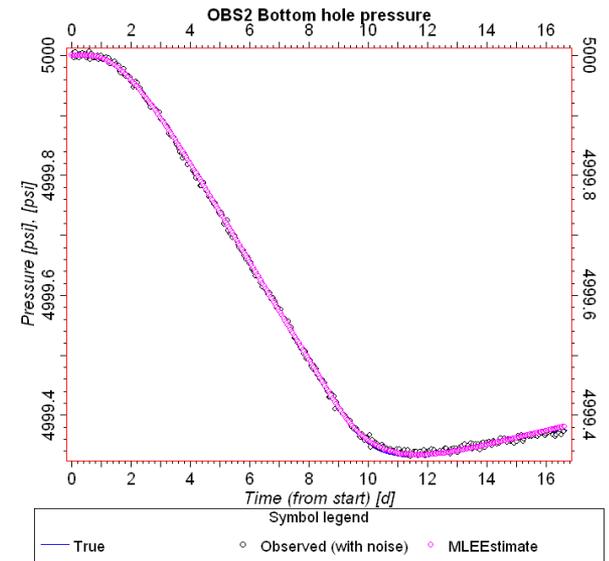
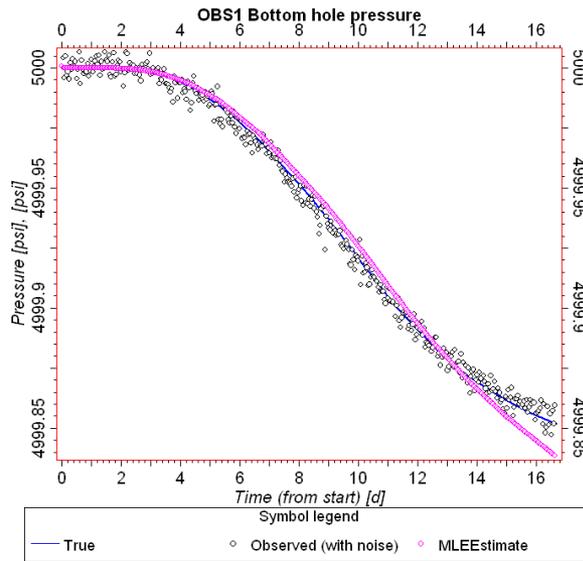
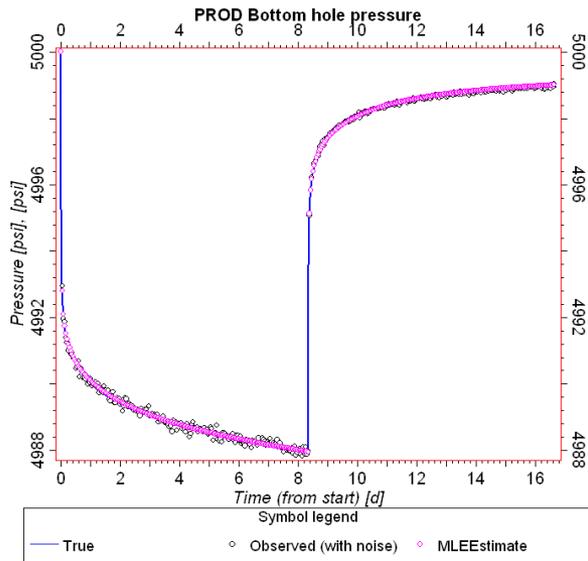
$$\mathbf{u}_{n+1} = \mathbf{u}_n - \alpha \nabla_u H[\mathbf{u}_n] \equiv \frac{\partial \mathbf{u}}{\partial \tau} = -\nabla_u H$$

- **Explicit** Euler scheme – conditional stability analogous to limit on  $\alpha$
- Prior is typically stiff – strong correlation between adjacent cells
- Semi-implicit scheme (separating prior and likelihood):

$$\mathbf{u}_{n+1} = \mathbf{u}_n - \Delta\tau (\nabla_u I[\mathbf{u}_n] + \theta \nabla_u R[\mathbf{u}_{n+1}] + (1 - \theta) \nabla_u R[\mathbf{u}_n])$$

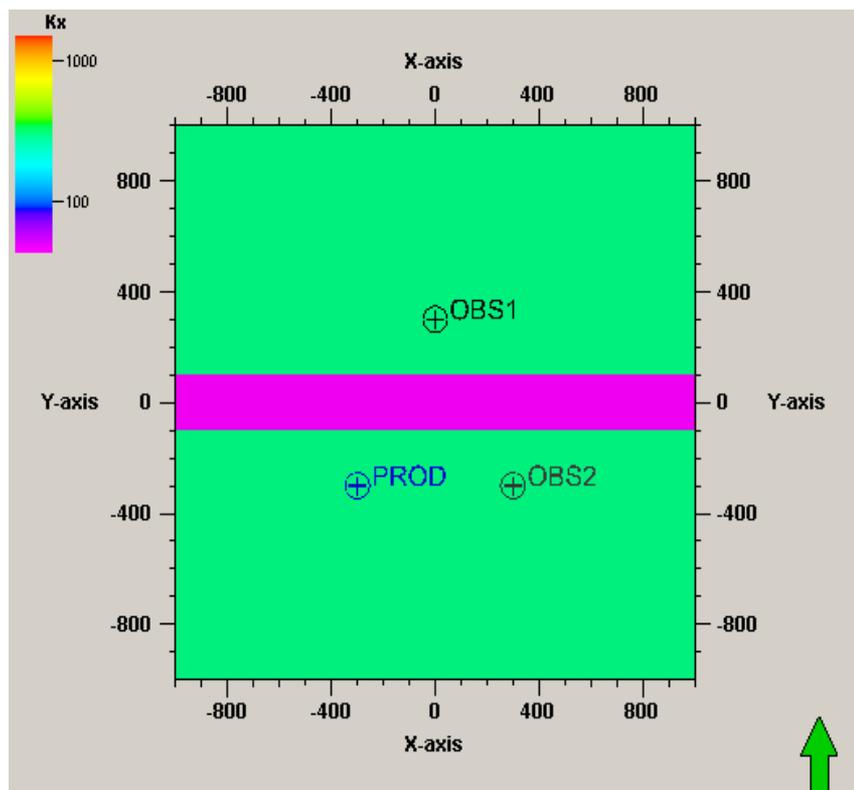
- Sparse representation of prior is useful

# Steepest descent/ Adjoint gradient History match

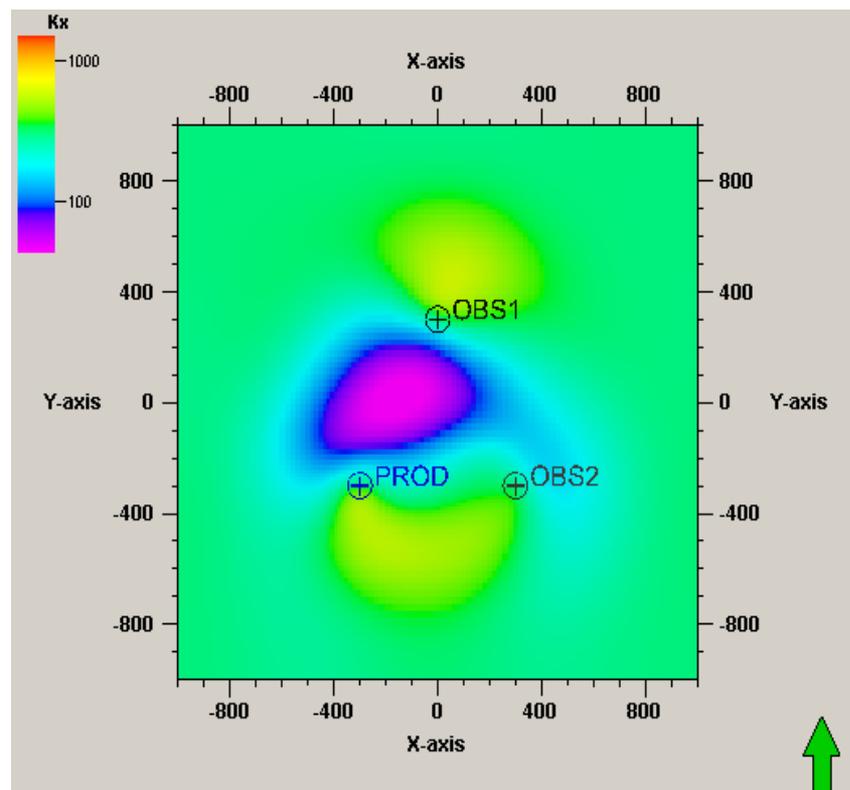


# MAP estimate not generally a good sample

## True permeability field



## Output permeability field



# Uncertainty - Langevin sampling method

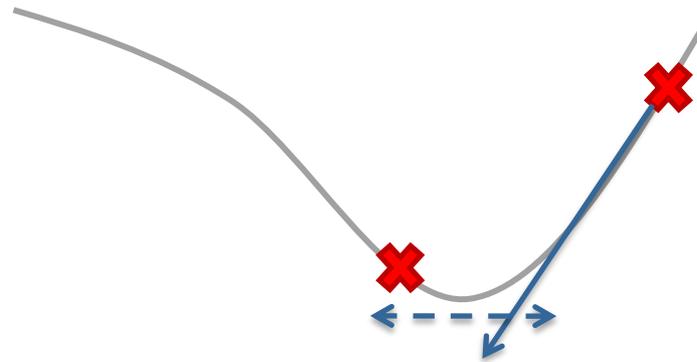
- Steepest descent

$$\frac{\partial u}{\partial \tau} = -\frac{\partial H}{\partial u}$$

- Stochastic differential equation

$$\frac{\partial u}{\partial \tau} = -\frac{\partial H}{\partial u} + \sqrt{2}\eta(x, \tau)$$

- Steepest descent with noise
  - magnitude related to step size.



# Langevin sampling method

- Fokker-Planck – assured convergence in distribution, but not necessarily fast.

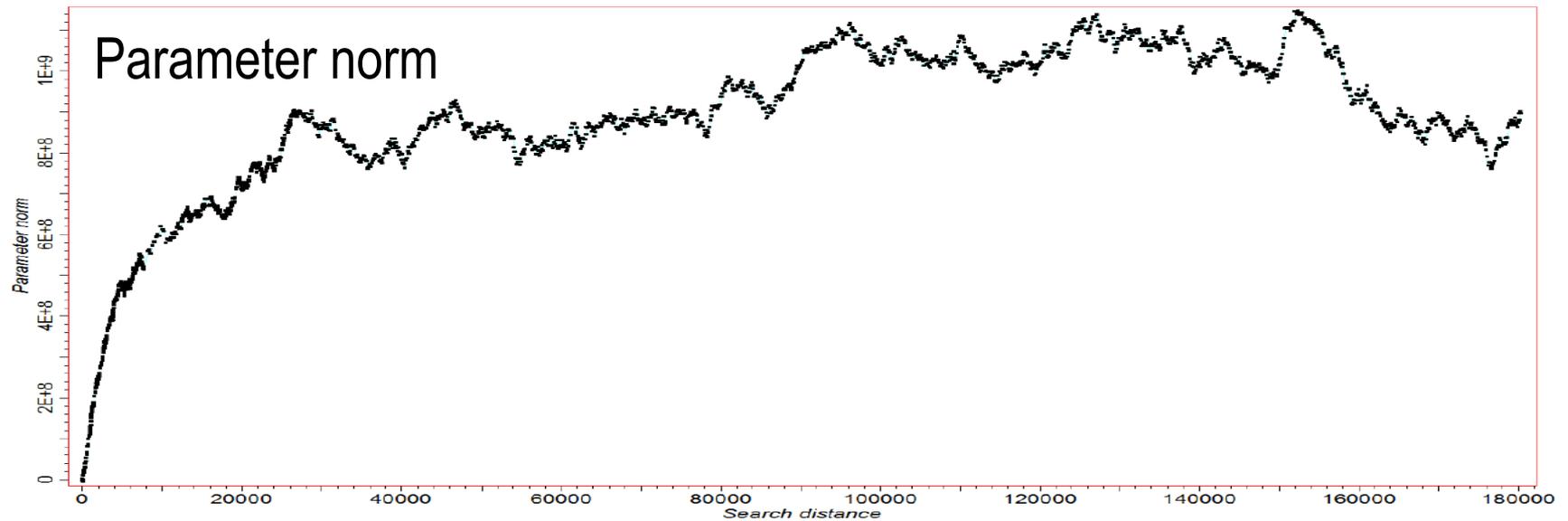
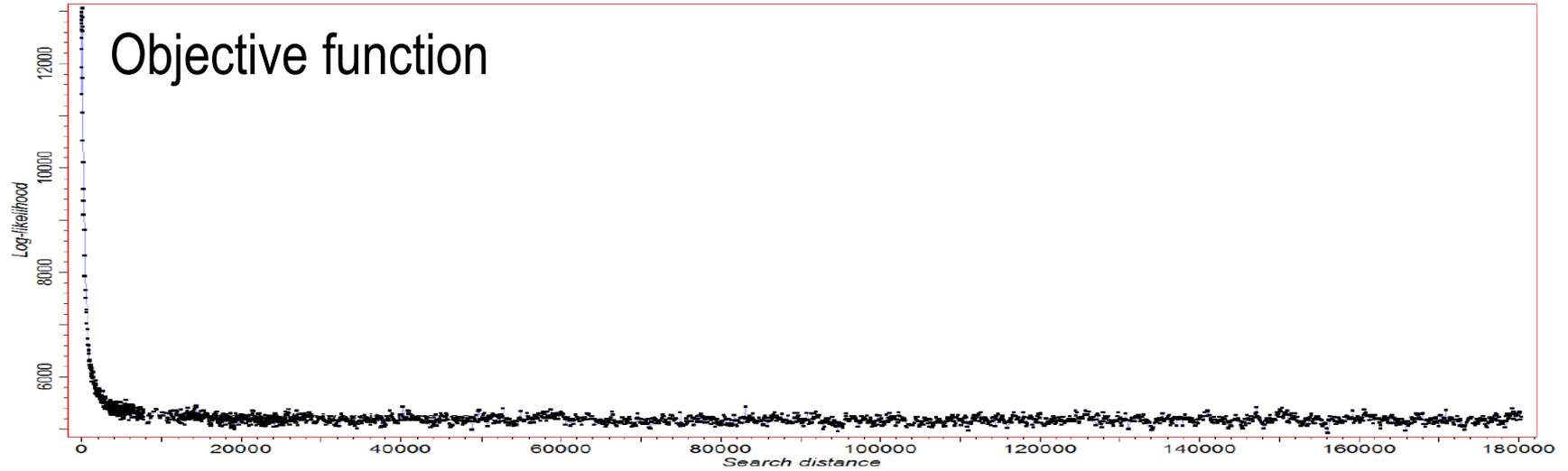
- Need stochastic analogue of ‘line search’

$$p_{\text{accept}} = \frac{\pi[u'_n | \mathcal{M}] Q[u_n; u'_n]}{\pi[u_n | \mathcal{M}] Q[u'_n; u_n]}$$

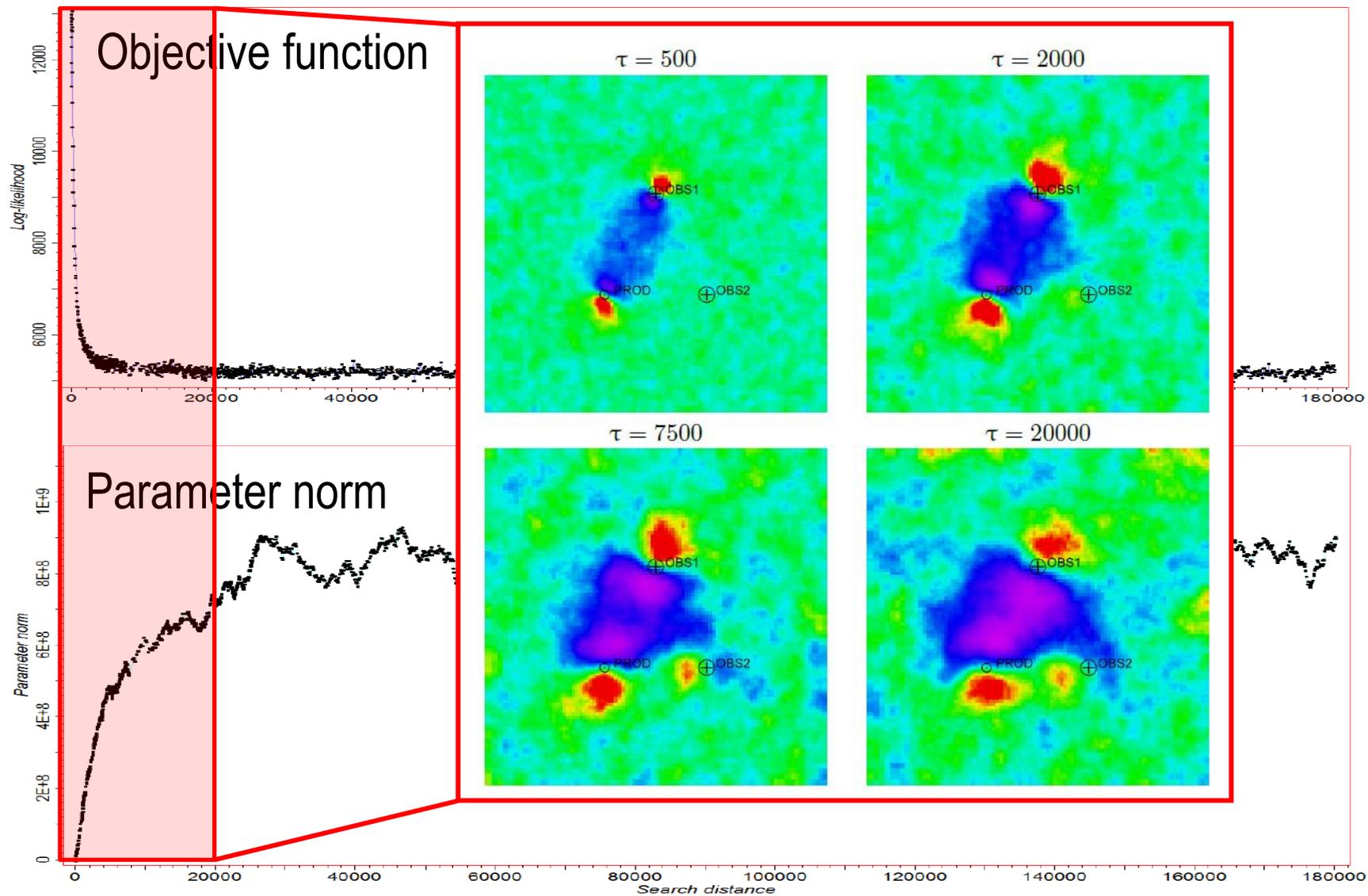
- Construct MCMC using Metropolis-Hastings
- Langevin gives sample distribution.
- Semi-implicit scheme again important for acceptance of large steps.
  - For sampling, accuracy is important too.
  - Need trapezoidal scheme ( $\theta=1/2$ )

$$\mathbf{u}_{n+1} = \mathbf{u}_n - \Delta\tau \left( \nabla_u I[\mathbf{u}_n] + \frac{1}{2} \nabla_u R[\mathbf{u}_{n+1}] + \frac{1}{2} \nabla_u R[\mathbf{u}_n] \right) + \sqrt{2\Delta\tau} \eta(\mathbf{x})$$

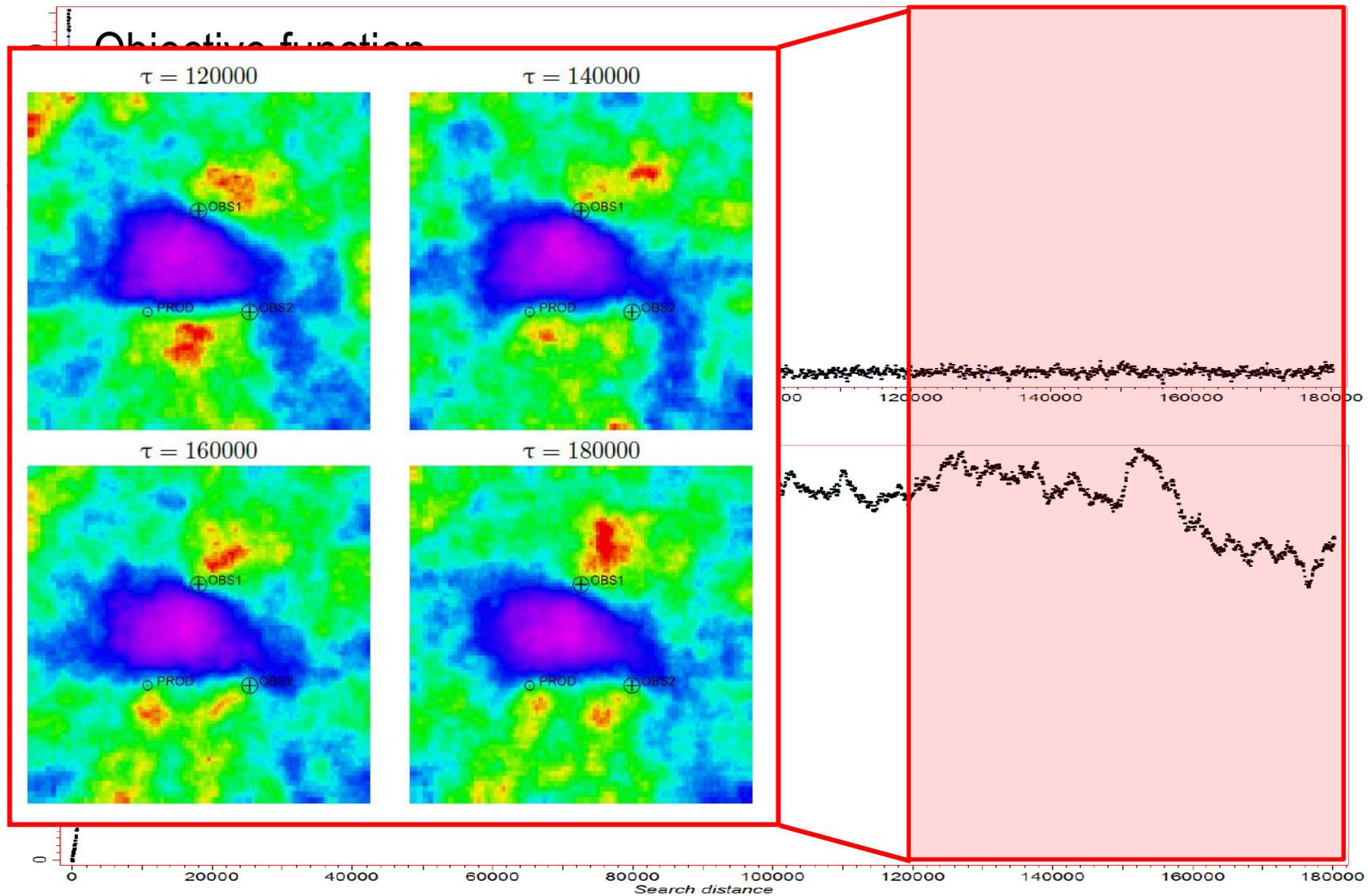
# Langevin sampling



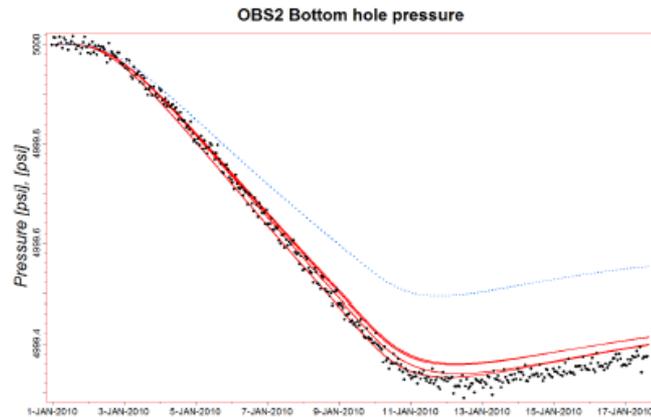
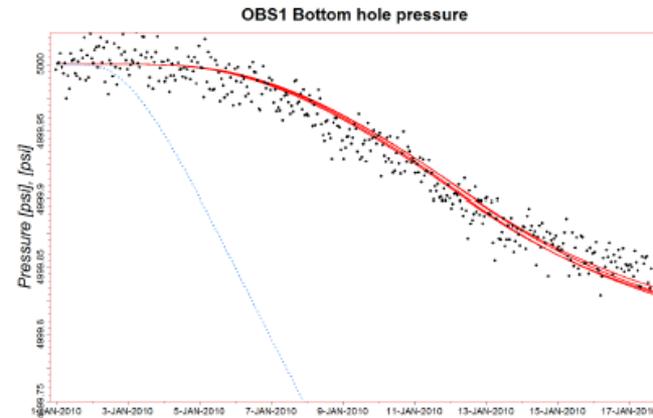
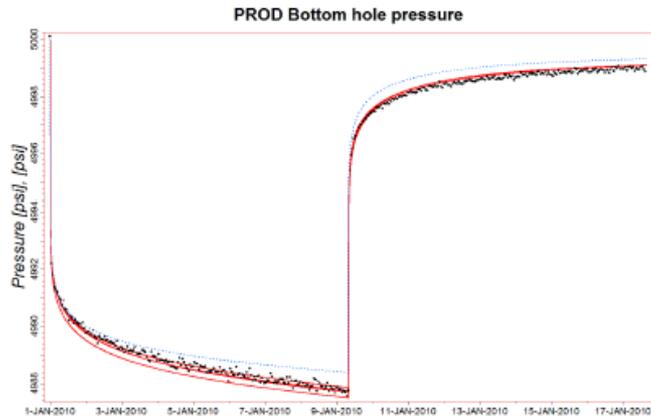
# Langevin sampling



# Langevin sampling



# Langevin sampling



Simulated well responses from samples after convergence.

# Conclusions

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- PTT can be used to identify reservoir features, but significant uncertainty will remain.
- EnKF can give a poor match to PTT data.
- Gradient based methods
  - Can be made numerically inexpensive,
  - Provide good match with data.
  - Quantifying uncertainty still a challenge.
- Langevin method allows sampling but mixing rate is slow
  - Use second derivative information from quasi-Newton to improve implicit treatment of nonlinear term.
  - Optimized step-length selection.
  - Parallel sampling of ensemble.
  - Parameter reduction?