

Including non-linearities Dynamical II A.1

RG:

fluctuations in $\vec{v}_\perp, \delta g \rightarrow \infty$

as $q \rightarrow 0$ ($L \rightarrow \infty$)

(Justifies hydrodynamic approach)

But: Can you neglect NL's?

is $v_\perp \nabla v_\perp$ still "small"?

Solving NL problem:

Exact: hopeless: Different

Fourier modes coupled

$$v(r) \nabla v(r) \rightarrow \sum_p v(q+p) (q-p) v(q-p)$$

Proceed perturbatively in NL^2 's (III A)

Represent Graphically: (Feynmann Graphs)

$$\Rightarrow \alpha = \Psi_\alpha \quad (\Psi_\varphi = \delta\varphi)$$

$$\Psi_{V_{\perp i}} = V_{\perp i}$$

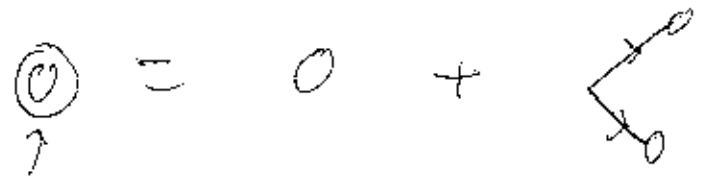
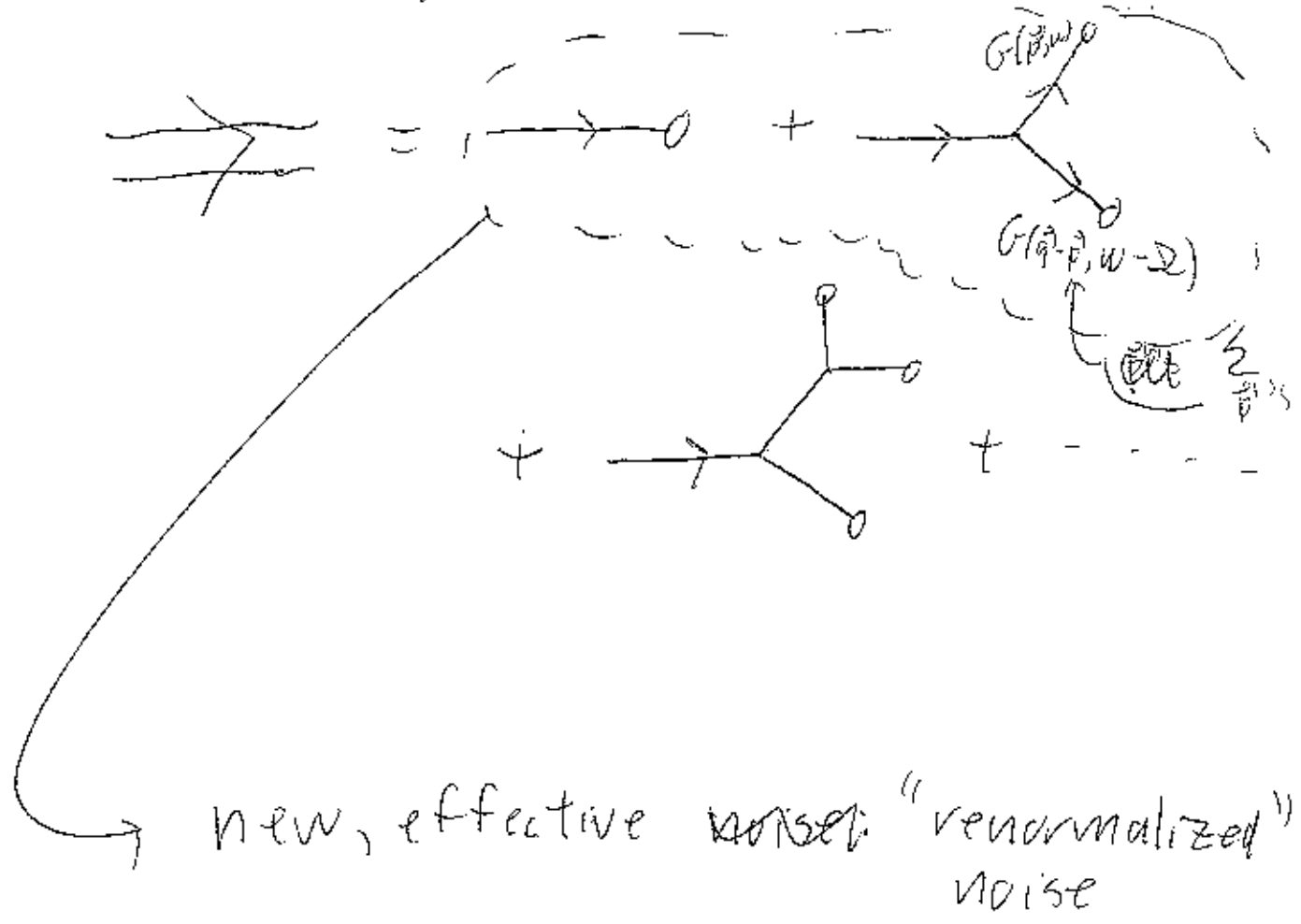
Linear theory:

$$\Psi_\alpha(\vec{q}, \omega) = G_\alpha(\vec{q}, \omega) f_B(\vec{q})$$

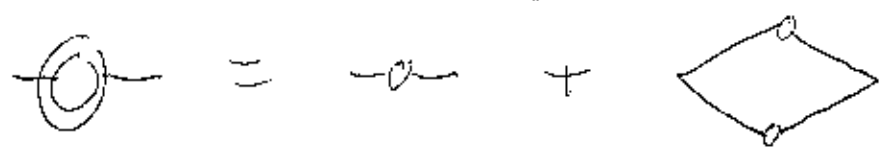
noise

Full equation:

To solve perturbatively, iterate:



⇒ renormalized Δ (noise correlation)



$\Delta_r = \Delta_0 + \text{Graphical correction } (\Delta, D, \Lambda, \dots)$

But: This perturbation theory may
diverge ($\sum_{\vec{p}} \frac{1}{p^2}$) as $\vec{p} \rightarrow 0$, since
fluctuations are big there.

How to deal with this?

Dynamical RG:

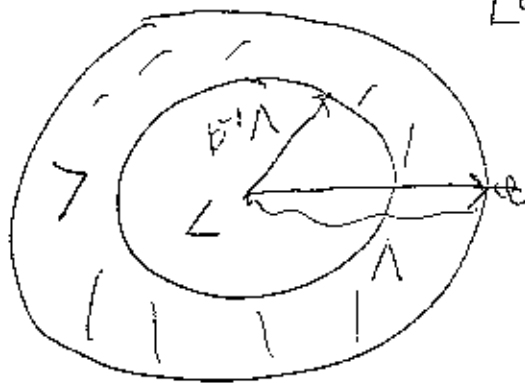
Forster, Nelson, + Stephen
Phys Rev A 16, 732 (1977)

Separate $\Psi(\vec{q}, \omega)$ into
"fast" and "slow" spatial
components:

slow: $\Psi_<(\vec{q}, \omega) = \Psi(\vec{q}, \omega)$ for $|\vec{q}| < b^{-1}\Lambda$

$\Psi_>(\vec{q}, \omega) = \Psi(\vec{q}, \omega)$ " $b^{-1}\Lambda < |\vec{q}| < \Lambda$ "
 $L\vec{q}$

Brillouin
zone

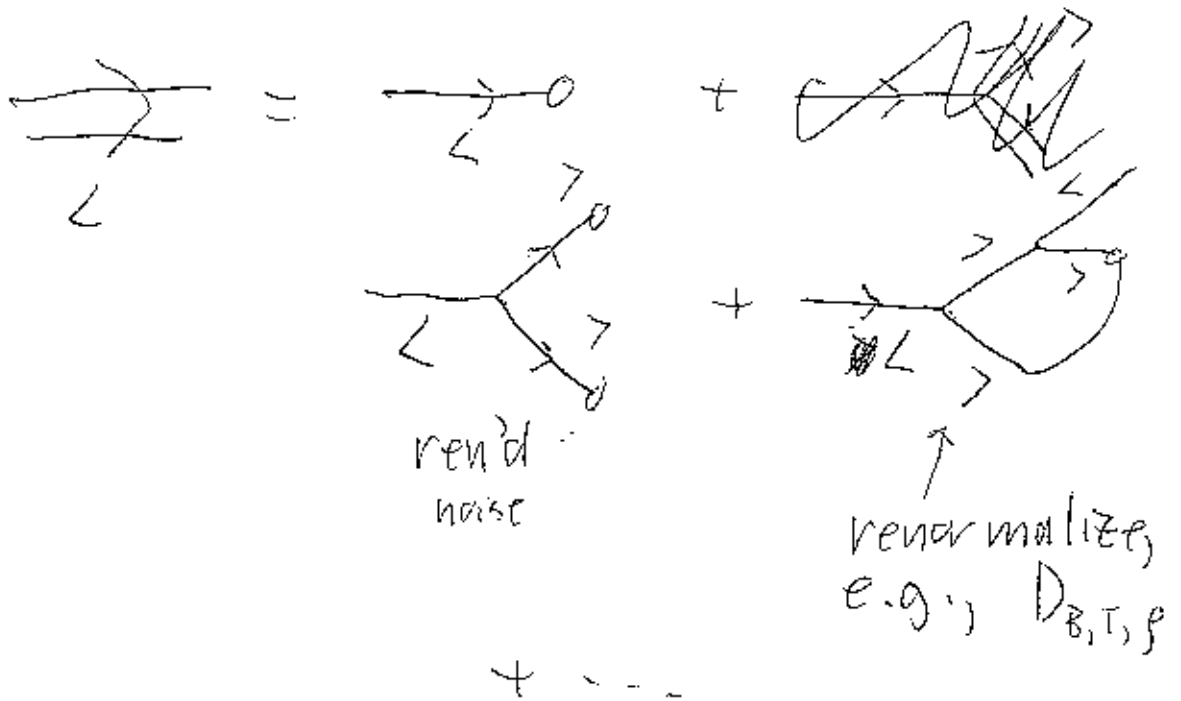


Average out all fields ψ_L in "shell" (□ A)

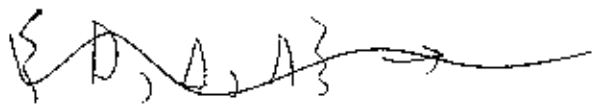
Do this in P.T.

No divergences, because we don't include $\vec{q} \rightarrow 0$ in sums

Left with EOM's for ψ_L 's alone



Unrenormalize



$$\{ D, \Delta, \lambda, \Lambda \} \rightarrow \{ D_I, \Delta_I, \lambda_I, b^{-1} \Lambda \}$$

Non-linearities

repeat.

(III)

Big question: Does problem get easier as we repeat, or harder

I.e., do perturbations \uparrow
or \downarrow as we renormalize?

Easy way to tell:

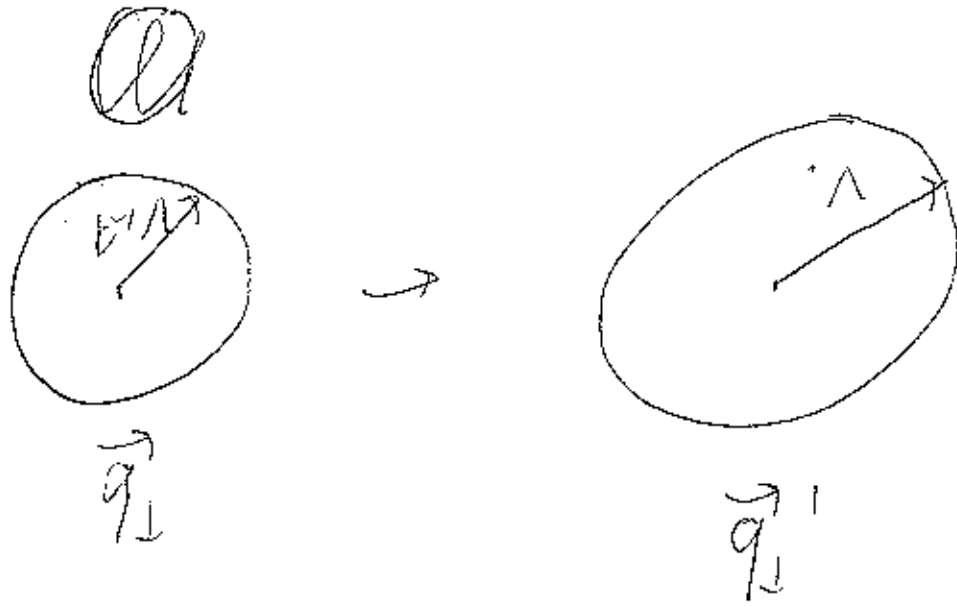
Add extra, rescaling step:

$$\begin{aligned} \vec{q}_\perp &= b^{-1} \vec{q}'_\perp \leftarrow \text{new wavevector coordinates} \\ \Rightarrow \vec{r}_\perp &= b \vec{r}'_\perp \leftarrow \text{" position co-ordinates} \\ \vec{\nabla}_\perp &= b^{-1} \vec{\nabla}'_\perp \leftarrow \text{" gradient} \\ r_{||} &\equiv b^{\zeta} r'_{||} \leftarrow \text{anisotropic scaling} \\ t &\equiv b^{\zeta} t' \end{aligned}$$

$\zeta \equiv$ anisotropy exponent

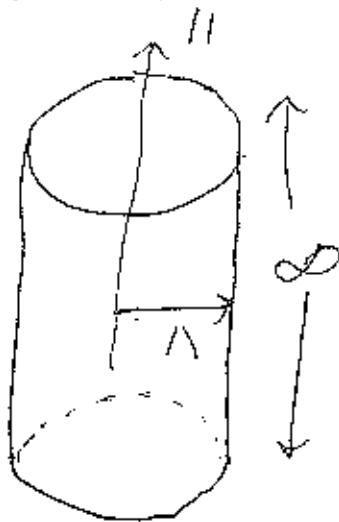
$\zeta \equiv$ dynamical exponent

Technical aside: To make anisotropic



rescaling \vec{q}_\perp restores UV cutoff to Λ

∞ Hypercylindrical BZ:



Also, rescale fields:

$$\psi_d^{(r)} \equiv b^{\lambda_d} \psi_d'(\tilde{r}', t')$$

$$\Rightarrow \cancel{g_d}^R = b^{\lambda_d} g_d^I = b^{\lambda_d} (g_d^0 + \text{Graphs})$$

\uparrow
 parameter
 in EOM
 after
both
 RG steps

Choose λ_d 's to keep
 fluctuation controlling parameters
 fixed ($D_{3, \tau, \varphi}, \Delta$) in our problem)

\Rightarrow On next step of RG, fluctuations
 will be same size
 (Λ also same)

⇒ Perturbations will only grow if
Non-linear coefficients

$$\{ \lambda_1, \lambda_2, \sigma_2, \dots \} \text{ grow}$$

Full EOMs:

$$\partial_t \rho + \bar{\rho}_0 \vec{\nabla}_\perp \cdot \vec{v}_\perp + \lambda_\rho \vec{\nabla}_\perp \cdot (\delta \rho \vec{v}_\perp) + D_\rho \partial_{||}^2 \delta \rho = 0$$

$$\begin{aligned} \partial_t \vec{v}_\perp + \lambda (\vec{v}_\perp \cdot \vec{\nabla}_\perp) \vec{v}_\perp + \lambda_2 \vec{v}_\perp (\vec{\nabla}_\perp \cdot \vec{v}_\perp) + \lambda_1 \partial_{||} \delta \rho \vec{v}_\perp + \lambda_2' \delta \rho \partial_{||} \vec{v}_\perp \\ + \lambda_2 \vec{v}_\perp \partial_{||} \delta \rho \\ = - \vec{\nabla}_\perp \left(\sum_{n=1}^{\infty} \sigma_n (\delta \rho)^n \right) + D_B \vec{\nabla}_\perp (\vec{\nabla}_\perp \cdot \vec{v}_\perp) \\ + D_T \vec{\nabla}_\perp^2 \vec{v}_\perp + D_{||} \partial_{||}^2 \vec{v}_\perp + \vec{f}_\perp \end{aligned}$$

↑
Expansion
of

Do rescaling: $\delta \rho \equiv b^{\chi_\rho} \delta \rho'$ (I'll choose $\chi_\rho = \chi_v = \chi$ since $\delta \rho \sim v_\perp$)
 $\vec{v}_\perp \equiv b^{\chi_v} \vec{v}_\perp'$

$$b^{-z+\chi_\phi} \partial_{t'} d_\phi' + b^{\chi_\phi-1} \vec{\nabla}_\perp' \cdot \vec{v}_\perp' + b^{2\chi_\phi-1} \lambda_\phi \vec{\nabla}_\perp' (d_\phi' \vec{v}_\perp')$$

$$+ b^{\chi_\phi-2\beta} D_\phi \partial_{||}'^2 d_\phi' = 0$$

$$b^{-z+\chi_\phi} \partial_{t'} \vec{v}_\perp' + b^{2\chi_\phi-1} \lambda_1 (\vec{v}_\perp' \cdot \vec{v}_\perp') \vec{v}_\perp' + b^{2\chi_\phi-1} \lambda_2 \vec{v}_\perp' (\vec{v}_\perp' \cdot \vec{v}_\perp')$$

$$+ b^{\chi_\phi-3\gamma} \partial_{||}' \vec{v}_\perp' + b^{2\chi_\phi-3} \gamma' d_\phi' \partial_{||}' \vec{v}_\perp'$$

$$+ b^{2\chi_\phi-3} \vec{v}_\perp' \partial_{||}' d_\phi'$$

$$= - \vec{\nabla}_\perp' \left(\sum_{n=1}^{\infty} b^{n\chi_\phi-1} \epsilon_n (d_\phi')^n \right) + D_\phi b^{\chi_\phi-2} \vec{\nabla}_\perp' (\vec{v}_\perp' \cdot \vec{v}_\perp')$$

$$+ b^{\chi_\phi-2} D_T \vec{\nabla}_\perp'^2 \vec{v}_\perp' + b^{\chi_\phi-3} D_{||} \partial_{||}'^2 \vec{v}_\perp'$$

$$+ \vec{f}_\perp'$$

$$\Rightarrow D_S' = b^{z-2\beta} (D_S + \text{Graphs}(\{\lambda_i, D_i, \Delta\}))$$

$$\Rightarrow D_{B,T}' = b^{z-2} (D_{B,T} + \text{Graphs})$$

$$D_{11}' = b^{z-2\beta} (D_{11} + \text{Graphs})$$

$$\vec{f}_\downarrow' = \vec{f}_\downarrow b^{z-\gamma_0}$$

$$\Rightarrow \langle f_\downarrow'(r_1, t_1) f_\downarrow'(r_2, t_2) \rangle = b^{z(z-\gamma_0)} \Delta \delta^{dr}(r_1 - r_2) \delta(t_1 - t_2)$$

$$\delta^{dr}(\vec{r}_1 - \vec{r}_2) = \delta^{dr}(b^{\alpha}(\vec{r}_1' - \vec{r}_2')) = b^{-(d+1)\alpha} \delta^{dr}(\vec{r}_1' - \vec{r}_2')$$

$$\delta(t_1 - t_2) = \delta(b^z(t_1' - t_2')) = b^{-z} \delta(t_1' - t_2')$$

$$\delta(r_{11} - r_{12}) = \delta(b^3(r_{11}' - r_{12}')) \quad \text{property of } \delta \text{ fn:}$$

$$= b^{-3} \delta(r_{11}' - r_{12}') \quad \delta(kx) = \frac{1}{k} \delta(x)$$

$$\text{So } \langle f' f' \rangle = b^{z(z-\gamma) - d - zH - 3} \Delta \delta^{dr}(r_1' - r_2') \delta(t_1' - t_2')$$

$$\Rightarrow \Delta' = b^{z-2\gamma+dH-3} (\Delta + \text{Graphs})$$

.....

Suppose $\lambda_i, \epsilon_{n>1}$, and γ_1, γ_2 all small initially (before RG)

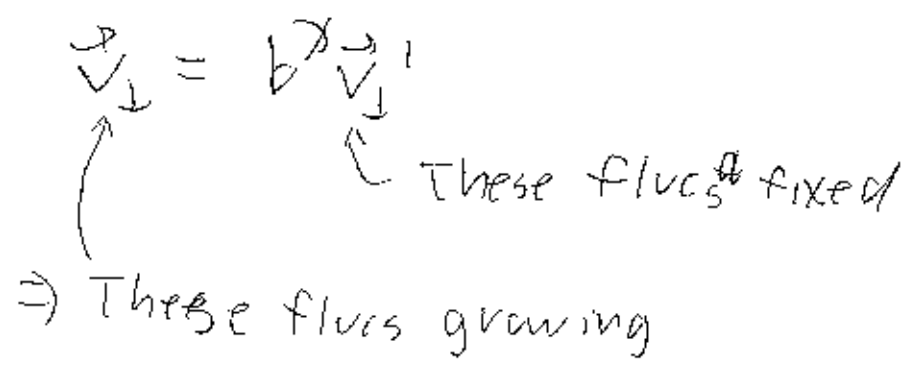
\Rightarrow can neglect graphs (at this point in RG)

\Rightarrow To keep fluxes fixed (keep D_s, Δ fixed) choose

$$\left. \begin{aligned} D_{S,II} \text{ fixed} &\Rightarrow z = 2\beta \\ D_{S,T} \text{ fixed} &\Rightarrow z = 2 \end{aligned} \right\} \Rightarrow \boxed{\beta = 1}$$

$$\Delta \text{ fixed} \Rightarrow z = \frac{2\chi + d}{\chi - 1} \Rightarrow \boxed{\chi = 1 - \frac{d}{2}}$$

Note: $\chi > 0$ for $d < 2$
(Mermin-Wagner)



Now, as we keep running RG, can be continue to neglect graphs?

Since fluxes fixed with this choice of (z, β, χ) , we can

iff λ_i 's, $\sigma_{n>2}$ all $\rightarrow 0$ as $b \uparrow$.

$$\lambda'_{1,2} = b^{\chi+z-1} (\lambda_{1,2} + \text{graphs}) = b^{\phi_1 - \frac{d}{2}} (\lambda_{1,2} + \text{graphs})$$

$$\sigma'_n = b^{(n-1)\chi-1+z} (\sigma_n + \text{graphs}) = b^{\phi_n - \frac{(n-1)d}{2}} (\sigma_n + \text{graphs})$$

\Rightarrow RG eigenvalues:

$$\phi_1 = z - \frac{d}{2} > 0 \text{ if } d < 2z$$

$$\Rightarrow \lambda_{1,2} \text{ grow for } d < 2z$$

$$\phi_n = n\chi - \frac{(n-1)d}{2} > 0 \text{ for } d < \frac{2n\chi}{n-1} = d(n)$$

$$\Rightarrow \text{biggest is } n=2$$

\Rightarrow for $d < 4$, σ_2, λ_i 's grow

upon RG, if initially small

\Rightarrow "relevant"

\Rightarrow can not neglect them
for b big enough

\Rightarrow can not neglect them for
large distance L

$$\gamma^1 = b^{\chi+z-3} (\gamma + G_{\text{graphs}})$$

$$\gamma_2 = b^{\chi+z-3} (\gamma + G_{\text{graphs}})$$

$$\phi_{\gamma^1} = \chi+z-3 = 1 - \frac{d}{2} + 2 - 1 = 2 - \frac{d}{2} \Rightarrow \text{These}$$

also relevant for $d < 4$

Eventually, must do graphs

Aside: What would have happened if we assumed finite range spatio-temporal correlations of f ?

$$\langle f_i(\vec{r}, t) f_j(\vec{r}', t') \rangle = \delta_{ij} g(\vec{r} - \vec{r}', t - t')$$

$$\Rightarrow \langle f_i(\vec{q}, \omega) f_j(-\vec{q}, -\omega) \rangle = \delta_{ij} \int d^d r dt g(\vec{q}, \omega)$$

$$g(\vec{q}, \omega) \equiv \int d^d r dt g(\Delta \vec{r}, \Delta t) e^{i(\vec{q} \cdot \vec{r} - \omega t)}$$

If $g(\Delta \vec{r}, \Delta t)$ decays sufficiently rapidly as $\Delta \vec{r}, \Delta t \rightarrow \infty$,

$$g(\vec{q} \rightarrow \vec{0}, \omega \rightarrow 0) \rightarrow \int d^d r dt g(\Delta \vec{r}, \Delta t) \text{ finite} \equiv \Delta$$

$$\Rightarrow \langle f_i(\vec{q}, \omega) f_j(-\vec{q}, -\omega) \rangle \xrightarrow{\vec{q}, \omega \rightarrow 0} \Delta$$

\Rightarrow small \vec{q}, ω behavior exactly the same

$$\lambda'_9 = b^{\chi+2-1} \lambda_9 = b^{2-\frac{d}{2}} \lambda_9$$

$\Rightarrow \lambda_9$ relevant for $d < 2$

$\Rightarrow \lambda_{1,2}, \epsilon_2, \lambda_9, \delta'_1, \delta_2$ all relevant
NL's for $d < 4$.

How to deal with them?

Do graphs.

Example: Subset of graphs for λ_2
(only those linear in λ_2 , drop δ 's)

14 graphs, 200+ pages of algebra,
3 months of JF's life

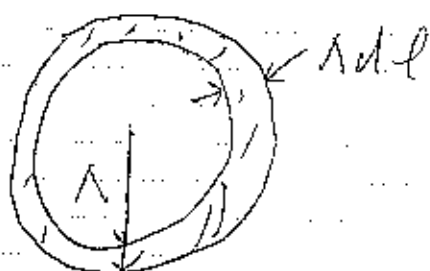
Find $\left. \frac{\delta \lambda_2}{\delta \text{Graph}} \right| = 0$

Not very useful anyway, because only valid near $d=4$.

Why?

Easy way to see: Turn ~~into diff. eqn~~ recursion relation into differential equation:

$$b = 1 + d\ell, \quad d\ell \ll 1$$



\Rightarrow Graphs λ & $d\ell$ as well

\Rightarrow ~~$\frac{d\lambda}{d\ell} \approx \lambda$~~

~~$\lambda_1 = 1 + \frac{d\ell}{2}(4-d)$~~

$\lambda_1 \approx 1 + \left(\frac{4-d}{2}\right)d\ell \equiv 1 + \frac{\epsilon}{2}d\ell, \quad \epsilon \equiv 4-d$

$$EG \Rightarrow \lambda_1' \equiv (1 + \frac{\epsilon}{2} dl) (\lambda_1 + f(\lambda) dl)$$

$$= \lambda_1 + dl [\frac{\epsilon}{2} \lambda_1 + f]$$

$$\Rightarrow \frac{\lambda_1' - \lambda_1}{dl} = (\frac{\epsilon}{2} \lambda_1 + f)$$

$$\Rightarrow \frac{d\lambda_1}{dl} = \frac{\epsilon}{2} \lambda_1 + f$$

Likewise for β_2, δ_0 's, etc.

Since we can only calculate f in P.T., must hope that λ 's etc stay small. \Rightarrow hope $f < 0$.

Typically, ~~ϵ~~

$$f = -C \lambda^2 \text{ (lowest order in } \lambda)$$



$$\Rightarrow \frac{d\lambda_1}{d\epsilon} = \frac{\epsilon}{2} \lambda_1 - C \lambda_1^2 \Rightarrow \lambda_1 = \frac{\epsilon}{2C} : \text{small if } \epsilon \ll C$$

Basis of ϵ -expansion

Only valid near $d=4$.

Often works well in $d=3$, but ~~not~~

need to go to $O(\epsilon^2)$ to decide delicate competition between λ, γ , etc.

Nothing one can do near $d=2$.

However: Let's assume that

Graphs are such that $\gamma's \rightarrow 0$.

\Rightarrow In $d=2$, only NL's left are

$$\lambda_9, \lambda_{1,2}, \beta_2$$

Look at $\lambda_{1,2}$ in $d=2$



$$\langle \vec{v} \rangle = v_0 \hat{y}$$

$$\vec{v}_1 = v_1 \hat{x} = \text{Only one component}$$

$$\begin{aligned} \Rightarrow (\vec{v}_1 \cdot \vec{v}_1) \vec{v}_1 &= \hat{x} v_1 \partial_x v_1 \\ &= \frac{1}{2} \hat{x} \partial_x (v_1^2) \end{aligned}$$

$$\begin{aligned} \vec{v}_1 (\vec{v}_1 \cdot \vec{v}_1) &= \hat{x} v_1 \partial_x v_1 \\ &= \frac{1}{2} \hat{x} \partial_x (v_1^2) : \text{Same!} \end{aligned}$$

Both λ_1 and λ_2 terms are the same in $d=2$!

Furthermore, both are total
x ~~derivatives~~ (i.e., \perp) derivatives

\Rightarrow 1) Renormalization of noise
correlations $\Delta = O(q^2) \ll \Delta_0$

\Rightarrow Neglect
(No noise renorm)

$$\Rightarrow \Delta' = b^{z-2\chi-d} \Delta$$

exact in $d=2$

\Rightarrow To fix flux, must choose

~~$$z = 2\chi + d = 2\chi + 2 \quad (1)$$~~

$$z = 2\chi + d + 3 - 1 = 2\chi + 3 + 1 \quad (1)$$

since
 $d=2$

2) ~~D_{11} graphs~~
No D_{11} graphs

$D_{11} \partial_{11}^2, \lambda's \propto d_{\perp}$

$\Rightarrow D_{11}' = b^{z-2\beta} D_{11}$ Exactly

$\Rightarrow \boxed{z=2\beta} (2)$

3) If $\lambda_{\beta} = \lambda_1 + \lambda_2 \equiv \lambda$, EOM's have

exact Pseudo-Galilean invariance:

$\vec{V}_{\perp}(\vec{r}, t) \rightarrow \vec{V}_{\perp}(\vec{r} - \lambda \vec{v}_{\perp}^0 t, t) + \vec{v}_{\perp}^0$

$d_{\beta}(\vec{r}, t) \rightarrow d_{\beta}(\vec{r} - \lambda \vec{v}_{\perp}^0 t, t)$

Must be preserved with same value of λ

\Rightarrow No graphs for λ in this case.

Furthermore, we know there are no graphs for λ_g (~~conservation~~ # conservation is exact)

$\Rightarrow \sigma_{\lambda_g} = 0$ always

\Rightarrow if bare $\lambda_{\text{bare}} < \lambda_g$, renormalized $\lambda_{\text{ren}}^{\text{ren}} \lambda_{\text{ren}}^{\text{ren}}$ will always be $< \lambda_g$. (if equal, λ_{bare} gets no graphs \downarrow has same R.P. as $\lambda_g \Rightarrow$ remains equal)

\Rightarrow If F.P. exists, since same λ (λ or λ_g) must be $\neq 0$ at it, λ_g must be non-zero at it.

RR for λ_f

$$\lambda_f' = b^{z+\lambda-1} \lambda_f$$

\Rightarrow To get FP, must have

$$\boxed{z + \lambda = 1} \quad (3)$$

3 eqns (1, 2, 3) for 3 unknowns
(z, λ, β).

Solve: (2), (3) into (1) $\Rightarrow z = 2(1-z) + 1 + \frac{z}{2}$

$$\Rightarrow \frac{5}{2}z = 3 \Rightarrow \boxed{z = \frac{6}{5}}$$

$$\Rightarrow \beta = \frac{3}{5}, \quad \lambda = 1 - z = -\frac{1}{5} < 0 \Rightarrow \text{LRO!}$$

If you believe this works in all d ,

$$\frac{5}{2}z = d - 1 + 2 = d + 1 \Rightarrow z = \frac{z(d+1)}{5} = \begin{cases} 2, & d=4 \\ 6/5, & d=2 \end{cases}$$

$$\beta = \frac{d+1}{5} = \begin{cases} 1, & d=4 \\ 3/5, & d=2 \end{cases}$$

$$\lambda = \frac{3-2d}{5} = \begin{cases} -1, & d=4 \quad (=1-\frac{d}{2}) \\ -1/5, & d=2 \end{cases}$$

References: J. Taner + Y. Tu,

Phys. Rev. E 58, 4828 (1998)

J. T., ~~and~~ Y. Tu, and S. Ramaswamy

Ann. Phys. 318, 170 (2005)

Background on hydrodynamics:

D. Forster: "Hydrodynamic Fluctuations,
Broken Symmetry, and
Correlation Functions"

Dynamical RG:

D. Forster, DR Nelson, + M. J. Stephen,

Phys. Rev. A 16, 732 (1977)