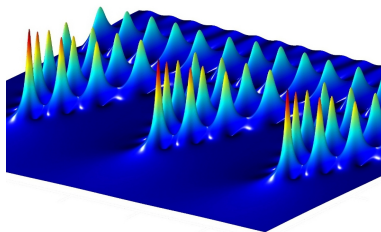
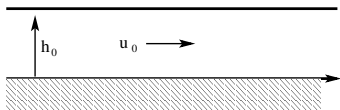


Modulation and water waves – Part 1

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Modulation of uniform flows and KdV



$$Q = h_0 u_0 \quad (\text{mass flux})$$

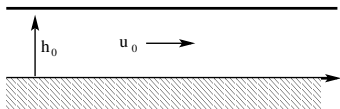
$$R = gh_0 + \frac{1}{2} u_0^2 \quad (\text{total head, Bernoulli energy}).$$

Modulate the uniform flow

$$u = u_0 + \varepsilon q(X, T, \varepsilon), \quad X = \varepsilon x, \quad T = \varepsilon t \quad (\text{SWEs})$$

$$u = u_0 + \varepsilon^2 q(X, T, \varepsilon), \quad X = \varepsilon x, \quad T = \varepsilon^3 t \quad (\text{KdV}).$$

Modulation of uniform flows and KdV



$$Q = h_0 u_0 \quad (\text{mass flux})$$

$$R = gh_0 + \frac{1}{2}u_0^2 \quad (\text{total head, Bernoulli energy}).$$

The flow is **critical** when

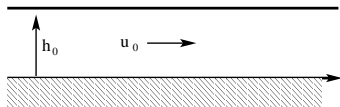
$$\left. \frac{\partial Q}{\partial u_0} \right|_{R \text{ fixed}} = 0.$$

Computing,

$$Q|_{R \text{ fixed}} = h_0 u_0 = \frac{u_0}{g} \left(R - \frac{1}{2}u_0^2 \right).$$

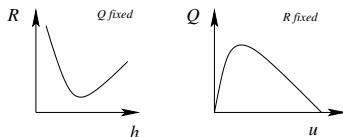
Differentiate with respect to u_0 .

Modulation of uniform flows and KdV



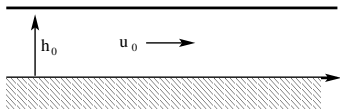
Computing,

$$\left. \frac{\partial Q}{\partial u_0} \right|_{R \text{ fixed}} = \frac{1}{g} \left(R - \frac{3}{2} u_0^2 \right) = \frac{1}{g} \left(g h_0 - u_0^2 \right).$$



What does second derivative $\left. \frac{\partial^2 Q}{\partial u_0^2} \right|_{R \text{ fixed}}$ at the maximum mean?

Modulation of uniform flows and KdV



Modulate the uniform flow:

$$u = u_0 + \varepsilon^2 q(X, T, \varepsilon), \quad X = \varepsilon x, \quad T = \varepsilon^3 t.$$

Claim: q satisfies the KdV equation with

$$2\mathcal{M}_u \frac{\partial q}{\partial T} + \left. \frac{\partial^2 Q}{\partial u_0^2} \right|_{R \text{ fixed}} q \frac{\partial q}{\partial X} + \mathcal{K} \frac{\partial^3 q}{\partial X^3} = 0.$$

Modulation of the mass CLAW for the full water wave problem

$$M_t + Q_x = 0,$$

where \mathcal{M} is M evaluated on the uniform flow.

Symmetry, modulation, and KdV

- basic state: (h_0, u_0)
- conservation laws: $Q_x = 0$ and $R_x = 0$
- symmetry of water wave problem: $\phi \mapsto \phi + \gamma$, for all $\gamma \in \mathbb{R}$
- the uniform flow is a symmetry induced solution:
 $\phi(x, y, t) = u_0 x + \phi_0$
- if the system is generated by a Lagrangian then symmetry implies the conservation law
- strategy: modulate basic state, use connection between symmetry and CLAW to get modulation equation

Symmetry, modulation, KdV

- Lagrangian $\int \int \int L dx dz dt$ (e.g. Luke's Lagr)
- One-parameter symmetry group \Rightarrow CLAW $A_t + B_x = 0$
- basic state: $\widehat{Z}(\theta, k)$ with $\theta = kx + \theta_0$
- modulate: $Z(x, t) = \widehat{Z}(\theta + \varepsilon\psi, k + \varepsilon^2q) + \varepsilon^3W(\theta, X, T)$
- Evaluate CLAW on basic state: $\mathcal{A}(k)$ and $\mathcal{B}(k)$
- If $\mathcal{B}'(k) = 0$ (criticality) then KdV emerges

$$2\mathcal{A}_k q_T + \mathcal{B}_{kk} q q_X + \mathcal{K} q_{XXX} = 0.$$

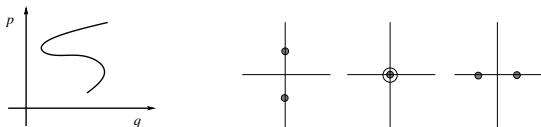
- \mathcal{K} : Krein signature, sign of momentum flux, dispersion relation,

Planar homoclinic bifurcation

Consider a parameter-dependent planar Hamiltonian system

$$-\dot{p} = \frac{\partial H}{\partial q}, \quad \dot{q} = \frac{\partial H}{\partial p}, \quad \text{with } H(q, p, \alpha).$$

Suppose there is a family of equilibria $(q_0(\alpha), p_0(\alpha))$.



Suppose further that at some value $\alpha = \alpha_0$ there is a saddle-centre transition of eigenvalues.

Planar homoclinic bifurcation

At the saddle-centre transition, there is a Jordan chain associated with the zero eigenvalue

$$\mathbf{L}\xi_1 = 0 \quad \text{and} \quad \mathbf{L}\xi_2 = \mathbf{J}\xi_1 .$$

The linear system can be transformed to (symplectic) Jordan normal form

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{pmatrix} \tilde{q} \\ \tilde{p} \end{pmatrix}_t = \begin{bmatrix} 0 & 0 \\ 0 & s \end{bmatrix} \begin{pmatrix} \tilde{q} \\ \tilde{p} \end{pmatrix}, \quad (s = \pm 1 \text{ is a symplectic sign}).$$

(\tilde{q}, \tilde{p}) are the transformed (q, p) .

Planar homoclinic bifurcation – nonlinear theory

Introduce a nonlinear normal form transformation up to quadratic order. Again calling the new coordinates $\tilde{q}(t)$ and $\tilde{p}(t)$, they satisfy

$$\begin{aligned}-\tilde{p}_t &= I - \frac{1}{2}\kappa\tilde{q}^2 + \dots \\ \tilde{q}_t &= s\tilde{p} + \dots\end{aligned}$$

where $I = c(\alpha - \alpha_0)$ is an unfolding parameter and

$$\kappa = \langle \xi_1, D^3 H(q_0, p_0)(\xi_1, \xi_1) \rangle$$

Nonlinear normal form found in textbooks ...

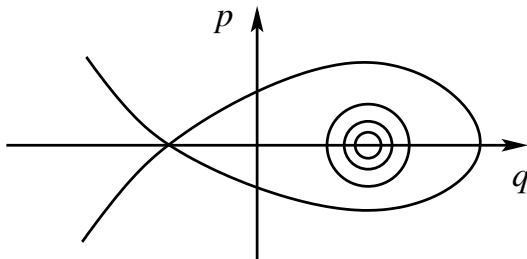
- [ARNOLD ET AL, Dyn Sys III](#); [MEYER & HALL, Ham Sys](#)

Planar homoclinic bifurcation and curvature

Generates the familiar homoclinic (fish) diagram.

$$-\tilde{p}_t = 1 - \frac{1}{2}\kappa\tilde{q}^2 + \dots$$

$$\tilde{q}_t = s\tilde{p} + \dots$$



Claim: more to the story – the coefficient κ is a curvature

Normal form via modulation

The normal form can be interpreted as a modulation equation and the coefficient κ emerges from the modulation

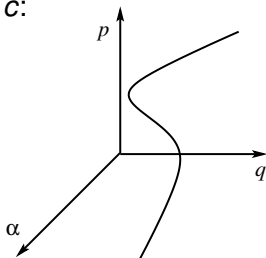
$$\begin{aligned}-\tilde{p}_t &= I - \frac{1}{2}\alpha''\tilde{q}^2 + \dots \\ \tilde{q}_t &= s\tilde{p} + \dots\end{aligned}$$

α is a function of a parameter c :

lift to (p, q, α) space

How to choose the c ?

$$c = \frac{\partial H}{\partial \alpha}$$



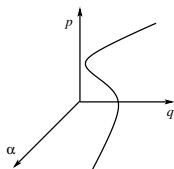
Modulation and curvature

Claim: the family of equilibria satisfy

$$H_q = 0$$

$$H_p = 0$$

$$H_\alpha = c$$



Saddle-centre at $c = c_0 \Leftrightarrow \alpha'(c_0) = 0$

Nonlinear coefficient κ equals the curvature $\alpha''(c_0)$.

Lift: equilibria ↗ relative equilibria

$$\left. \begin{aligned} -\dot{p} &= H_q \\ \dot{q} &= H_p \\ -\dot{\alpha} &= 0 \end{aligned} \right\} \text{standard lift}$$

add in $\dot{\theta} = H_\alpha$ (symplectic lift)

Symplectic lifted system has symmetry! $\gamma \mapsto \theta + \gamma \quad \forall \gamma \in \mathbb{R}$.

The equilibrium becomes a RE, $\theta(t) = ct + c_0$

RE satisfy

$$H_q = 0, \quad H_p = 0, \quad H_\alpha = c.$$

Normal form via modulation

Hamiltonian system on \mathbb{R}^4

$$\mathbf{J}Z_t = \nabla H(Z), \quad Z \in \mathbb{R}^4. \quad (1)$$

One-parameter abelian symmetry group with RE:

$$\widehat{Z}(\theta, \mathbf{c}) \quad \text{where} \quad \theta = ct + \theta_0.$$

Evaluate conserved quantity, $\alpha_t = 0$ on RE: $\alpha(\mathbf{c})$

Modulate (ansatz)

$$Z(t) = \widehat{Z}(\theta + \varepsilon\phi, \mathbf{c} + \varepsilon^2\mathbf{q}) + \varepsilon^3 W(\theta, T, \varepsilon), \quad (2)$$

where $\phi(T, \varepsilon)$ and $T = \varepsilon t$.

Normal form via modulation

Substitute the ansatz

$$Z(t) = \widehat{Z}(\theta + \varepsilon\phi, \mathbf{c} + \varepsilon^2\mathbf{q}) + \varepsilon^3 W(\theta, T, \varepsilon), \quad (3)$$

into $\mathbf{J}Z_t = \nabla H(Z)$, expand everything in powers of ε

- ε^2 : $\mathbf{q} = \phi_T$
- ε^3 : solvability for W_1 requires $\alpha'(c_0) = 0$ for some c_0
- ε^4 : solve equation for W_2
- ε^5 : solvability for W_3 if and only if

$$\alpha''(c_0)qq_T - sq_{TTT} = 0.$$

Normal form via modulation

Substitution of the ansatz, and equating terms up to ε^5 to zero gives

$$q = \phi_T \quad \text{and} \quad \alpha''(c_0)qq_T - sq_{TTT},$$

or, integrating the second equation and calling the constant of integration I ,

$$\begin{aligned} -\dot{I} &= 0 \\ -\dot{p} &= I - \frac{1}{2}\alpha''(c_0)q^2 \\ \dot{\phi} &= q \\ \dot{q} &= sp. \end{aligned}$$

Now reduce back to the planar system, giving the modulation characterisation of the planar normal form.

Normal form via modulation

$$-\dot{p} = l - \frac{1}{2}\alpha''(c_0)q^2$$

$$\dot{q} = sp$$

$$-\dot{l} = 0$$

$$\dot{\phi} = q$$

The first two components recover the normal form, with a new interpretation of the coefficient of nonlinearity as a curvature.

Note that the spectrum of the linear system (the “dispersion relation”) is not computed: the saddle-centre is predicted by $\alpha'(c_0) = 0$.

Saddle-centre to homoclinic bifurcation

- Dynamical systems approach: compute eigenvalues, identify saddle-centre transition, normal form transformations, analyze normal form
- Geometric approach: lift equilibria to RE, generates function $\alpha(c)$, $\alpha'(c) = 0$ then implies saddle-centre, $\alpha''(c)$ gives coefficient of normal form, analyze normal form.
- Concomitantly, can modulate a family of RE, and generate conditions and normal form for homoclinic bifurcation
- $\alpha''(c_0)qq_T - sq_{TTT} = 0$ with T replaced by X is steady KdV

KdV via RE and modulation

Where does the KdV equation come from?

Most widely used approach: the dispersion relation \Rightarrow KdV equation

For some system of PDEs, suppose the dispersion relation to leading order is

$$\omega = -c_0 k + a k^3 + \dots$$

replace $i\omega$ by ∂_t and ik by ∂_x and add in nonlinearity

$$0 = \eta_t + c_0 \eta_x + a \eta_{xxx} + \begin{cases} b \eta^2 \\ b \eta \eta_x \\ b \eta_x^2 \end{cases}$$

Symmetry argument leads to the middle choice. Now compute coefficients. *The most difficult calculation is the coefficient b of the nonlinearity.*

Derivation of KdV for water waves

- Assume shallow water: $h_0/L \rightarrow 0$. The limiting equation is the SWEs.
- “amplitude balances dispersion” – introduce an amplitude parameter take amplitude and h_0/L to zero in appropriate ratio. Limiting equation is a two way Boussinesq SWE.
- Now uni-directionalise: split the Boussinesq equation into a left-running and right-running component. Result is a pair of KdV equations. (hidden assumption of criticality)

— Shallow water is neither necessary nor sufficient for emergence of the KdV equation —

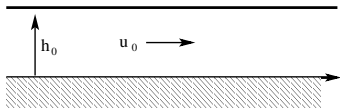
Emergence of KdV by modulating background state

- New observation: KdV emerges due to modulation of the background state
- The resulting KdV equation takes a universal form

$$2\mathcal{A}'(k)q_T + \mathcal{B}''(k)qq_X + \mathcal{K}q_{XXX} = 0$$

- Coefficients – including nonlinearity – reduced to an elementary calculation.
- **KdV arises due to a critical point of a family of RE – in the classic case the RE is a uniform flow.**

The KdV equation in shallow water hydrodynamics



The KdV equation in shallow water is

$$2\mathcal{A}'(u_0)qq_T + \mathcal{B}''(u_0)qq_X + \mathcal{K} q_{XXX} = 0,$$

where, relative to a laboratory frame,

$$\mathcal{A}(u_0) = h_0 = \frac{1}{g}(R - \frac{1}{2}u_0^2) \quad \text{and} \quad \mathcal{A}'(u_0) = -\frac{u_0}{g},$$

and

$$\mathcal{B}(u_0) = h_0 u_0 = \frac{u_0}{g}(R - \frac{1}{2}u_0^2) \quad \text{and} \quad \mathcal{B}''(u_0) = -3\frac{u_0}{g}.$$

KdV in shallow water continued

Substituting

$$-2\frac{u_0}{g}q_T - 3\frac{u_0}{g}qq_X + \frac{1}{3}h_0^3q_{XXX} = 0,$$

and computing $\mathcal{K} = h_0^3/3$. Now let $q = -u_0 h/h_0$, then

$$-\frac{1}{u_0}h_T + \frac{3}{2h_0}hh_X + \frac{1}{6}h_0^3h_{XXX} = 0,$$

the familiar form of the KdV found in textbooks, noting that $u_0 = \pm\sqrt{gh_0}$ (since $\mathcal{B}'(u_0) = 0$).

$$\mathcal{K} = \frac{2\mathcal{A}_u}{6}\omega_{kkk} = \Delta S = \frac{h_0^3}{3}.$$

Dynamical systems interpretation of \mathcal{H}

Write the universal KdV as a first order system

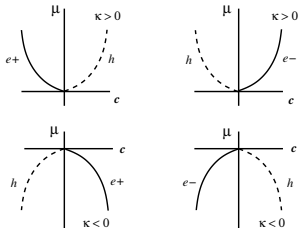
$$-\mathcal{A}_k q_T - \mu X = 0$$

$$\mathcal{A}_k \phi_T - pX = \mu - \frac{1}{2} \mathcal{B}_{kk} q^2$$

$$\phi_X = q$$

$$q_X = sp \quad s = -\mathcal{H},$$

Steady RE: $\phi(X) = cX + \phi_0$. There are 4 classes depending on the sign of s and $\kappa = \mathcal{B}_{kk}$. e^\pm are the Krein signatures of the “incoming” periodic solution.



Emergence of KdV based on modulation of RE

Consider a PDE with Lagrangian

$$\mathcal{L}(Z) = \int \int L(Z_t, Z_x, Z) dx dt,$$

with Euler-Lagrange equation

$$\frac{\partial}{\partial t} \left(\frac{\delta L}{\delta Z_t} \right) + \frac{\partial}{\partial x} \left(\frac{\delta L}{\delta Z_x} \right) - \frac{\delta L}{\delta Z} = 0.$$

Symmetry, Noether, CLAW, relative equilibrium

$$Z(x, t) = \widehat{Z}(\theta, k), \quad \theta = kx + \theta_0,$$

associated with symmetry and a conservation law

$$A_t + B_x = 0.$$

Modulate: $Z(x, t) = \widehat{Z}(\theta + \varepsilon\psi, k + \varepsilon^2q) + \varepsilon^3W(\theta, X, T, \varepsilon)$

Modulate and expand in powers of ε

Modulate the family of RE: $\widehat{Z}(\theta, k)$

$$Z(x, t) = \widehat{Z}(\theta + \varepsilon\psi, k + \varepsilon^2q) + \varepsilon^3W(\theta, X, T, \varepsilon),$$

with $\psi(X, T, \varepsilon)$, $q(X, T, \varepsilon)$ and scaling

$$T = \varepsilon^3t \quad \text{and} \quad X = \varepsilon x.$$

With $W = W_1 + \varepsilon W_1 + \varepsilon^2 W_2 + \dots$, the ε^n terms give

$$\varepsilon^2 : \quad q = \psi_X$$

$$\varepsilon^3 : \quad \text{equation for } W_1 \text{ solvable iff } \mathcal{B}'(k) = 0$$

$$\varepsilon^4 : \quad \text{gives equation for } W_2,$$

Fifth order terms

and at ε^5 ,

$$\mathbf{L}W_3 = (\mathbf{M}\hat{Z}_k + \mathbf{J}\zeta) \mathbf{q}_T + (\mathbf{J}\hat{Z}_{kk} + \mathbf{J}(\hat{\xi}_3)_\theta - D^3 \mathbf{S}(\hat{Z}^0)(\hat{Z}_k, \hat{\xi}_3)) \mathbf{q}q_x + \mathbf{J}\hat{\xi}_4 \mathbf{q}_{xxx}.$$

Solvability gives (after a few pages!)

$$2\mathcal{A}'(k) \mathbf{q}_T + \mathcal{B}''(k) \mathbf{q}q_x + \mathcal{K} \mathbf{q}_{xxx} = 0$$

Symmetry and conservation laws

Lagrangian + symmetry + Noether's Theorem \Rightarrow CLAW

Consider a classical finite-dimensional Hamiltonian system

$$\mathbf{J}Z_t = \nabla H(Z).$$

Suppose it has a one-parameter symmetry with action and generator

$$G_\theta Z \quad \text{and} \quad \left. \frac{d}{d\theta} G_\theta Z \right|_{\theta=0} = \widehat{Z}_\theta.$$

Then invariance of H : $H(G_\theta Z) = H(Z)$ gives $A_t = 0$ with

$$A(Z) = \frac{1}{2} \langle \mathbf{J} \widehat{Z}_\theta, Z \rangle \quad \Rightarrow \quad \nabla A(Z) = \mathbf{J} \widehat{Z}_\theta.$$

Hence

$$\mathcal{A}_C = \langle \nabla A(\widehat{Z}), \widehat{Z}_C \rangle = \langle \mathbf{J} \widehat{Z}_\theta, \widehat{Z}_C \rangle.$$

Lagrangian \rightarrow Hamiltonian \rightarrow Multisymplectic

Start with a **Lagrangian** formulation

$$\mathcal{L}(U) = \int \int L(U_t, U_x, U) dxdt,$$

Legendre transform $V = \delta L / \delta U_t$, giving a **Hamiltonian** formulation

$$\mathcal{L}(W) = \int \int \left[\frac{1}{2} \langle \mathbf{M}W_t, W \rangle - H(W_x, W) \right] dxdt,$$

Legendre transform again $P = \delta L / \delta W_x$, giving a **multisymplectic Hamiltonian** formulation

$$\mathcal{L}(Z) = \int \int \left[\frac{1}{2} \langle \mathbf{M}Z_t, Z \rangle + \frac{1}{2} \langle \mathbf{J}Z_x, Z \rangle - S(Z) \right] dxdt,$$

two symplectic structures and a Hamiltonian function $S(Z)$.

Symmetry and conservation laws

Starting with

$$\mathbf{M}Z_t + \mathbf{J}Z_x = \nabla S(Z), \quad Z \in \mathbb{R}^n,$$

with a one-parameter symmetry group

$$G_\theta Z \quad \text{and} \quad \left. \frac{d}{d\theta} G_\theta Z \right|_{\theta=0} = \xi Z,$$

and associated conservation law

$$A_t + B_x = 0,$$

the invariance of $S(Z)$ in the multisymplectic setting gives

$$\nabla A(Z) = \mathbf{M} \left. \frac{d}{d\theta} G_\theta Z \right|_{\theta=0} \quad \text{and} \quad \nabla B(Z) = \mathbf{J} \left. \frac{d}{d\theta} G_\theta Z \right|_{\theta=0}$$

Moving frame

Moving frame: $x \mapsto x - ct$,

$$\mathbf{M}Z_t + (\mathbf{J} - c\mathbf{M})Z_x = \nabla S(Z), \quad Z \in \mathbb{R}^n.$$

Let $\hat{\mathbf{J}}(c) = \mathbf{J} - c\mathbf{M}$

$$\mathbf{M}Z_t + \hat{\mathbf{J}}(c)Z_x = \nabla S(Z), \quad Z \in \mathbb{R}^n.$$

and proceed as before.

$$\text{Criticality: } \mathcal{B}_k - c\mathcal{A}_k = 0,$$

and emergent KdV is replaced by

$$2\mathcal{A}_k q_T + (\mathcal{B}_{kk} - c\mathcal{A}_{kk})qq_X + \mathcal{K}(c)q_{XXX} = 0$$

with $\mathcal{A}(k, c)$ and $\mathcal{B}(k, c)$.

Classical multiple scales vs modulation

Given a basic state, represented by $\widehat{Z}(\theta, k)$, with $\theta = kx + \theta_0$, a multiple scales perturbation would be

$$Z(x, t) = \widehat{Z}(\theta, k) + \varepsilon^d \widetilde{W}(\theta, X, T, \varepsilon),$$

with slow space and time scales $T = \varepsilon^\alpha t$, $X = \varepsilon^\beta x$.
Include modulation of the basic state

$$Z(x, t) = \widehat{Z}(\theta + \varepsilon^a \psi, k + \varepsilon^b q) + \varepsilon^d W(\theta, X, T, \varepsilon),$$

with slow space and time scales $T = \varepsilon^\alpha t$, $X = \varepsilon^\beta x$.
They are equivalent ... but the second formulation encodes info about basic state.

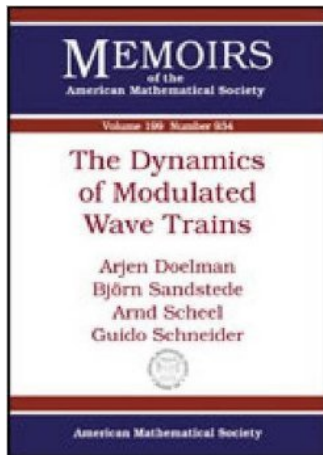
- homoclinic bifurcation from RE – clearly related to steady KdV $\alpha'' qq_T - sq_{TTT}$ with T replaced by X .
- Must be a generalization to KDV

$$[?]q_T + \kappa qq_X + \mathcal{K} q_{XXX} = 0$$

where κ is some curvature.

- ad hoc approach: nf transforms in space then in time - works: coefficient is related to CLAW density★
- Not completely satisfactory approach
- Roger Grimshaw: "... can you do it with a solvability condition?"

★ TJB [2012] PRSLA, Emergence of DSWs



History 3: Doelman et al (2009)

Start with reaction diffusion system

$$\mathbf{U}_t = \mathbf{D}\mathbf{U}_{xx} + \mathbf{f}(\mathbf{U}), \quad \mathbf{U} \in \mathbb{R}^n$$

with period solution $\widehat{\mathbf{U}}(\theta, k)$, $\theta = kx - \omega t$.

Modulate

$$\mathbf{U}(x, t) = \widehat{\mathbf{U}}(\theta + \phi, k + \varepsilon q) + \varepsilon^2 W,$$

with $X = \varepsilon x$, $T = \varepsilon^2 t$. Expansion and solvability lead to

$$q_T + aq_X = \nu q_{XX} \quad (\text{Burger's equation})$$

Kivshar (1990): use modulation for defocussing NLS to KdV

$$\Psi(x, t) = (\Psi_0 + \varepsilon^2 q(X, T, \varepsilon)) e^{i(kx + \varepsilon \phi(X, T, \varepsilon))}$$

with $T = \varepsilon^3 t$.

History 4: other influences

- Hall & Hewitt (1998) modulation of shear flows in Navier-Stokes leading to Burger's equation coupled to mean flow
- Whitham (1965) modulation of periodic travelling waves leading to conservation of wave action
- Kivshar (1990) modulation of plane waves
- Grimshaw (2012) Madelung transformation, solvability condition

Combine: (a) generalize scaling ansatz ; (b) association with symmetry & RE; (c) Lag/Ham/MSS setting; (d) use of geometry of RE and conservation laws; (e) curvature & coefficients.