

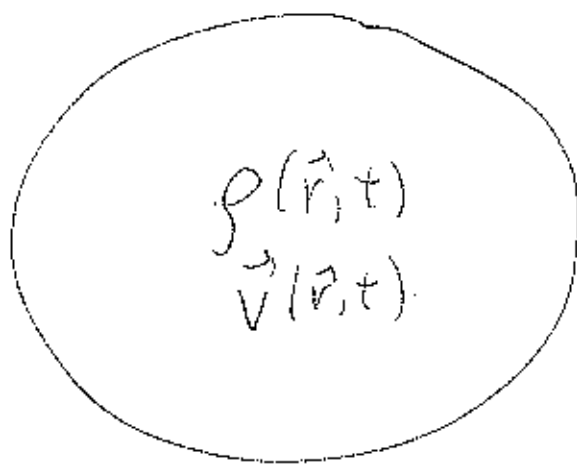
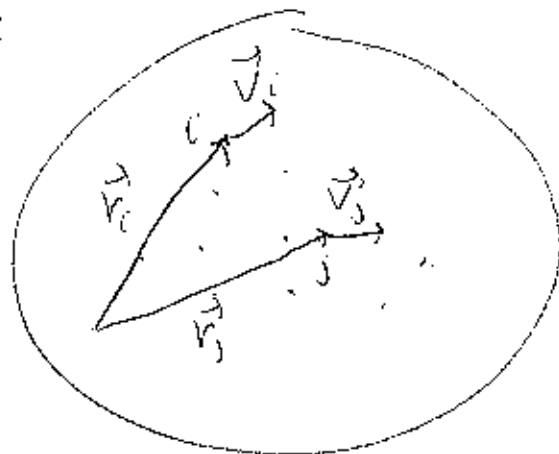
# Deriving Continuum EOM:

(II) AI. <sup>DI</sup>

Hydrodynamic approach: (e.g.) simple fluid

Go from:

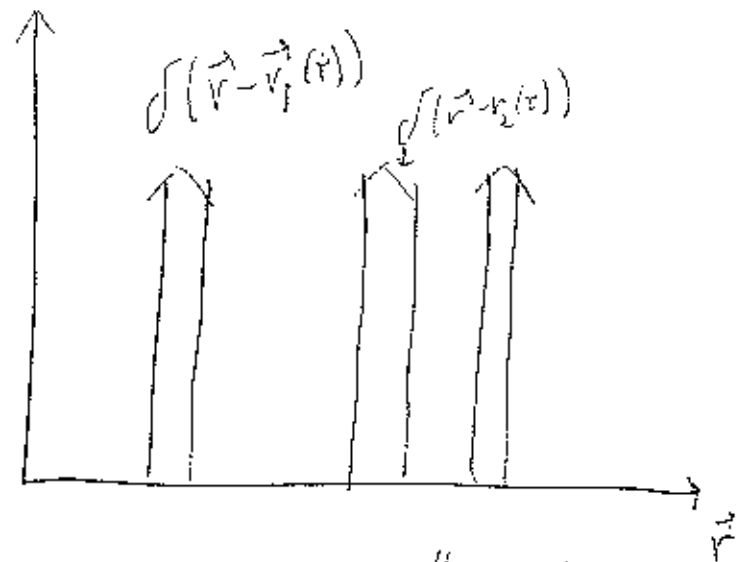
Discrete:  
 $\{\vec{r}_i(t), \vec{v}_i(t)\}$



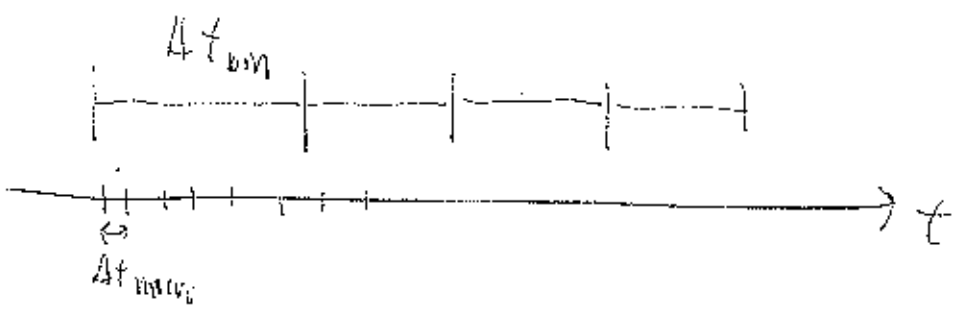
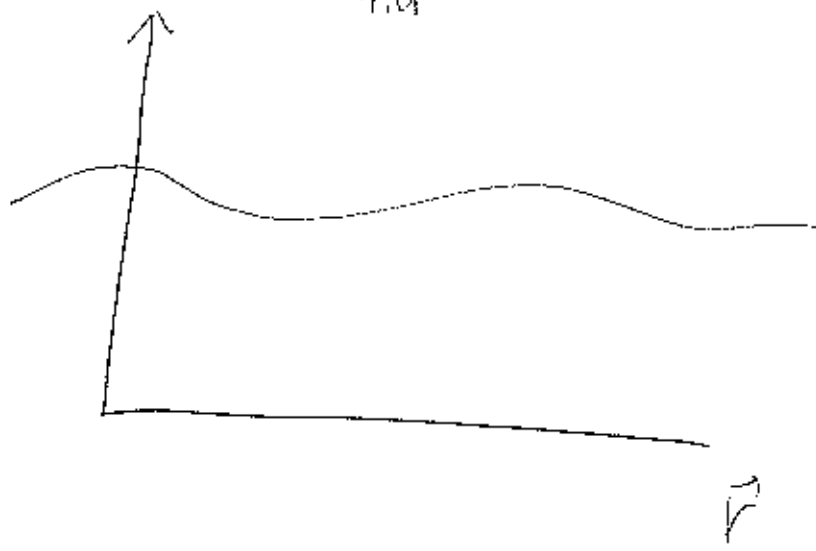
By "course-graining"

(either space, time, or both)

$\rho(\vec{r}, t)$  INSTANTANEOUS:

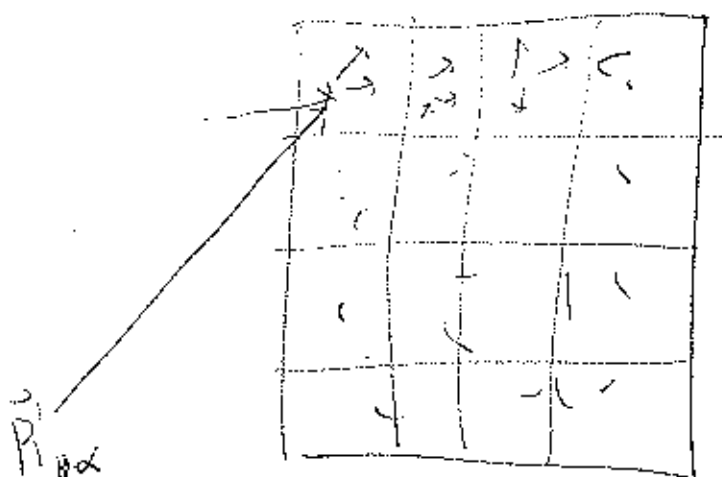


TIME AVERAGE: over "bins"  $\Delta t_{bin} \gg \Delta t_{step}$   
 $\langle \rho_{bins} \rangle_{\Delta t_{bin}}$



space average:

JA



$R_{i,t}$   
box  
↑  
EOM  
(Spatial  
eq. label)

$$\rho(\vec{R}_{i,t}) \equiv \frac{N_e \text{ kind}}{V_{\text{bin}}} \Big|_{\text{time } t}$$

$$\downarrow$$
$$\rho(\vec{r}, t)$$

Same with  $\vec{v}$ .

Try to "guess" EOM's from

symmetry principles

and

conservation laws

This "hydrodynamic" approach  
intrinsically long wavelength,  
long time (indeed, long ~~area~~ time  
at long wavelength)

$L \gg a \leftarrow$  "microscopic" length (e.g.,  
inter-bird distance)

$t \gg \Delta t \leftarrow$  "time  
(e.g., ~~update~~  
direction update time  
"taking watch")

We hope (and invariably find)  
universality at these length and  
time scales

(e.g.: All ~~fluids~~ simple fluids obey  
Navier-Stokes equation

Problem: How do you know

$\rho(\vec{r}, t)$ ,  $\vec{v}(\vec{r}, t)$  are only fields you need?

What about other variables  $X_{\alpha}(\vec{r}, t)$ ?

(E.g.)  $X_1(\vec{r}, t)$  = # of birds moving "backwards" ( $\theta < 90^\circ$  to mean direction of neighbors) in bin  $\Delta$ ).

Answer: Almost all variables are "fast" (i.e., relax rapidly to values determined by local values of "slow" variables (Here,  $\rho$  and  $\vec{v}$ )).

(See discussion in D. Forster, "Hydrodynamic ~~and~~ Fluctuations, Broken Symmetry, and Correlation Functions")

Consider some <sup>"fast"</sup> variable "x". What is its EOM?



$$\partial_t x = -\frac{x}{\tau_x} + f(\text{slow variables})$$

relaxation time for x.

If we're considering slow modes (i.e., modes for which <sup>(frequency)</sup>  $\omega \rightarrow 0$  as  $L \rightarrow \infty$ ), LHS  $(\partial_t x) \ll \frac{x}{\tau} \Rightarrow$  drop it

$$\Rightarrow \boxed{x = \tau f(\text{slow variables})} *$$

$\Rightarrow$  If "slow variables" contain EOM's contain x:

$$\partial_t (\text{slow}) = g(x) + \dots$$

Can use \* to rewrite

as  $\partial_t(\text{slow}) = f(\text{slow})$

So: We only need to consider slow variables

Strategy: Guess form of  $f(\text{slow})$

(Actually, write down most general form allowed by symmetries + conservation laws)

What are slow variables?

Variables for which  $\tau \rightarrow \infty$  as wavelength  $L \rightarrow \infty$ .

~~Why are the~~

(11)

Why are there any slow variables?  
 ("slow" variables = "hydrodynamic variables")

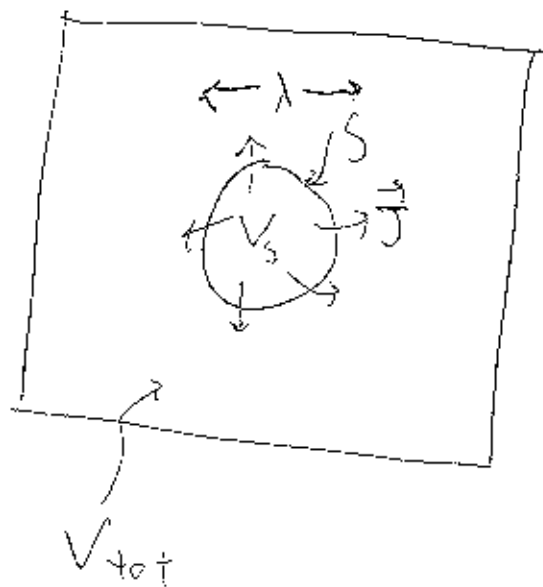
Ans: Symmetries and conservation laws  
 Conservation laws

Example: Number density  $\rho(\vec{r})$   
 (for either fluid or flock):

$$\int_{V_{\text{tot}}} \rho(\vec{r}) d^d r = N = \text{constant}$$

$$\frac{d}{dt} \int_{V_S} \rho(\vec{r}) d^d r = - \oint_S \vec{J}_n \cdot d\vec{S}$$

$\vec{J}_n$   
 particle current  
 number





⇒ Divergence Thm

$$\Rightarrow \boxed{\partial_t \rho + \vec{\nabla} \cdot \vec{J} = 0}$$

⇒ If  $\vec{J}(\vec{r}, t)$  varies on length scale  $\lambda$ ,  $\vec{\nabla} \cdot \vec{J} \sim \frac{J}{\lambda}$

$$\partial_t \rho \sim \frac{J}{\lambda} \rightarrow 0 \text{ as } \lambda \rightarrow \infty$$

⇒  $\rho$  hydrodynamic (slow)



Are there any ~~add~~ other conserved quantities?

Insert  
IIA!

For fluid moving in vacuum, yes!  
momentum density  $\vec{g} = m \vec{v}$   
particle mass

For fluid (or flock) moving on substrate: No! Friction between substrate and fluid (or flock)

⇒ As discussed earlier, can eliminate  $\vec{g}$ .

In fact, we all know:

$$\vec{J} = \rho \vec{v} \equiv \vec{g}/m$$

↑  
number current

$$\Rightarrow \partial_t \rho + \vec{\nabla} \cdot \left( \frac{\vec{g}}{m} \right) = 0$$

continuity equation

$$\Rightarrow \boxed{\partial_t \vec{g} = - \mu \vec{g} - \vec{\nabla} P(\rho)}$$

linear friction coefficient

$\Rightarrow$  for slow modes,  $|\partial_t \vec{g}| \ll (\mu \vec{g})$  (def'n of hydrodyn limit)

$$\Rightarrow 0 \approx -\mu \vec{g} - \vec{\nabla} P(\rho)$$

$$\Rightarrow \vec{g} = -\frac{1}{\mu} \vec{\nabla} P(\rho)$$

Put in continuity equation

$$\Rightarrow \boxed{\partial_t \rho = -\frac{1}{\mu m} \vec{\nabla}^2 P(\rho)} \quad (1)$$

Now, if we assume  $P(\rho) = \rho \lambda^{-3}$   
 $\uparrow$   
 inverse compressibility

$$\Rightarrow \boxed{\partial_t \rho = \left( \frac{1}{\mu m \lambda} \right) \nabla^2 \rho \equiv D \nabla^2 \rho}$$

Diffusion equation.

Note, in any case, whatever  $P(\rho)$  is, (1) involves only  $\rho$ . (I.e., only hydrodynamic variables appear in hydrodynamic eqn)

(See, e.g., Puri + Mazenko, 198(?) )

for discussion of beyond hydrodynamic description of this)

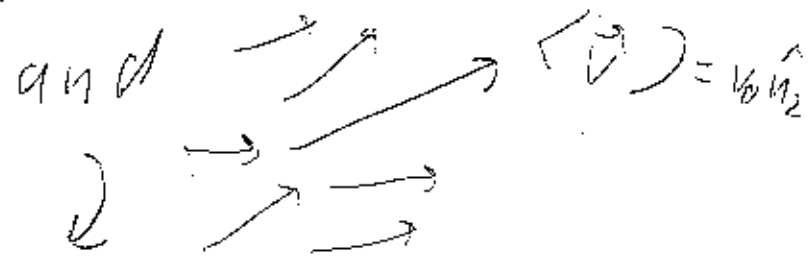
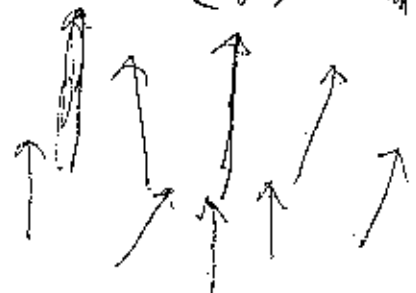
Now: ~~the~~ 2nd class of hydrodynamic variables: Goldstone modes

Spontaneously broken continuous symmetry

Example: Flock

a priori,

$$\langle \vec{v} \rangle = v_0 \hat{n}_1$$

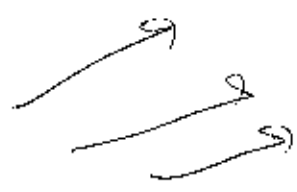


are equally likely. (For rotationally invariant rules)

If a state with all  $\vec{v}(\vec{r}) = v_0 \hat{n}_1$  is a steady state



So is



$$v(\vec{r}) = v_0 \hat{n}_2$$

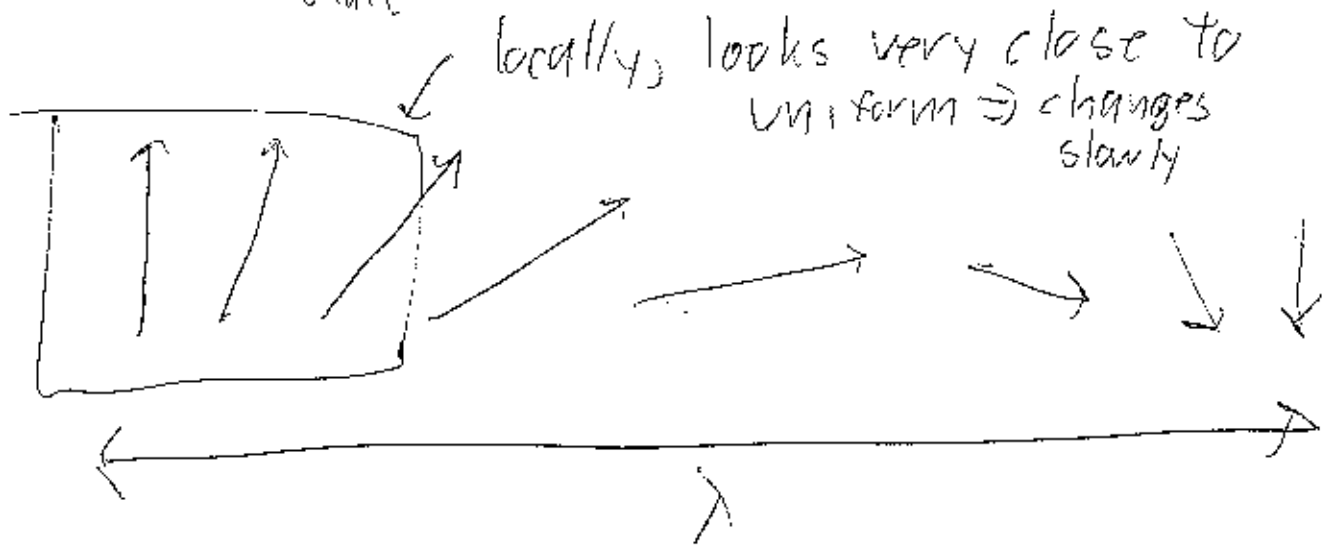
But: flock can only be in one of this continuum of possible states

(ferromagnetic)

⇒ By establishing flocking state,  $\langle \vec{v} \rangle \neq \vec{0}$ , spontaneously breaks continuous symmetry (in this case, rotation invariance)

But ⇒ by continuity, if  $\frac{d\vec{v}}{dt} \Big|_{\text{uniform state}} = \vec{0}$

$\frac{d\vec{v}}{dt} \Big|_{\text{slowly varying state}} \rightarrow 0$  as  $\lambda \rightarrow \infty$



⇒ ~~It is thought~~

$\vec{v}$  is still a hydrodynamic variable (or, at least, some components are) for

flock on substrate, in broken symmetry

state (i.e., when flock actually

moves). ⇒  $\vec{v}$  is a Goldstone (Nambu) mode

Other examples from condensed matter:

<del>Magnetization</del> system	broken symmetry	Goldstone mode variable
ferromagnet	rotational invariance	magnetization $\vec{M}(\vec{r}, t)$
flock		velocity $\vec{v}(\vec{r}, t)$
nematic (equilibrium or active)		$\vec{Q}$ (nematic order parameter)
crystal (active or under equilibrium)	translational invariance	$\vec{u}(\vec{r}, t)$ displacement field

Formulating hydrodynamic equations.

~~work~~

Gradient expansion

We know hydrodynamic variables  $\rho(\vec{r}, t), \vec{v}(\vec{r}, t)$

How do we write down EOM's?

$$\partial_t \rho = \text{stuff}(\rho, \vec{v})$$

$$\partial_t \vec{v} = \overrightarrow{\text{stuff}}(\rho, \vec{v})$$

Hard way: derive "stuff" from microscopic.

Easy way: Write down all terms in stuff allowed by symmetry (not in flocks, not inv.)  
 + conservation laws (# conservation in flocks)

Still a lot of terms.

Further reduction: Gradient expansion

Since we're interested in wavelengths

$$\lambda \rightarrow \infty, \text{ and } \vec{\nabla} \sim \frac{1}{\lambda};$$

keep only terms with fewest gradients. (small)

Eg: in  $\vec{v}$  eqn., ~~terms~~

$$\vec{\text{stuff}}_1 \equiv \eta \nabla^2 \vec{v} \quad \text{and}$$

$$\vec{\text{stuff}}_2 \equiv \eta_0 \nabla^4 \vec{v}$$

are both allowed by ~~symmetry~~

rotation invariance

$$\text{But } \vec{\text{stuff}}_1 \sim \frac{v}{\lambda^2} \gg \vec{\text{stuff}}_2 \sim \frac{v}{\lambda^4}$$

$\Rightarrow$  drop  $\vec{\text{stuff}}_2$



Instantly eliminates  $\infty$  many terms:  $\eta \nabla^2 \vec{v} \equiv \overrightarrow{\text{stuff}}_{\eta}$

terms can all be dropped.

Bly Reduces eqns to finite set of terms.

We ~~do~~ "bury our ignorance" of microscopic details in phenomenological parameters like  $\eta$

Different flocks (or fluids) will have different  $\eta$ , but all flocks (or fluids) will have  $\eta \nabla^2 \vec{v}$  term in  $\vec{v}$  ECM.

OK, so let's go:

$$\partial_t \rho = ?$$

~~RM~~ Conservation of #

$$\Rightarrow \partial_t \rho = -\vec{\nabla} \cdot \vec{J}$$

We know that  $\vec{J} = \frac{\vec{g}}{m} = \rho \vec{v}$

So  $\partial_t \rho + \vec{\nabla} \cdot (\rho \vec{v}) = 0$  1 down,  
1 to go.

What about  $\vec{v}$  equation?

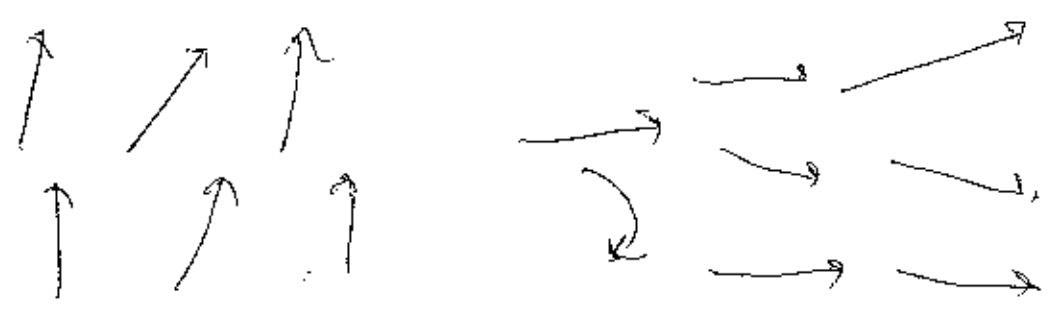
Constrained by rotation invariance

$\Rightarrow$  stuff can not contain

any a priori fixed vectors

$\vec{n}$  (these pick out special direction)

If we rotate whole picture:



EOM for  $\vec{v}$  should not change

$$\Rightarrow \text{If } \vec{v} \rightarrow R \vec{v}$$

$$\vec{r} \rightarrow R \vec{r}$$

$$\vec{v} \rightarrow R \vec{v}$$

EOM should not change.

So, what sort of terms does that allow for  $\vec{v}$  stuff?

$$\partial_t \vec{v} \rightarrow R \partial_t \vec{v}$$

$\vec{\text{stuff}}_1 = \alpha \vec{V}$  is allowed

also,

$\vec{\text{stuff}}_2 = f(|\vec{V}|) \vec{V}$  " "

↑  
any  $f$  (will discuss  $f$ 's that ~~also~~ have ferromagnetic flock state later)

What else?

$\vec{\nabla} P(\phi) \rightarrow \vec{\nabla} P(\phi, \vec{V})$  is allowed (any  $P(\phi)$ )

$P(\phi) \equiv$  "Pressure"

What else?

~~Any combination of  $\partial_i, v_j$~~

$\partial_i v_j =$  Any comb of  $(\partial_j, v_k, \phi)$  with one free index  $i$

Any vector  $\vec{V}$  made out of  $\vec{v}, \vec{v}, \rho$ .

But: because gradient expansion, need only keep terms with small # of grad  $\vec{v}$ 's.

Possibilities with 1 gradient:

$$(\partial_t \vec{v}_0)_{\lambda_1} \equiv \lambda_1 (\vec{v} \cdot \nabla) \vec{v}$$

(or:  $\nabla v_i$ )

$$(\partial_t v_i)_{\lambda_1} \equiv \lambda_1 v_j \partial_j v_i$$

(like "convective derivative" in fluid mechanics:

$$\partial_t \vec{v}_{fluid} + (\vec{v}_f \cdot \nabla) \vec{v}_f = \dots$$

$$\Rightarrow \partial_t \vec{v}_f = -(\vec{v}_f \cdot \nabla) \vec{v}_f + \dots$$

$$\Rightarrow \boxed{\lambda_i^{fluid} = -1}$$

~~Digression: Why does~~

Digression: Why does  $\lambda_1 = -1$  in fluid?

No substrate  $\Rightarrow$  Galilean invariance (extra symmetry)

$$\Rightarrow \vec{v}(\vec{r}, t) \rightarrow \vec{v}(\vec{r} + \vec{v}_0 t, t) + \vec{v}_0$$

speed of moving frame

(Galilean transformation (go to moving frame))

$$\Rightarrow \partial_t \vec{v} \rightarrow \partial_t \vec{v} + \vec{v}_0 \cdot \vec{\nabla} \vec{v}$$

$$(\vec{v} \cdot \vec{\nabla}) \vec{v} \rightarrow \vec{v} \cdot \vec{\nabla} \vec{v} + \vec{v}_0 \cdot \vec{\nabla} \vec{v}$$

~~$$\Rightarrow \partial_t \vec{v} = \lambda_1 \vec{v} \cdot \vec{\nabla} \vec{v}$$~~

$$\partial_t \vec{v} = \lambda_1 \vec{v} \cdot \vec{\nabla} \vec{v} \rightarrow \partial_t \vec{v} + \vec{v}_0 \cdot \vec{\nabla} \vec{v}$$

$$= \lambda_1 \vec{v} \cdot \vec{\nabla} \vec{v} + \lambda_1 \vec{v}_0 \cdot \vec{\nabla} \vec{v}$$

must balance  $\Rightarrow \lambda_1 = 1$

But for flock on substrate,

No Galilean invariance

(substrate  $\Rightarrow$  special frame)

~~$\lambda_1$  need not~~  $\lambda_1 \neq 1$  in general

Note:  $f(|\vec{v}|)\vec{v}$  term also violates Galilean invariance  $\Rightarrow$  forbidden in fluid mechanics (no substrate) allowed in presence of substrate.

For fluid, no other ~~terms~~ of  $\vec{v} \nabla \vec{v}$  terms allowed (Galilean invarian.

---

For flock, 2 more:

$$\lambda_2 \vec{v} (\vec{\nabla} \cdot \vec{v}) \propto$$

$$\partial_t v_i = \lambda_2 v_{0i} (\partial_j v_j)$$

forbidden by Galilean invariance

$$\lambda_2 \vec{v} (\vec{\nabla} \cdot \vec{v}) \rightarrow \lambda_2 \vec{v} (\vec{\nabla} \cdot \vec{v}) + \lambda_2 \vec{v}_0 (\vec{\nabla} \cdot \vec{v})$$

Nothing to cancel  $\Rightarrow \lambda_2 = 0$  if Gal. inv. holds

Can also have

$$\lambda_3 \vec{\nabla} |\vec{v}|^2$$

$$\partial_t v_i = \lambda_3 \partial_i (v_j v_j)$$

Anything else with  $\perp \vec{\nabla}$ ?

Yes (thanks to SR):

$$\lambda_4 \partial_j (v_i v_j P_2(\rho))$$

$$= \lambda_4 P_2(\rho) [v_{j0} (\partial_j v_i) + v_{i0} (\partial_j v_j)]$$

$$+ \lambda_4 P_2(\rho) [v_i v_j \partial_j P_2(\rho)]$$

absorb in  $\lambda_1(\rho), \lambda_2(\rho)$

New piece  
 (potentially relevant;  
 doesn't change linear results;  
 might change non-linear results;  
 hard to treat;  
 will ~~not~~ drop for now)

New



3  $\vec{\nabla}$  terms:

~~$\mu_1 \nabla^2 \vec{v}$~~ ,  ~~$\mu_2 \nabla_3 (\vec{v} \cdot \vec{v})$~~

~~$\mu_2 \nabla_2 (\vec{v} \cdot \vec{v}) \vec{v}$~~

(more powers of  $\vec{v}$ , but  $\langle \vec{v} \rangle \neq \vec{0}$ )

$\Rightarrow$  not necessarily smaller than  $\mu_{1,2}$  terms  $\Rightarrow$  keep.

~~$\mu_1, \mu_2$  could potentially~~

~~$\mu_{T,R}(s, |\vec{v}|)$ ,  $\mu_{B,S}(s, |\vec{v}|)$~~ : Bulk shear, bulk, and funny viscosities

~~$\mu_{T,R} \nabla \nabla^2 \rho$~~   ~~$\nabla$ 's~~: Ignore (gradient expansion)

$\nabla \nabla^2 \rho$ ?  $\ll \rho (\vec{v} \cdot \vec{v}) \vec{v}$  term  $\Rightarrow$  drop.

~~$\mu_{T,R} > 2$~~   ~~$\nabla$ 's~~: Drop ( $\vec{\nabla}$  expansion)

Final term: Langevin noise  $\vec{f}(\vec{r}, t)$  (mistakes) Gaussian, white noise, short spatio-temporal correlation

IIA2.

Comment: Crucial difference between flock with substrate  
( $\vec{v}$  slow because of symmetry, not momentum conservation and fluid without substrate  
( $\vec{v}$  slow because  $\vec{g}$  conserved)

In no-substrate case,  $\vec{g}$  conserved  
 $\Rightarrow \vec{v} \cdot \vec{f} = 0 \Rightarrow$  Effects of  $\vec{f}$  small at long wavelengths  $\lambda$

Why? Spatial Fourier transform:

$$\vec{q} \cdot \vec{f}(\vec{q}, t) = 0$$

$$\Rightarrow \langle f_i(\vec{q}, t) f_j(-\vec{q}, t') \rangle = \Delta(\vec{q}) P_{ij}(\vec{q}) \delta(t-t')$$

$P_{ij}(\vec{q}) \equiv \delta_{ij} - \frac{q_i q_j}{q^2}$  : Transverse projection operator

But:  $\langle ff \rangle$  must be analytic function of  $\vec{q}$  (otherwise, long ranged correlations)

$$\Rightarrow \Delta(\vec{q} \rightarrow 0) \rightarrow \langle q^2 \rightarrow 0 \text{ as } |\vec{q}| \rightarrow 0$$

Flerk Flock with ~~the~~ substrate: (IA)

→ slow because of rotation invariance

$$\Rightarrow \vec{v} \cdot \vec{f} \text{ need not } \neq 0$$

$\Rightarrow \langle ff \rangle$  does not vanish as  $\vec{q} \rightarrow \vec{0}$ .

$$\langle f_i(\vec{q}, t) f_j(-\vec{q}, t') \rangle = \Delta \delta(t-t')$$

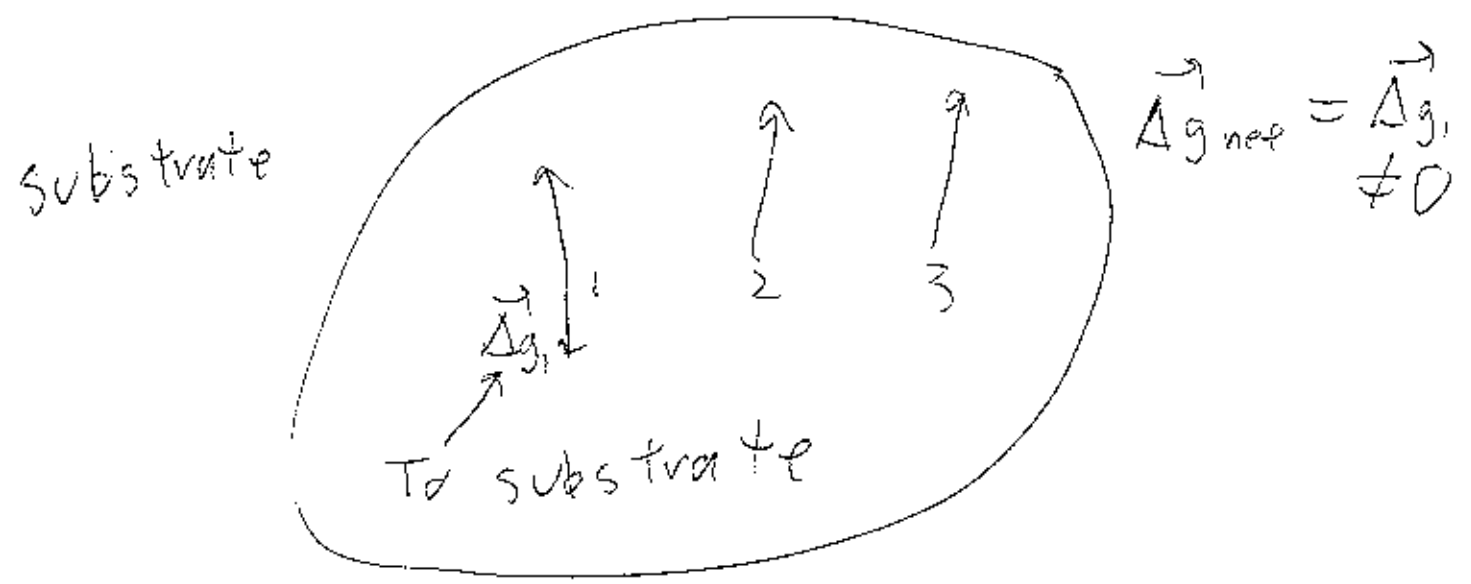
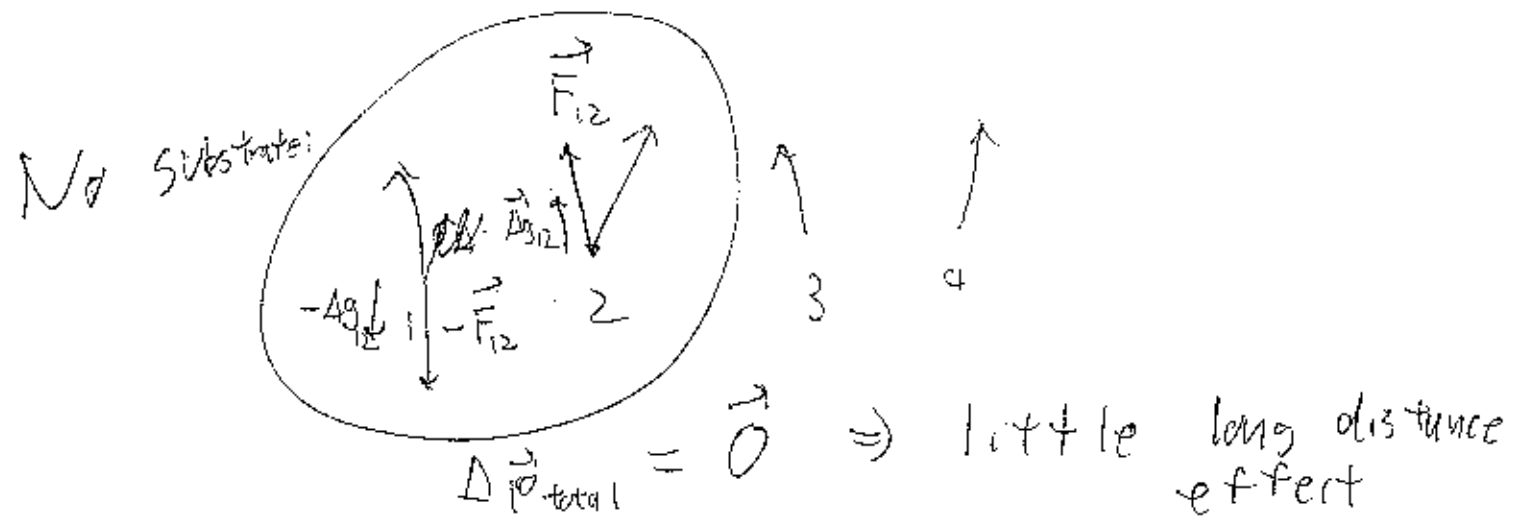
↑  
constant  
as  $|\vec{q}| \rightarrow 0$

↓

~~$\langle f_i(\vec{q}, t) f_j(-\vec{q}, t') \rangle = \Delta \delta_{ij} \delta(t-t')$~~

$$\langle f_i(\vec{r}, t) f_j(\vec{r}', t') \rangle = \Delta \delta_{ij} \delta^d(\vec{r}-\vec{r}') \delta(t-t')$$

Physics: If  $\vec{g}$  conserved, random forces only transfer momentum from particle to particle:



For flocks, you get to have your kick and speed up, too

So, full EOM:

$$\partial_t \vec{v} = -\lambda_1 (\vec{v} \cdot \vec{\nabla}) \vec{v} - \lambda_2 \vec{\nabla} (\vec{v} \cdot \vec{v}) - \lambda_3 \vec{\nabla} (|\vec{v}|^2) + f(\vec{v}) \vec{v} - \vec{\nabla} P(\rho) + D_B \vec{\nabla} (\vec{v} \cdot \vec{v}) + D_T \nabla^2 \vec{v} + D_2 (\vec{v} \cdot \vec{\nabla})^2 \vec{v} + \vec{f}$$

$$\langle f_i(\vec{v}, t) f_j(\vec{v}', t') \rangle = \Delta \delta_{ij} \delta^d(\vec{v} - \vec{v}') \delta(t - t')$$

~~MB~~ + continuity eqn:

$$\partial_t \rho + \vec{\nabla} \cdot (\rho \vec{v}) = 0$$

We've "buried our ignorance" (D. Forster, "Hydrodynamic fluctuations, Broken Symmetries, and Correlation Functions") in small number of parameters  $\Delta, \lambda_{1,2,3}, f(\vec{v}), P(\rho), D_{T,B,2}(\vec{v}, \rho)$ . We'll now reduce unknown functions to unknown #'s.

If asked:

Why not

$$\langle f_i f_j \rangle = v_i v_j \Delta \dots$$

Ans: long. piece ( $\langle \vec{v} \rangle \neq 0$ )

$$\vec{v} = \underbrace{\langle \vec{v} \rangle}_{\text{mean}} + \underbrace{\delta \vec{v}}_{\text{small fluctuations}}$$

irrelevant  
(that comp. of  $\vec{v}$   
not slow)

transverse piece  $|\delta \vec{v}| \ll 1$

$\Rightarrow$  these terms  $\ll$  those already kept

# The broken symmetry state I.B.1

Ignore noise: What are steady state solutions? Depend on form of  $f(|v|)$ :  
 $\rho = \rho_0$ ,  $\vec{v}(t) = \vec{v}_0 = \text{const}$

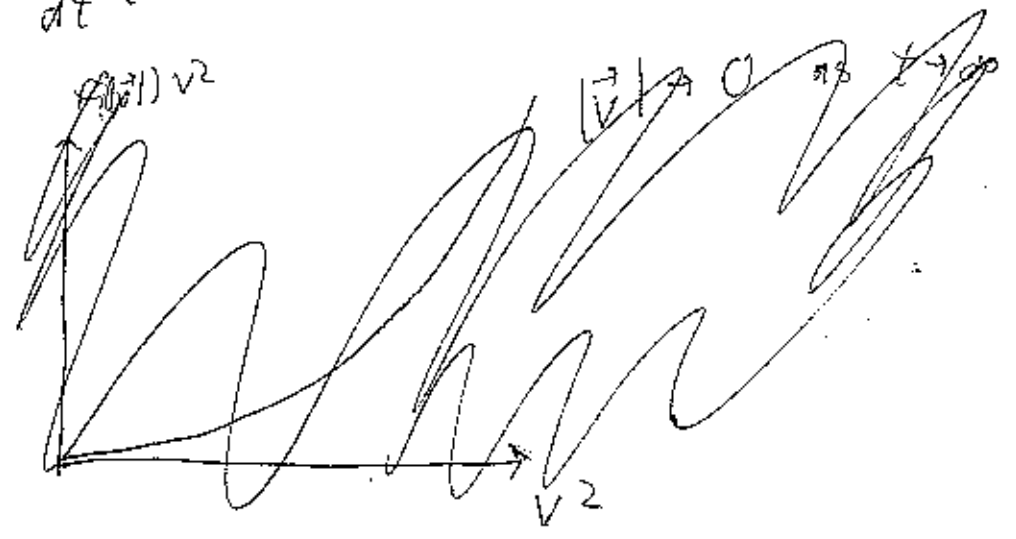
~~$f(|v|)v$~~   
Spatially uniform state:  $\vec{\nabla} \rho = 0, \vec{\nabla} \cdot \vec{v} = 0$

$$\Rightarrow \vec{v} \cdot \left[ \partial_t \vec{v} = f(|v|) \vec{v} \right]$$

$\Rightarrow \vec{v}$  always in same direction

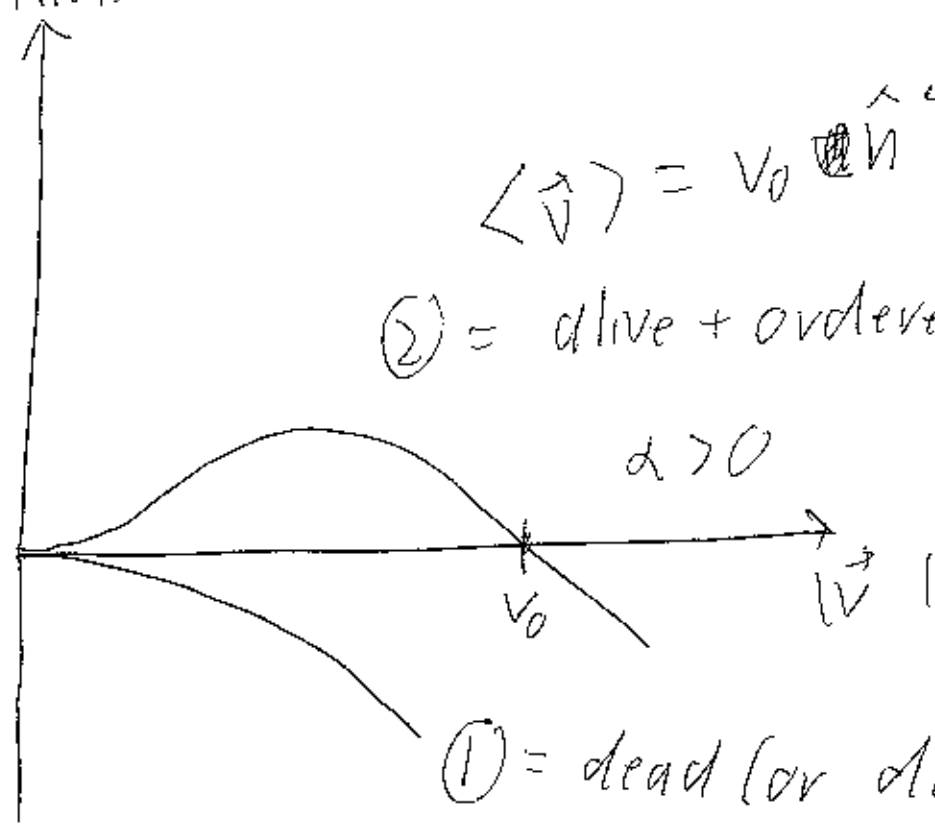
Speed:  $|\vec{v}|^2 =$

$$\frac{d}{dt} |\vec{v}|^2 = f(|v|) |\vec{v}|^2$$



Two generic cases:

$f(|\vec{v}|)v^2$



② = alive + ordered

① = dead (or disordered)  
( $\alpha < 0$ )

~~Most of~~  
Simplest example:

$$f(|\vec{v}|) = \alpha - B|\vec{v}|^2$$

$\alpha < 0 \Rightarrow$  case ① dead or disordered

$\alpha = 0 \Rightarrow$  transition

$\alpha > 0$ : ordered ( $v_0 = \sqrt{\frac{\alpha}{B}}$ )



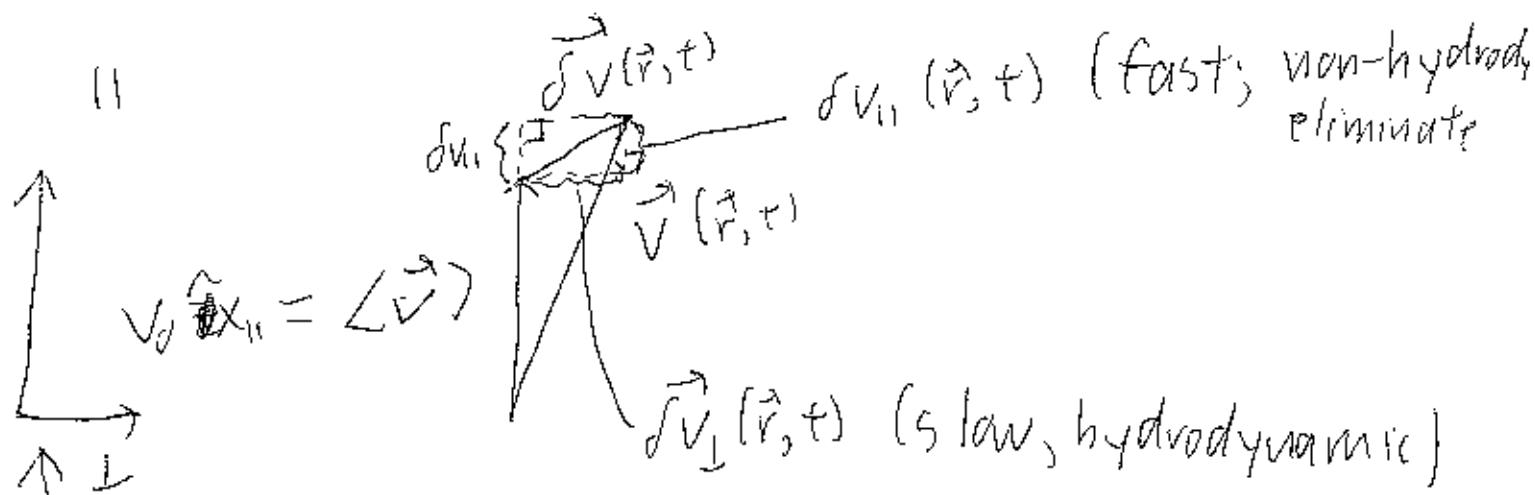
Ullmann

Fluctuations around ordered state:

Ullmann

Assume:

$$\vec{v}(\vec{r}, t) = \underbrace{\langle \vec{v} \rangle}_{\text{mean}} + \underbrace{\delta \vec{v}(\vec{r}, t)}_{\text{small fluctuations}} \equiv v_0 \hat{x}_{||} + \delta \vec{v}(\vec{r}, t)$$



$$|\vec{v}(\vec{r}, t)| = v_0 + \delta v_{||} + O(|\delta \vec{v}_{\perp}|^2)$$

$\Rightarrow \vec{v}_{\perp}$  does not change  $f(|\vec{v}|) \Rightarrow f(|v|)$

Note: Broken symmetry state is quasi isotropic (only so)

Terms drop out of EOM  $\Rightarrow \vec{v}_{\perp}$  is slow

$$P \equiv \sigma_1 \delta_f + P_0$$

ITC-2

$$\delta v_{11}$$

$$\equiv \frac{\Gamma_1}{\rho_0}$$

$$\equiv \frac{\Gamma_2}{\rho_0}$$

$$\frac{d \delta v_{11}}{d t} \approx -\sigma_1 \partial_{11} \delta_f + \delta v_{11} \left( \frac{\partial f}{\partial v_{11}} \right)_{f=f_0} + \delta_f \left( \frac{\partial f}{\partial \sigma_1} \right)_{\sigma_1}$$

neglect  $\partial_t \ll \frac{1}{\tau_1}$

$$\Rightarrow \delta v_{11} = -\frac{\sigma_1}{\Gamma_1} \partial_{11} \delta_f - \frac{\Gamma_2}{\Gamma_1} \delta_f$$

$$\partial_t \vec{v}_\perp + \gamma \partial_{11} \vec{v}_\perp$$

$$(\vec{v}_\perp \cdot \vec{\nabla}) \vec{v}_\perp = v_{11} \partial_{11} \vec{v}_\perp + (\vec{v}_\perp \cdot \vec{\nabla}) \vec{v}_\perp$$

$$\begin{aligned} \partial_t \vec{v}_\perp + \gamma \partial_{11} \vec{v}_\perp + \lambda_1 (\vec{v}_\perp \cdot \vec{\nabla}) \vec{v}_\perp + \lambda_2 (\vec{\nabla}_\perp \cdot \vec{v}_\perp) \vec{v}_\perp \\ = -\vec{\nabla}_\perp P + D_B \vec{\nabla}_\perp (\vec{\nabla}_\perp \cdot \vec{v}_\perp) + D_T \vec{\nabla}_\perp^2 \vec{v}_\perp \\ + D_{11} \partial_{11}^2 \vec{v}_\perp + \vec{f}_\perp \end{aligned}$$

$$\partial_t \delta_f + \rho_0 \vec{\nabla}_\perp \cdot \vec{v}_\perp + \vec{\nabla}_\perp \cdot (\vec{v}_\perp \delta_f) + v_{02} \partial_{11} \delta_f = D_f \partial_{11}^2 \delta_f$$

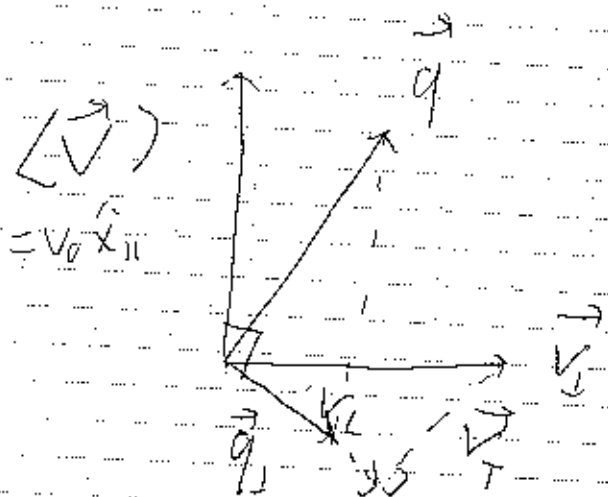
$$v_2 \equiv v_0 - \frac{\rho_0 \Gamma_2}{\Gamma_1}$$

~~$c(\omega - \gamma q_{||}) +$~~

$$-c(\omega - \gamma q_{||}) \vec{v}_{\perp} + D_B q_{\perp} (\vec{q}_{\perp} \cdot \vec{v}_{\perp}) + D_T q_{\perp}^2 \vec{v}_{\perp} + D_{||} q_{||}^2 \vec{v}_{\perp} + c \vec{q}_{\perp} \cdot \vec{v}_{\perp} d_{\perp} = \vec{f}_{\perp}$$

$$[-c(\omega - v_2 q_{||}) + D_S q_{||}^2] d_{\perp} + c \vec{q}_{\perp} \cdot \vec{v}_{\perp} = 0$$

Simplify further: project along and  $\perp$  to  $\vec{q}_{\perp}$ :



Note: No transverse component of  $\vec{v}_{||}$  in  $d = 2$ !

$$\Rightarrow \left[ -i(\omega - \gamma q_{\parallel}) + \underbrace{\left( D_{\perp} + D_{\parallel} \right) q_{\perp}^2 + D_{\parallel} q_{\parallel}^2}_{\Gamma_L(q)} \right] v_L + i\beta_1 q_{\perp} d\beta = f_L$$

$$\left[ -i(\omega - \gamma q_{\parallel}) + \underbrace{\left( D_{\perp} q_{\perp}^2 + D_{\parallel} q_{\parallel}^2 \right)}_{\Gamma_T(q)} \right] \vec{v}_T = \vec{f}_T$$

$$\left[ -i(\omega - \gamma_2 q_{\parallel}) + \underbrace{D_{\parallel} q_{\parallel}^2}_{\Gamma_P(q)} \right] d\beta + i\beta_0 q_{\perp} v_L = 0$$

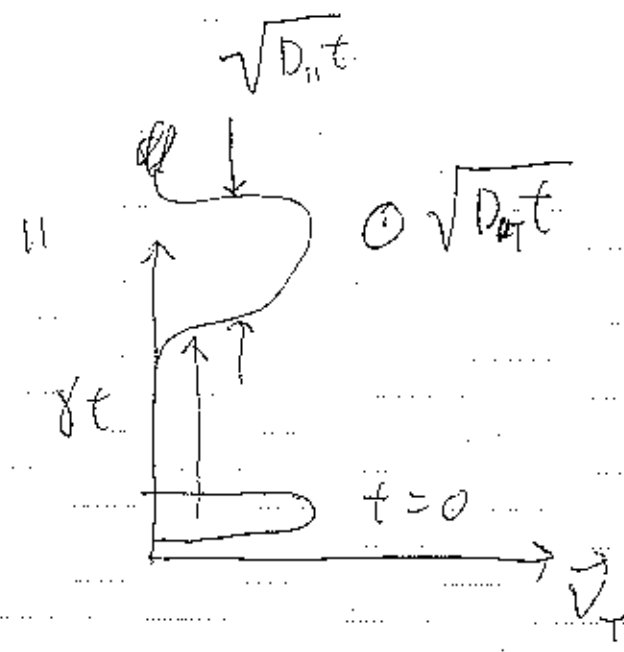
Note:  $\vec{v}_T$  decouples.

But Finding eigenfrequencies and eigenmodes:  $\vec{f} = \vec{0}$

$\vec{v}_T$  obvious eigenmode:  $\rightarrow$  anisotropic diffusion

$$\omega = \gamma q_{\parallel} - i \left( D_{\perp} q_{\perp}^2 + D_{\parallel} q_{\parallel}^2 \right)$$

$\uparrow$  "convecting speed"



Coupled  $v_L, \delta \varphi$  equations:

Guess  $w = c(\hat{q}) q$   
 ↑ direction of  $q$

work to leading order in  $q$  as  $q \rightarrow 0$

$$-i(\omega - \gamma q_{||}) v_L + i\beta_1 q_{\perp} \delta \varphi = 0$$

$$-(\omega - v_2 q_{||}) \delta \varphi + i\beta_0 q_{\perp} v_L = 0$$

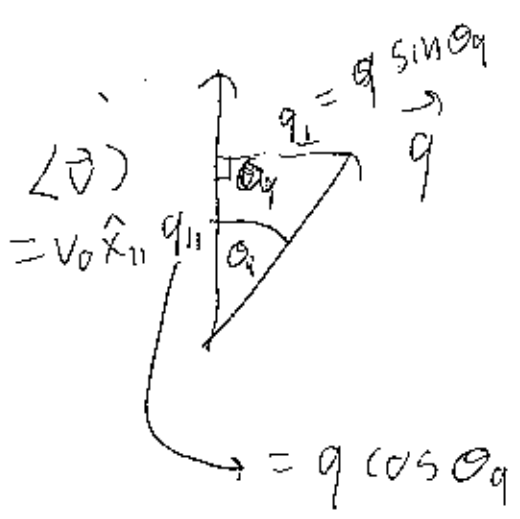
⇒

$$\omega (w - \gamma q_{||}) (w - v_2 q_{||}) + \delta_1 \rho_0 q_{\perp}^2 = 0$$

$$\Rightarrow -w^2 + (\gamma + v_2) q_{||} w + (\gamma v_2 q_{||}^2 + \delta_1 \rho_0 q_{\perp}^2) = 0$$

$$\omega = -\gamma + v$$

$$w(\vec{q}) \equiv c(\theta_{\vec{q}}) q$$



$$\Rightarrow c^2 - (\gamma + v_2) \cos \theta_q c + \gamma v_2 \cos^2 \theta_q - \delta_1 \rho_0 \sin^2 \theta_q = 0$$

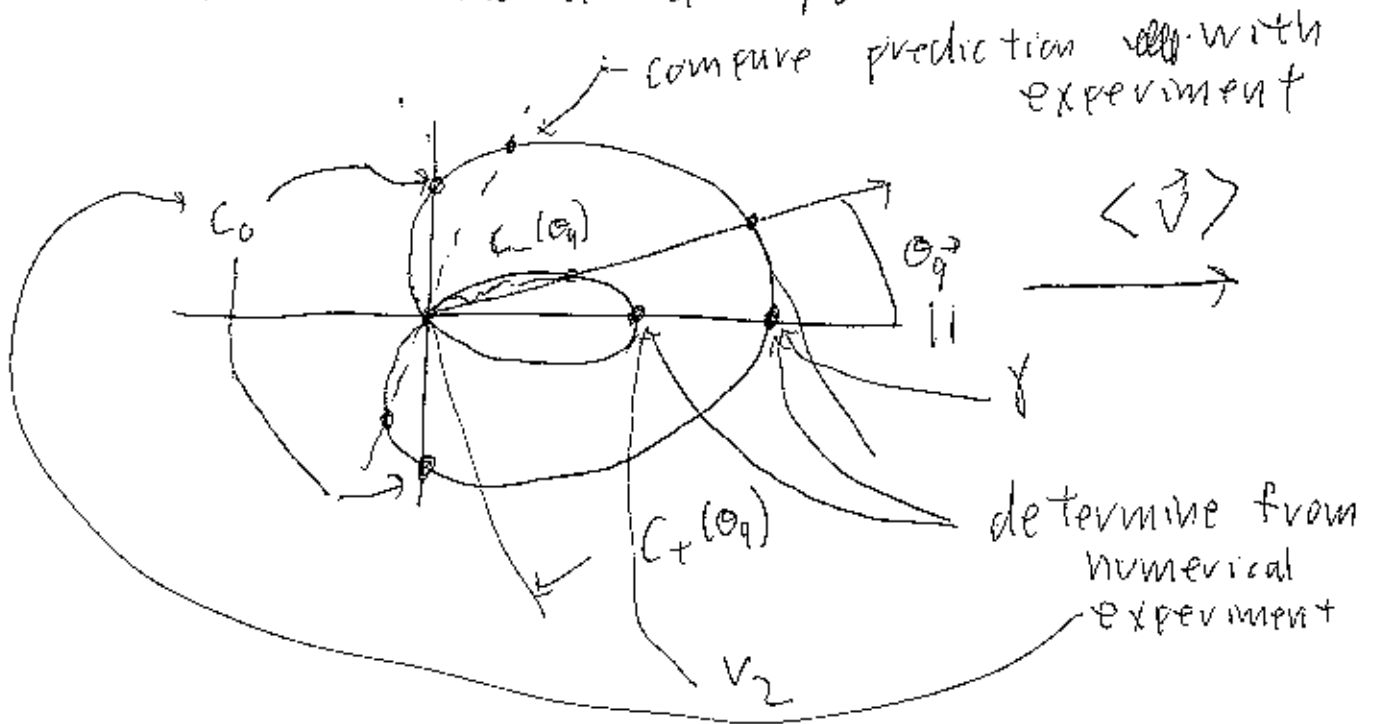
$$\Rightarrow c(\theta_q) = \left( \frac{\gamma + v_2}{2} \right) \cos \theta_q \pm \frac{1}{2} \sqrt{(\gamma + v_2)^2 \cos^2 \theta_q + 4 \delta_1 \rho_0 \sin^2 \theta_q - 4 \gamma v_2 \cos^2 \theta_q}$$

$$= \left( \frac{\gamma + v_2}{2} \right) \cos \theta_q \pm \sqrt{\frac{(\gamma - v_2)^2}{4} \cos^2 \theta_q + \delta_1 \rho_0 \sin^2 \theta_q}$$

3 parameters:  $\gamma, v_2, c_0 \equiv \sqrt{\beta_0 / \rho_0}$

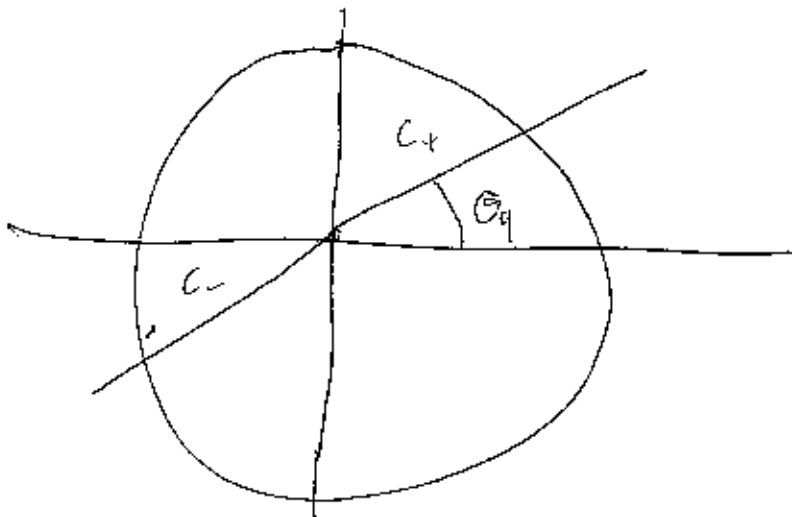
like ordinary, compression wave in simple fluid

Note: Rotated 90°



cf: same plot for simple fluid:

$$w = \pm c_0 q$$



Simple directions:

$$\theta_q = 0 \text{ (along flock motion)}$$

$$c_{\pm} = \frac{\gamma + v_2}{2} \pm \frac{\gamma - v_2}{2} = \begin{cases} \gamma & + \\ v_2 & - \end{cases}$$

$$\theta_q = \pm \frac{\pi}{2} \text{ (}\perp\text{ to flock motion)}$$

$$c_{\pm} = \pm \sqrt{6, \rho_0} \equiv \pm c_0$$

Damping (important for fluctuations,  
finite height of resonance)

assume  $\omega = \pm c_{\pm}(\theta_q^2) q + d_{\pm}(\vec{q})$

$$d(\vec{q}) \ll c q$$

Solve to next order in  $q$



find

Dissipative  
↓

$$d_{\pm}(\vec{q}) = -i \left[ (D_{411} q_{11}^2 + D_{22} q_3^2) f_1(\omega_q) + D_{55} q_{11}^2 f_2(\omega_q^2) \right]$$

$$f_1(\omega_q) = \frac{v_{\pm}(\omega_q)}{2 \omega_q C_2(\omega_q)}$$

$$v_{\pm}(\omega_q) = \pm \left( \frac{\gamma - v_2}{2} \right) \cos \theta_q + C_2(\omega_q)$$

$$C_2(\omega_q) = \sqrt{\dots}$$

Summary of longitudinal modes

$$\omega(\vec{q}) = \underbrace{c_{\pm}(\omega_q) q}_{\text{propagating}} - i \underbrace{q^2 F(\omega_q^2)}_{\text{damping}}$$

Note: Damping  $F q^2 \ll \text{real part } c q$  as  $q \rightarrow 0$ .

Aside:  $z = 1$   
or  
 $z = 2$  ?

$\Rightarrow$  very sharp resonance  
very high q

I'll take  $z = 2$ , because damping ~~is~~ controls fluctuations

Look ahead: Non-linearities do not change  $c_z(q)q$ , but do change damping

$$q^2 \rightarrow \begin{cases} q_{\perp}^2 \gg q_{\parallel}^2, & z \gg q^2 \\ q_{\perp}^2 \sim q_{\parallel}^2, & z < 2 \\ q_{\parallel}^2, & q_{\perp} \ll q_{\parallel} \quad |d=2: z = \frac{6}{5} \end{cases}$$

Calculating fluctuations:

Put forces back in, solve linear eqns for  $\vec{V}_j(\vec{q}, \omega)$ ,  $d_j(\vec{q}, \omega)$  i.t.o.  $\vec{f}_j(\vec{q}, \omega)$

~~Get:  $G_{SS} = \Delta$~~

Get:  $d_S(\vec{q}, \omega) = G_{S \perp L}(\vec{q}, \omega) f_L(\vec{q}, \omega) + G_{SS} f_S$

$V_{\perp L}(\vec{q}, \omega) = G_{\perp L L}(\vec{q}, \omega) f_L(\vec{q}, \omega) + G_{\perp S} f_S$

~~$\Gamma_{ij}$ 's are complicated,~~

$$\vec{V}_T(\vec{q}, \omega) = G_{TT}(\vec{q}, \omega) \vec{f}_T(\vec{q}, \omega)$$

Response functions

$$G_{TT}(\vec{q}, \omega) = \frac{1}{-i(\omega - \gamma q_{||}) + \Gamma_T(\vec{q})}$$

$$G_{LL}(\vec{q}, \omega) = \frac{i(\omega - v_{02} q) - \Gamma_P(\vec{q})}{\underbrace{(\omega - c_+ q)(\omega - c_- q) + i\omega[\Gamma_L(\vec{q}) + \Gamma_P(\vec{q})] - q_{||}[v_0 \Gamma_L(\vec{q}) + \gamma \Gamma_P(\vec{q})]}_{\text{Den}(\vec{q}, \omega)}}$$

$$G_{LS}(\vec{q}, \omega) = \frac{i b_1 q_{\perp}}{(\omega - c_+ q)(\omega - c_- q) + i\omega[\Gamma_+ \dots]}$$

$$G_{SL}(\vec{q}, \omega) = \frac{i p_0 q_{\perp}}{\text{Den}(\vec{q}, \omega)}$$

$$G_{PP}(\vec{q}, \omega) = \frac{i(\omega - \gamma q_{||}) - \Gamma_L(\vec{q})}{\text{Den}(\vec{q}, \omega)}$$

Note resonance structure:

at  $\omega = c_{\pm}(q)q$ ,  $\gamma_{qH}$

↑ for Long. modes

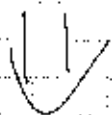
← for transverse modes,

all  $G_{dB}$ 's peak

$\omega = c_{\pm}q$ , Den  $\sim \omega \Gamma_L \sim (cq)(Dq^2)$

$G_{LL} \sim \frac{(c-v)q}{(cq)(Dq^2)} \sim \frac{1}{q^2} \sim G_{LP}, G_{SL}$

peak height  $\rightarrow \infty$  as  $q \rightarrow 0$



Long length scales ( $q \rightarrow 0$ ) have largest fluctuations ("stirred by noise")

Calculate correlations:

$$\langle V_{\vec{q}, \omega} V_{-\vec{q}, -\omega} \rangle$$

$$= |G_{\vec{q}, \omega}|^2 \langle f_{\vec{q}, \omega} f_{-\vec{q}, -\omega} \rangle$$

What are  $f_{\vec{q}, \omega}$  correlations?

$$\langle f_i(\vec{q}, \omega) f_j(-\vec{q}, -\omega) \rangle = \int e^{i\vec{q} \cdot (\vec{r} - \vec{r}') - i\omega(t - t')} \langle f_i(\vec{r}, t) f_j(\vec{r}', t') \rangle d^d r dt d^d r' dt'$$

$\underbrace{\int d^d r dt d^d r' dt'}_{\Omega T \text{ volume}}$

We took Gaussian, white

noise:  $\langle f_i f_j \rangle = \Delta \delta^d(\vec{r} - \vec{r}') \delta(t - t') \delta_{ij}$

$$\Rightarrow \langle f_i(\vec{q}, \omega) f_j(-\vec{q}, -\omega) \rangle = \Delta \text{ (constant, indep. of } \vec{q}, \omega \text{ (White))}$$

Aside: What would have happened if we assumed finite range spatio-temporal correlations of  $f$ ?

$$\langle f_i(\vec{r}, t) f_j(\vec{r}', t') \rangle = \delta_{ij} g(\vec{r} - \vec{r}', t - t')$$

$$\Rightarrow \langle f_i(\vec{q}, \omega) f_j(-\vec{q}, -\omega) \rangle = \delta_{ij} \text{FT}[g(\vec{q}, \omega)]$$

$$g(\vec{q}, \omega) \equiv \int d^d \Delta r dt g(\Delta \vec{r}, \Delta t) e^{i(\vec{q} \cdot \vec{r} - \omega t)}$$

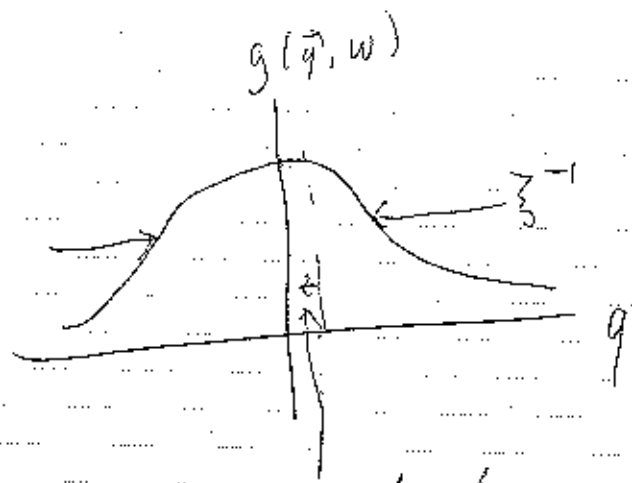
If  $g(\Delta \vec{r}, \Delta t)$  decays sufficiently rapidly as  $\Delta \vec{r}, \Delta t \rightarrow \infty$ ,

$$g(\vec{q} \rightarrow \vec{0}, \omega \rightarrow 0) \rightarrow \int d^d \Delta r dt g(\Delta \vec{r}, \Delta t) \text{ finite} \equiv \Delta$$

$$\Rightarrow \langle f_i(\vec{q}, \omega) f_j(-\vec{q}, -\omega) \rangle \xrightarrow{q, \omega \rightarrow 0} \Delta$$

$\Rightarrow$  small  $\vec{q}, \omega$  behavior exactly the same

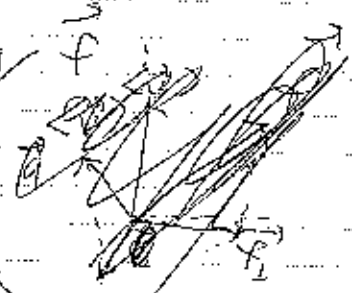
EG:  $g \propto e^{-\left(\frac{q^2}{\xi}\right)} \Rightarrow g(\vec{q}, \omega) \approx \frac{1}{q^2 + \xi^{-2}} \rightarrow \xi^2 \approx 0$



hydrodynamic limit  
(Guaranteed for short ranged correlations)

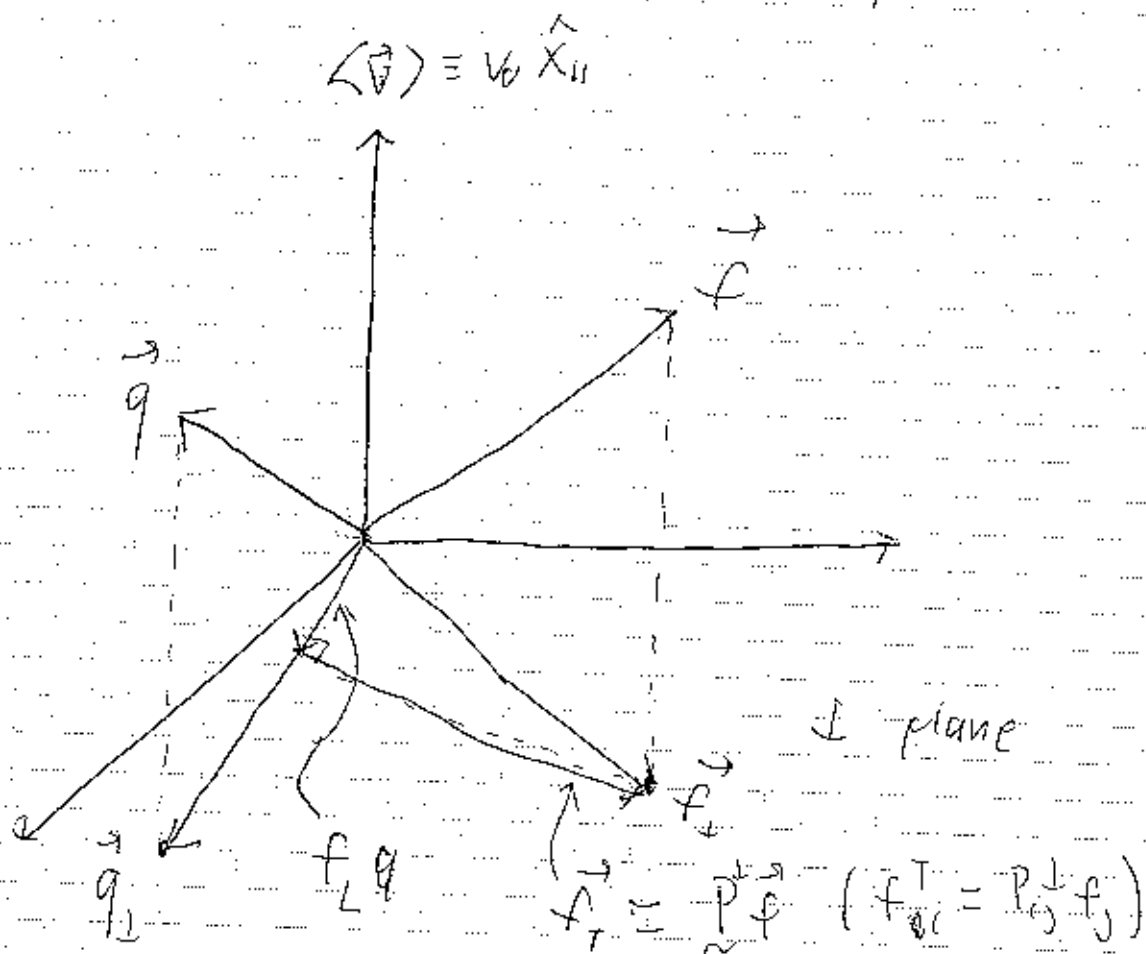
What getting  $f_{\perp}$  from  $\vec{f}$   
 projections:

- 1) Project  $\perp$  to  $(\vec{v})$
- 2) " " to  $\vec{q}_{\perp}$  in  $\perp$  plane.



$f_{LST}$  correlations:

$f_L = \text{comp. of } \vec{f} \text{ along } \vec{q}_\perp$



$$f_L = \hat{q}_\perp \cdot \vec{f} = \frac{q_i^\perp f_i}{q_\perp}$$

$$\vec{f}_\perp = \vec{f} - \hat{q}_\perp f_L = \vec{f} - \hat{q}_\perp (\hat{q}_\perp \cdot \vec{f})$$

$$\Rightarrow f_{\perp i}^T = f_i^\perp - \frac{q_i^\perp q_{jk}^\perp f_{jk}}{q_\perp^2}$$



$$\Rightarrow \langle f_i(\vec{q}, w) f_j(-\vec{q}, -w) \rangle = \frac{q_i^\perp q_j^\perp}{q_\perp^2} \langle f_i(\vec{q}, w) f_j(-\vec{q}, -w) \rangle$$

$$= \Delta \frac{q_i^\perp q_j^\perp}{q_\perp^2} \delta_{ij} = \Delta \frac{q_\perp^2}{q_\perp^2} = \Delta$$

$$\langle f_i^\perp f_j^\perp \rangle = \langle f_i^\perp f_j^\perp \rangle - 2 \frac{q_i^\perp q_k^\perp}{q_\perp^2} \langle f_i^\perp f_k^\perp \rangle$$

$$+ \frac{q_i^\perp q_j^\perp q_k^\perp q_l^\perp}{q_\perp^4} \langle f_k^\perp f_l^\perp \rangle$$

$$\delta_{ij}^\perp = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$= \Delta \left[ \delta_{ij}^\perp - 2 \frac{q_i^\perp q_j^\perp}{q_\perp^2} + \frac{q_i^\perp q_j^\perp q_k^\perp q_l^\perp}{q_\perp^4} \delta_{kl}^\perp \right]$$

$$= \Delta \left[ \delta_{ij}^\perp - \frac{q_i^\perp q_j^\perp}{q_\perp^2} \right] \equiv \Delta P_{ij}^\perp(\hat{q}_\perp)$$

$P_{ij}^\perp$  : "transverse projection operator" in  $\perp$  plane"

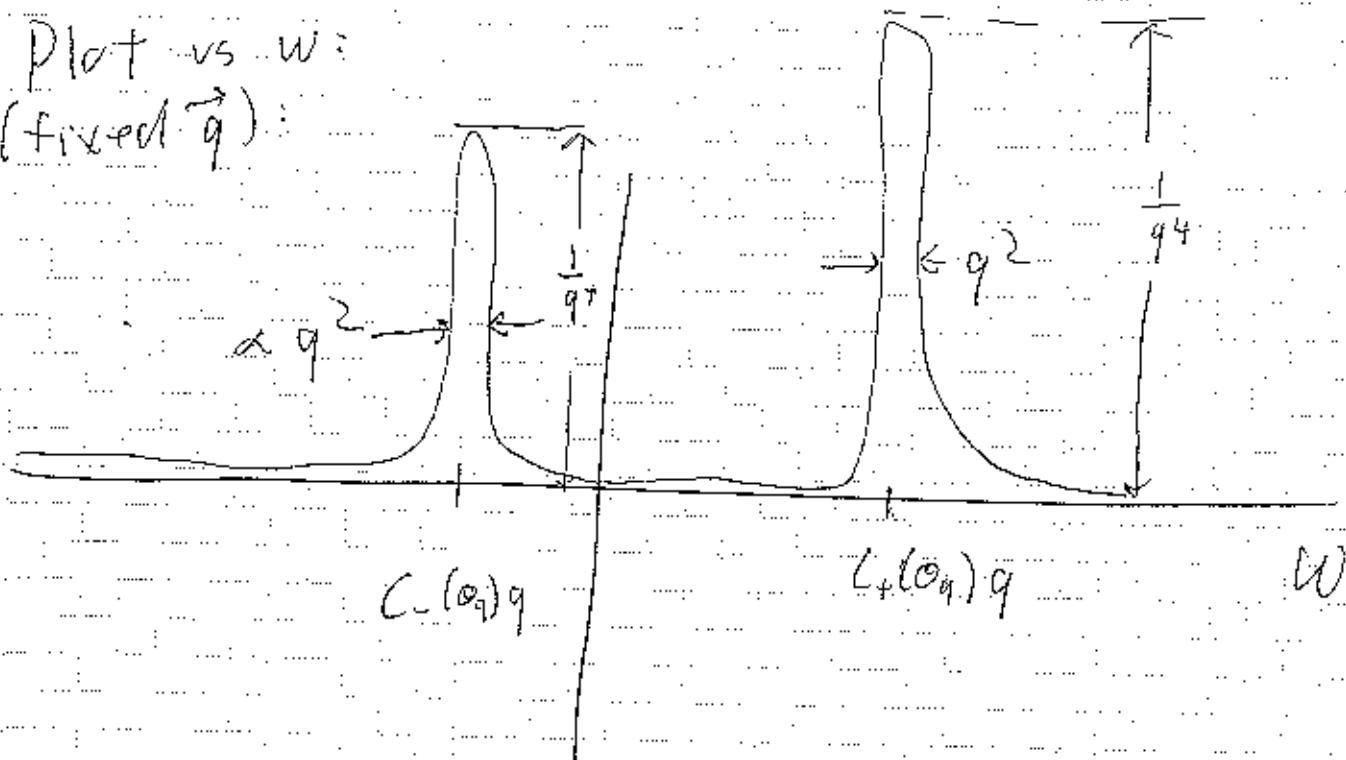
$$P_{ij}^\perp \hat{q}_j = A_i^\perp$$

↑  
any vector

So,

$$\begin{aligned} \langle |v_L(\vec{q}, \omega)|^2 \rangle &\equiv C_{LL}(\vec{q}, \omega) = |\sigma_{LL}(\vec{q}, \omega)|^2 \Delta \\ &= \frac{\Delta \left( (\omega - v_2 q_{||})^2 + \Gamma_g^2 \right)}{(\omega - c_+(\omega_q)q)^2 (\omega - c_-(\omega_q)q)^2 + (\omega(\Gamma_c + \Gamma_g) - q_{||}(v_2 \Gamma_c + \gamma \Gamma_g))^2} \end{aligned}$$

Plot vs  $\omega$ :  
(fixed  $\vec{q}$ ):



as  $q \rightarrow 0$ , width  $\propto$  distance between peaks

$\Rightarrow$  each peak nearly Lorentzian

What is  $\int_{-\infty}^{\infty} C_{LL}(\vec{q}, \omega) d\omega$ ?

=  $C_{LL}(\vec{q})$  (equal time) =  $\langle |v_L(\vec{q}, t)|^2 \rangle$ ?

roughly (peak height  $\sim \frac{1}{q^4}$  x peak width  $\sim q^2$ )  $\sim \frac{1}{q^2} \xrightarrow{q \rightarrow 0} \infty$

=> Huge small q Long wavelength fluctuations!

In fact, if we go to real space:

$\langle |v_L(\vec{r}, t)|^2 \rangle = \int d^d q \langle |v_L(\vec{q}, t)|^2 \rangle$

$\sim \int \frac{d^d q}{q^2} \propto \ln(L) \rightarrow \infty$   
 $\uparrow$   
 $d=2$   
 $\uparrow$   
 $q > \frac{1}{L}$

Ultra-violet cutoff  $\sim \frac{1}{a}$

No LRO (Mermin-Wagner Theorem)

More precisely,

$$C_{LL}(\vec{q}) \stackrel{\text{equal time}}{=} \frac{\Delta\phi(\Theta_{\vec{q}})}{\Gamma_L(\vec{q})}$$

$$\phi(\Theta_{\vec{q}}) = \frac{|\mathbf{Q}|}{(c_+ - c_-)q} \left[ \frac{(c_+ q - v_2 q_{||})^2}{c_+ q - v_2 q_{||} + (c_+ q - \delta q_{||}) \frac{\Gamma_p}{\Gamma_L}} + \frac{(c_- q - v_2 q_{||})^2}{c_- q - v_2 q_{||} + (c_- q - \delta q_{||}) \frac{\Gamma_p}{\Gamma_L}} \right]$$

$$\propto \frac{q^2}{q} \propto q^1 \Rightarrow \text{only fin of } \Theta_{\vec{q}}$$

Being finite,  $\omega_{\vec{q}} > 0$  in all directions.

$$\int C_{LL}(\vec{q}) d^d q = \left[ \int d\Omega \left( \frac{\phi(\Theta_{\vec{q}})}{D_2 \sin^2 \Theta_{\vec{q}} + D_{11} \cos^2 \Theta_{\vec{q}}} \right) \right]_{\text{finite dir}} \times \left( \int \frac{q^{d-1} dq}{q^2} \right)$$

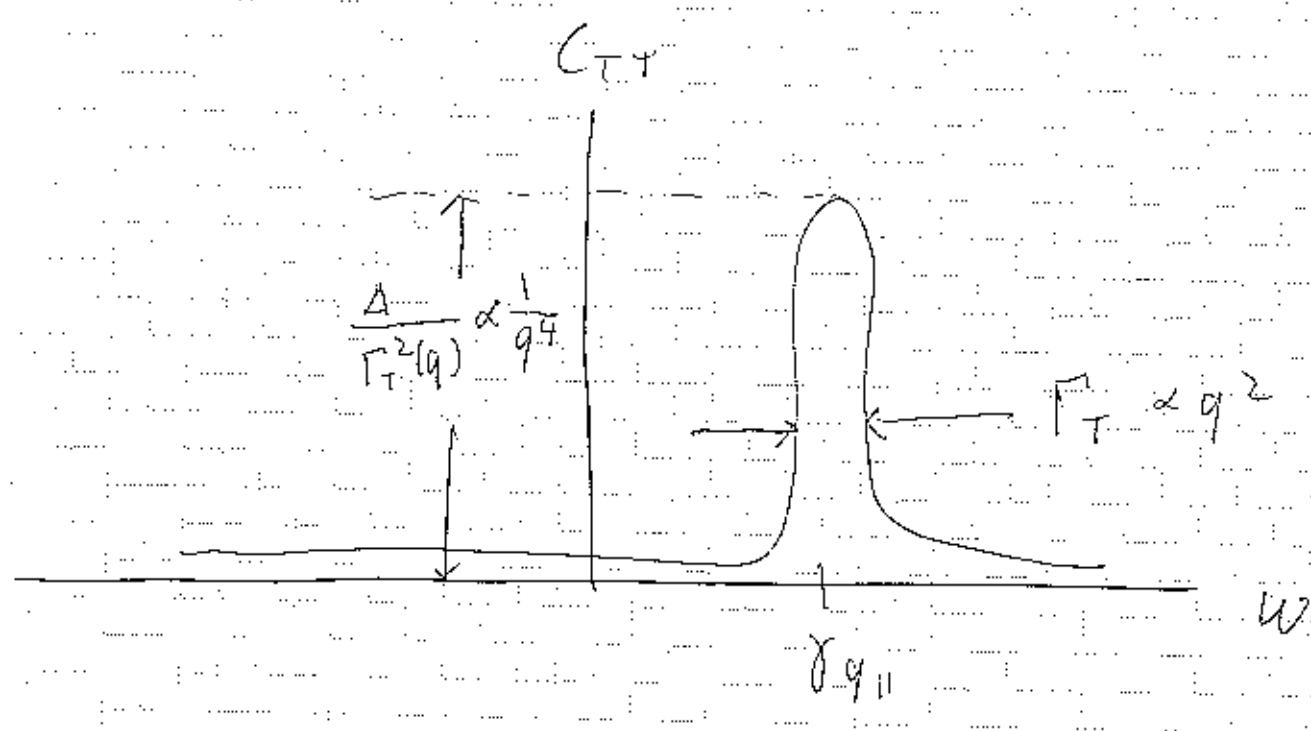
$\propto \ln L$  in  $d=2$

Same for  $C_{TT}$ :

$$\langle V_i^T(\vec{q}, \omega) V_j^T(-\vec{q}, -\omega) \rangle = \delta_{ij} |G_{TT}(\vec{q}, \omega)|^2 \langle f_i^T(\vec{q}, \omega) f_j^T(-\vec{q}, -\omega) \rangle$$

$$= C_{TT}(\vec{q}, \omega) P_{ij}^\perp(\hat{q}_\perp)$$

$$C_{TT}(\vec{q}, \omega) = \frac{\Delta}{\text{Re}(\omega - \delta q_{||})^2 + \Gamma_T^2(q)}$$



~~$\Delta \propto q_{||}^4$~~

$$\begin{aligned} \langle |\vec{V}_T(\vec{q}, \omega)|^2 \rangle &= \langle V_c^T V_c^T \rangle \\ &= C_{TT}(\vec{q}, \omega) \underbrace{P_{c^T c}^\perp}_{\substack{\downarrow \\ \sum_{i=1}^{d-1} \delta_{ii}^+ - \frac{q_i^+ q_i^+}{q^2} = d-2}} \end{aligned}$$

(No transverse components in  $d=2$ )

$$\Rightarrow \langle |\vec{V}_T(\vec{q}, \omega)|^2 \rangle = C_{TT}(\vec{q}, \omega) (d-2)$$

$$\begin{aligned} \Rightarrow C_{TT}^{\text{eq. time}}(\vec{q}) &\equiv \langle |\vec{V}_T(\vec{q}, t)|^2 \rangle \\ &= \int_{-\infty}^{\infty} d\omega C_{TT}(\vec{q}, \omega) (d-2) \\ &= \frac{(d-2) \Delta}{2 \Gamma_T(\vec{q})} = \frac{(d-2) \Delta}{2 (D_T q_\parallel^2 + D_\perp q_\perp^2)} \\ &\propto \frac{1}{q^2} \xrightarrow{\vec{q} \rightarrow 0} \infty \end{aligned}$$

⇒ real space fluctuations:

Here

Why is this different from simple fluid with no substrate?

Undramatic: anisotropy

More important: Noise correlations

$$\langle f f \rangle \propto FT(q)$$

$$\langle f_i(\vec{q}, \omega) f_j(-\vec{q}, -\omega) \rangle = \int d\vec{r} d\vec{r}' dt dt'$$

$$e^{i\vec{q} \cdot (\vec{r} - \vec{r}') - i\omega(t - t')}$$

$$\int d\vec{r} d\vec{r}' dt dt' \langle f_i(\vec{r}, t) f_j(\vec{r}', t') \rangle$$

(no substrate)

But for simple fluid, momentum

is conserved  $\Rightarrow \int d\vec{r} f(\vec{r}, t) = 0$

$$\Rightarrow \lim_{q \rightarrow 0} \langle f f \rangle \rightarrow 0$$

in fact,  $\langle f f \rangle \propto q^2$

$$\Rightarrow \left( \frac{\text{equal time}}{v} \right) \langle f f \rangle \propto q^2 \left( \text{flock answer} \right) \propto q^2 \left( \frac{1}{q^2} \right) \rightarrow \text{constant}$$

What about dead fluid on substrate? (II C.25)

Now,  $\vec{f}$  need not conserve; but

$\vec{v}$  is not a slow variable

$$\partial_t \vec{v} = -\alpha \vec{v} + \vec{f}$$

$$\Rightarrow \langle |v(q, \omega)|^2 \rangle \approx \frac{1}{\alpha^2} \langle |f|^2 \rangle = \frac{D}{\alpha^2} \rightarrow \text{const}$$

$\alpha \rightarrow 0$

Only for broken symmetry state (flock) can you have your kick and ~~eat~~ ~~it~~ ~~all~~ ~~sped~~ ~~up~~ ~~too~~)

That is: Only for broken symmetry state (moving flock) is

- 1)  $\vec{v}$  slow (Goldstone mode)
- 2)  $\vec{v}$  not conserved ( $\Rightarrow$  big noise)



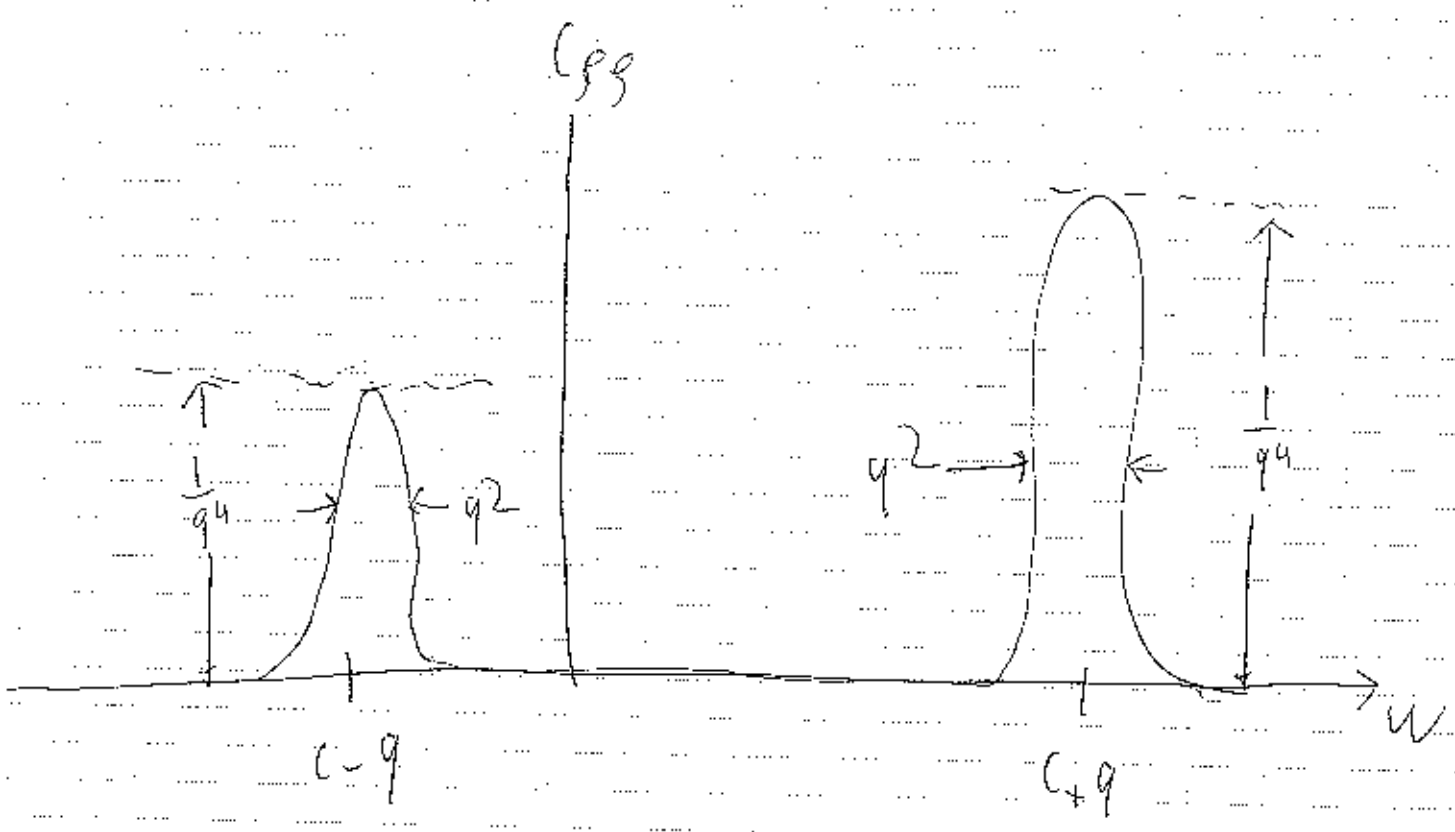
Final comment

Davis

Linearized theory also predicts:

Giant number fluctuations:

$$C_{SS}(\vec{q}, \omega) = \frac{\Delta \rho_0^2 q_\perp^2}{\text{Den}}$$



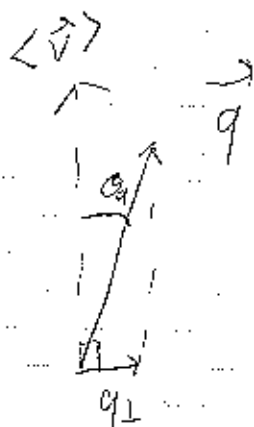
again,  $\int d\omega C_{SS}(\vec{q}, \omega) = C_{SS}^{\text{equal time}}(\vec{q}) = \langle |\rho(\vec{q}, t)|^2 \rangle$

$$= \frac{N(\rho_q)}{q^2}$$

Since  $\text{dim } \alpha q_{\perp}^2$

$$W(\theta_q \rightarrow 0) \rightarrow 0$$

(II Cr2)



Can rewrite:

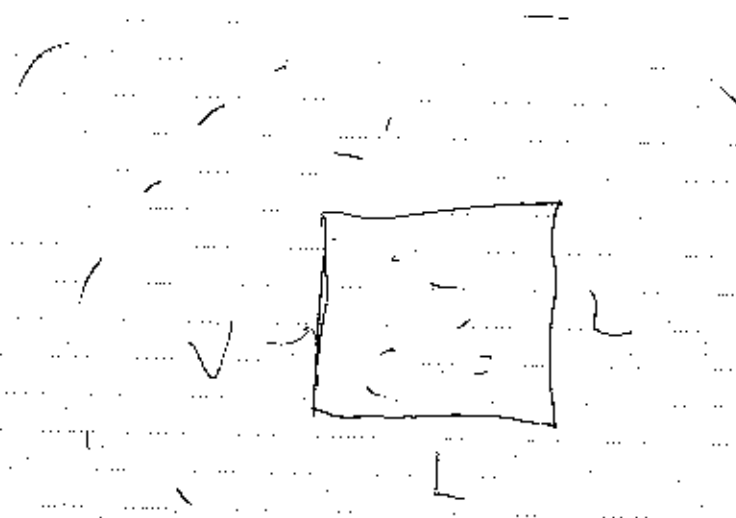
$$C_{SS}^{E.T.}(\vec{q}) = \frac{q_{\perp}^2}{q^4} \overbrace{W_2(\theta_q)}^{\text{finite, non-zero at } \theta_q}$$

$\Rightarrow$  as  $\theta_q \rightarrow 0$ ,  $q \rightarrow q_{\parallel}$

$$C_{SS}^{E.T.} \rightarrow \frac{q_{\perp}^2}{q_{\parallel}^4}$$

Back to real space

Giant # flux:




$$\delta N = \int_{\vec{r}} \delta \varphi(\vec{r}, t) \quad \left( \int_{\vec{r}} \equiv \int d^d r \right)$$

$$\langle \delta N^2 \rangle = \int_{\vec{r}, \vec{r}'} \langle \delta \varphi(\vec{r}, t) \delta \varphi(\vec{r}', t) \rangle$$

$$\langle \delta \varphi(\vec{r}, t) \delta \varphi(\vec{r}', t) \rangle = \frac{1}{V} \sum_{\vec{q}, \vec{q}'} e^{i(\vec{q} \cdot \vec{r} + \vec{q}' \cdot \vec{r}')} \langle \delta \varphi(\vec{q}, t) \delta \varphi(\vec{q}', t) \rangle$$

$$= \int \frac{d^d q}{(2\pi)^d} e^{i\vec{q} \cdot (\vec{r} - \vec{r}')} \langle \delta \varphi(\vec{q}) \rangle$$

$$\Rightarrow \langle \delta N^2 \rangle = \int_{r, r'} \int_{\vec{q}} e^{i\vec{q} \cdot (\vec{r} - \vec{r}')} \underbrace{C_{SS}^{ET}(\vec{q})}_{\text{--- } C_{SS}(\vec{q})}$$


$$C_{SS}^{ET}(\vec{q}) = \frac{f(\theta_q)}{q^2}$$

$$\int \frac{e^{i\vec{q} \cdot (\vec{r} - \vec{r}')}}{q^2} f(\theta_q) d^d q \Rightarrow C_{SS}^{ET}(\vec{r}) = \frac{g(\theta_{\vec{r}-\vec{r}'})}{|\vec{r}-\vec{r}'|^{d-2}}$$

Long ranged spatial correlations of density fluctuations!

$$\vec{q} \equiv \frac{\vec{q}}{|\vec{r}-\vec{r}'|} \Rightarrow \langle \delta N^2 \rangle = \int_{r, r'} \frac{g(\theta_{\vec{r}-\vec{r}'})}{|\vec{r}-\vec{r}'|^{d-2}}$$

$$(\vec{r}, \vec{r}') \equiv L(\vec{R}, \vec{R}')$$

$$\Rightarrow \langle \delta N^2 \rangle = L^{2d - (d-2)} \int_{R, R'} \frac{g(\theta_{R-R'})}{|R-R'|^{d-2}} \in \square$$

$$d L^{d+2} \propto \langle N \rangle^{\frac{d+2}{d}} = \langle N \rangle^{1 + \frac{2}{d}}$$

$$\langle N \rangle = \rho_0 L^d \Rightarrow L \propto \langle N \rangle^{\frac{1}{d}}$$

⇒ RMS fluctuations:

$$\sqrt{\langle \delta N^2 \rangle} \propto \langle N \rangle^{\frac{1}{2} + \frac{1}{d}} \gg \sqrt{\langle N \rangle} \quad \text{Law of large numbers!}$$

Ex:  $d=2$ ,  $\sqrt{\langle \delta N^2 \rangle} \propto \langle N \rangle$